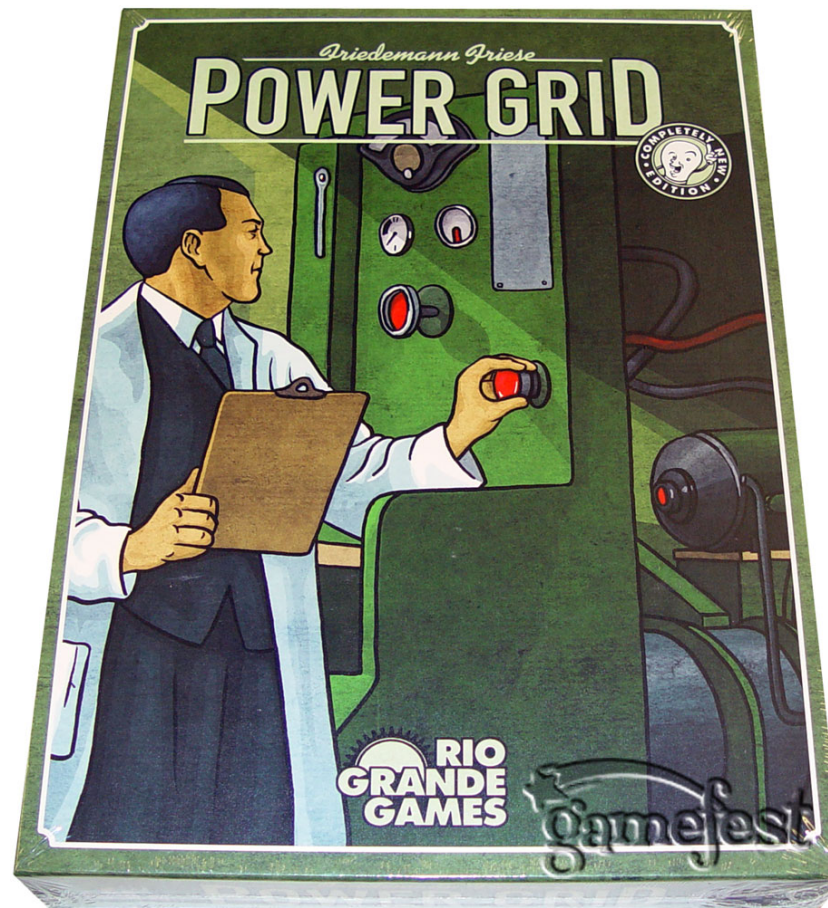


# Computational Astrophysics

Solving for Gravity

Alexander Knebe, *Universidad Autonoma de Madrid*



**Adaptive Mesh Refinement**

# Computational Astrophysics

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Solving for Gravity

- Poisson's equation

$$\Delta\Phi(\vec{x}) = 4\pi G\rho(\vec{x})$$

# Computational Astrophysics

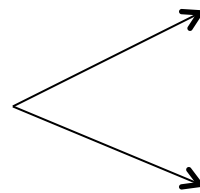
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## Solving for Gravity

- Poisson's equation

$$\vec{F}(\vec{x}) = -m\nabla\Phi(\vec{x})$$

$$\Delta\Phi(\vec{x}) = 4\pi G\rho(\vec{x})$$



### particle approach

$$\vec{F}(\vec{x}_i) = -\sum_{i \neq j} \frac{Gm_i m_j}{(x_i - x_j)^3} (\vec{x}_i - \vec{x}_j)$$

### grid approach ( $\vec{x}_{i,j,k}$ = position of centre of grid cell $(i,j,k)$ )

$$\Delta\Phi(\vec{x}_{i,j,k}) = 4\pi G\rho(\vec{x}_{i,j,k})$$

$$\vec{F}(\vec{x}_{i,j,k}) = -m\nabla\Phi(\vec{x}_{i,j,k})$$

# Computational Astrophysics

## Solving for Gravity

- Poisson's equation

$$\vec{F}(\vec{x}) = -m\nabla\Phi(\vec{x})$$

$$\Delta\Phi(\vec{x}) = 4\pi G\rho(\vec{x})$$

**weapon of choice: tree codes**

particle approach

$$\vec{F}(\vec{x}_i) = -\sum_{i \neq j} \frac{Gm_i m_j}{(x_i - x_j)^3} (\vec{x}_i - \vec{x}_j)$$

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# Computational Astrophysics

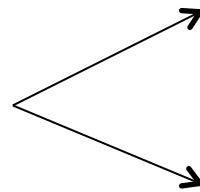
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## Solving for Gravity

- Poisson's equation

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$$\Delta\Phi(\vec{x}) = 4\pi G\rho(\vec{x})$$



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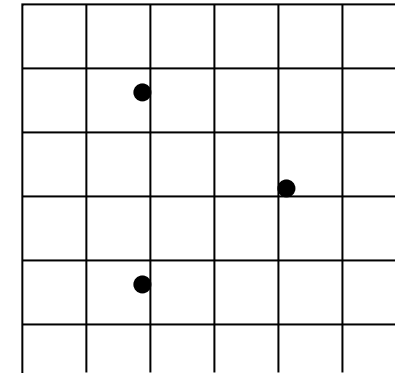
**weapon of choice: AMR codes**

Solving for Gravity

- Particle-Mesh (PM) method

$$\Delta\Phi(\vec{g}_{k,l,m}) = 4\pi G\rho(\vec{g}_{k,l,m})$$

$$\vec{F}(\vec{g}_{k,l,m}) = -m\nabla\Phi(\vec{g}_{k,l,m})$$



1. calculate mass density on grid
2. solve Poisson's equation on grid
3. differentiate potential to get forces
4. interpolate forces back to particles

$$\vec{x}_i \rightarrow \rho(\vec{g}_{k,l,m})$$

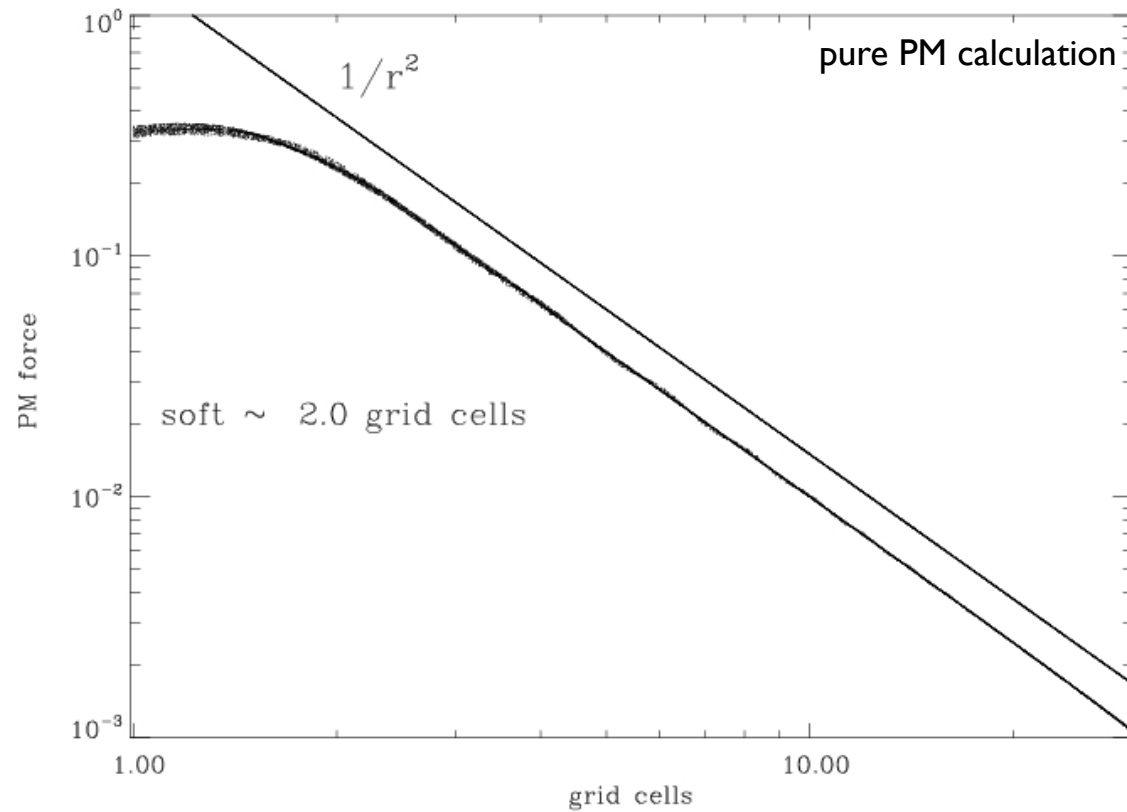
$$\Phi(\vec{g}_{k,l,m})$$

$$\vec{F}(\vec{g}_{k,l,m})$$

$$\vec{F}(\vec{g}_{k,l,m}) \rightarrow \vec{F}(\vec{x}_i)$$

### Solving for Gravity

- numerically integrate Poisson's equation



### Solving for Gravity

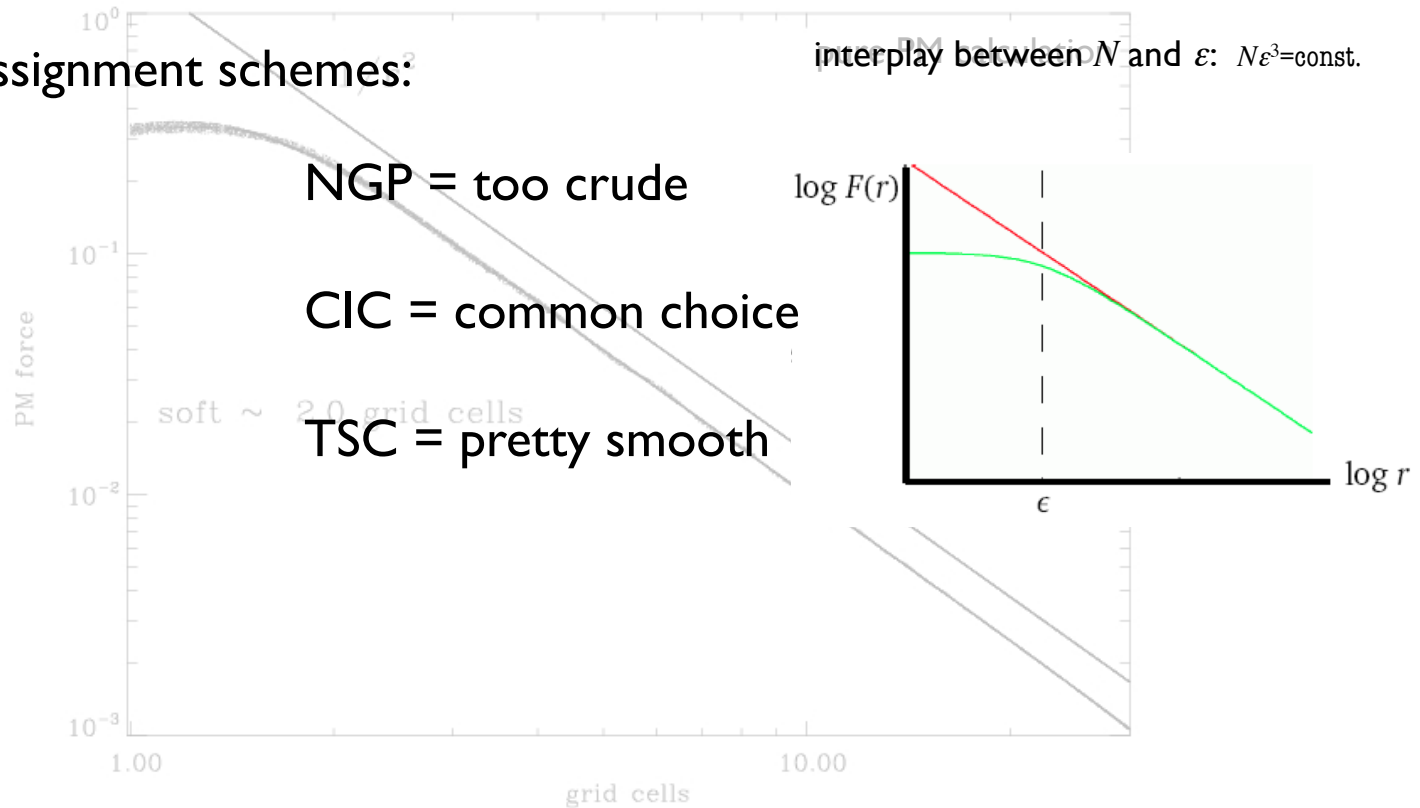
- numerically integrate Poisson's equation

- density assignment schemes:

NGP = too crude

CIC = common choice

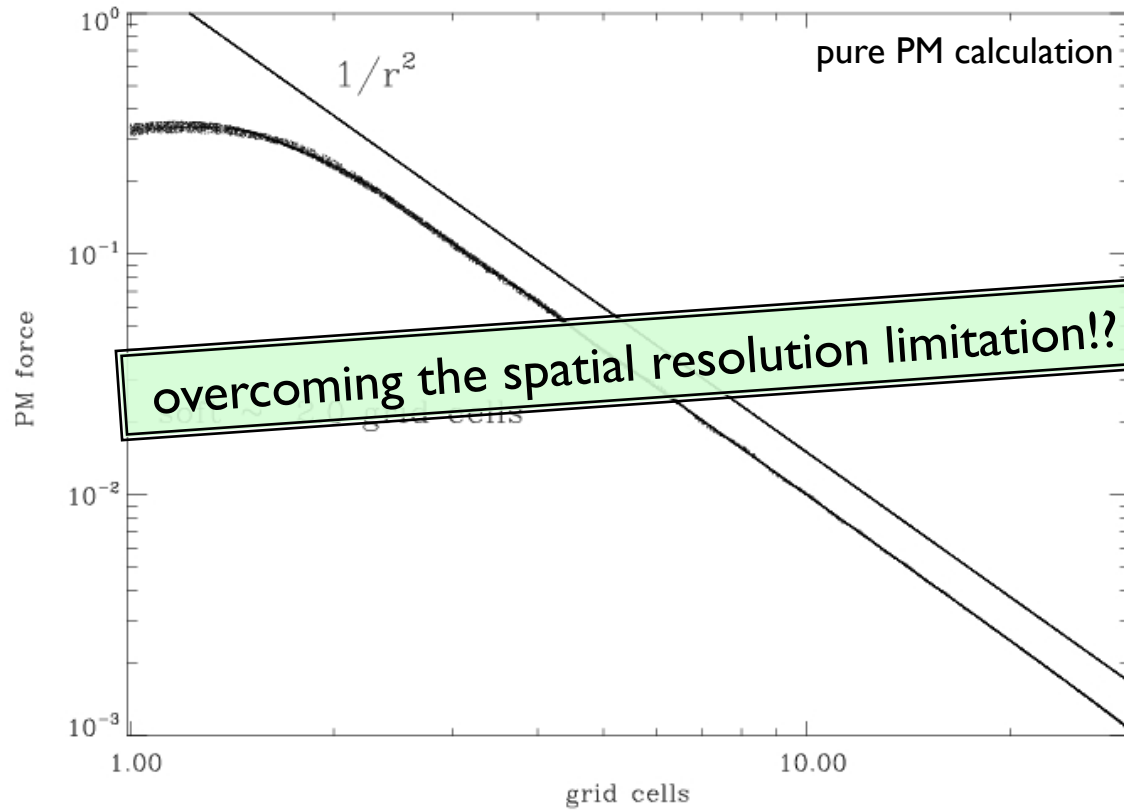
TSC = pretty smooth





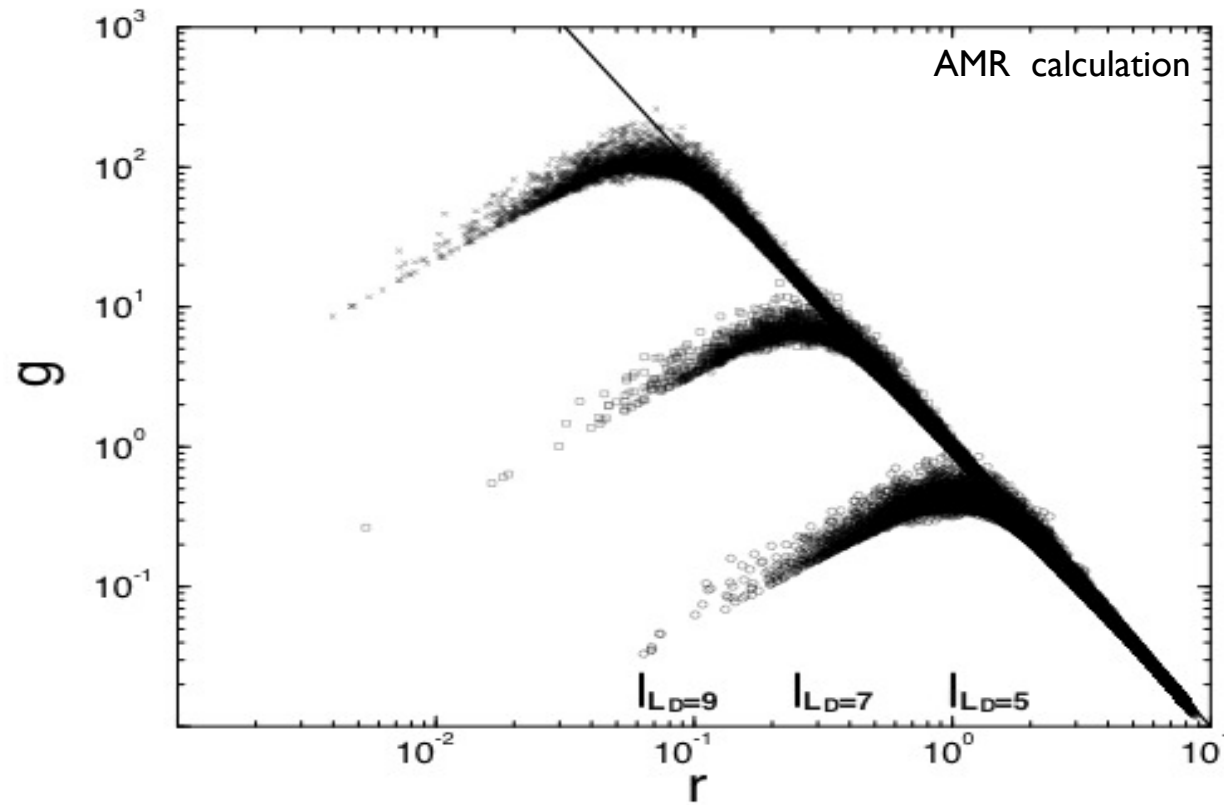
### Solving for Gravity

- numerically integrate Poisson's equation



## Solving for Gravity

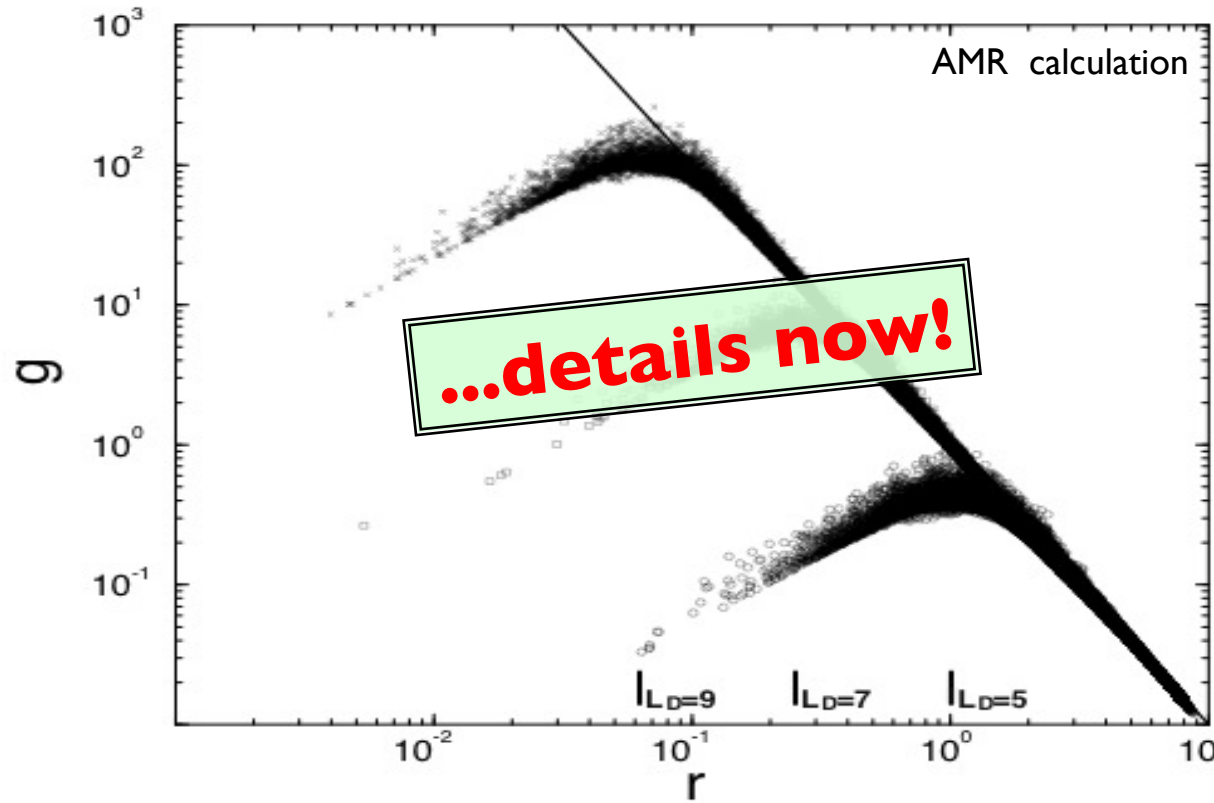
- numerically integrate Poisson's equation



Yahagi &amp; Yoshi (2001)

Solving for Gravity

- numerically integrate Poisson's equation



Yahagi & Yoshi (2001)

## Solving for Gravity

- mesh refinements
- adaptive mesh refinement
- adaptive mesh refinement for  $N$ -body codes
- handling irregular grids
- adaptive leap-frog integration

## Solving for Gravity

- **mesh refinements**
- adaptive mesh refinement
- adaptive mesh refinement for  $N$ -body codes
- handling irregular grids
- adaptive leap-frog integration

### Solving for Gravity

- types of mesh refinement

- $r$  refinement: move or stretch the mesh
- $p$  refinement: adjust the order of the method
- $h$  refinement: change the mesh spacing

### Solving for Gravity

- types of mesh refinement –  $r$  refinement

- non-uniform mesh

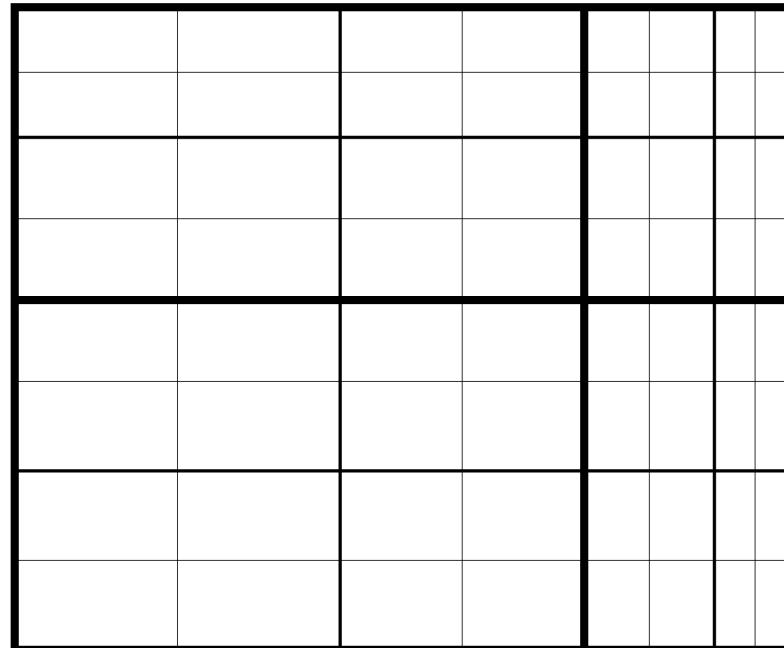
*(refined region is known)*

= advantages:

- simple to implement

= disadvantages:

- difference expression for non-constant zone spacing



COSMOS code (Ricker 2000)

### Solving for Gravity

- types of mesh refinement –  $r$  refinement

- Lagrangian mesh

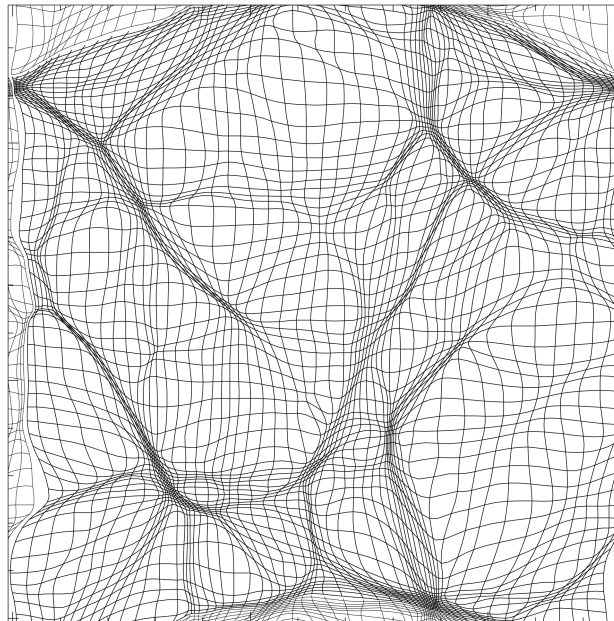
*(mesh is tied to fluid)*

= advantages:

- constant mass resolution
- sharp resolution of contacts

= disadvantages:

- grid stretching causes numerical dissipation
- grid tangling in rotational flows



MMH code (Pen 1998)



### Solving for Gravity

- types of mesh refinement –  $r$  refinement

- Lagrangian mesh

*(mesh is tied to fluid)*

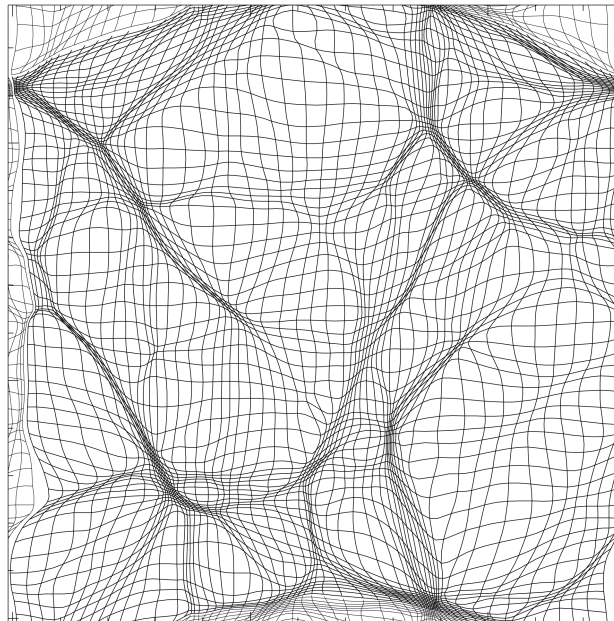
= advantages:

- constant mass resolution
- sharp resolution of contacts

= disadvantages:

- grid stretching causes numerical dissipation
- grid tangling in rotational flows

**usually used only in 1D (e.g. stellar evolution codes)**



MMH code (Pen 1998)

### Solving for Gravity

- types of mesh refinement –  $r$  refinement

- arbitrary Lagrangian-Eulerian mesh

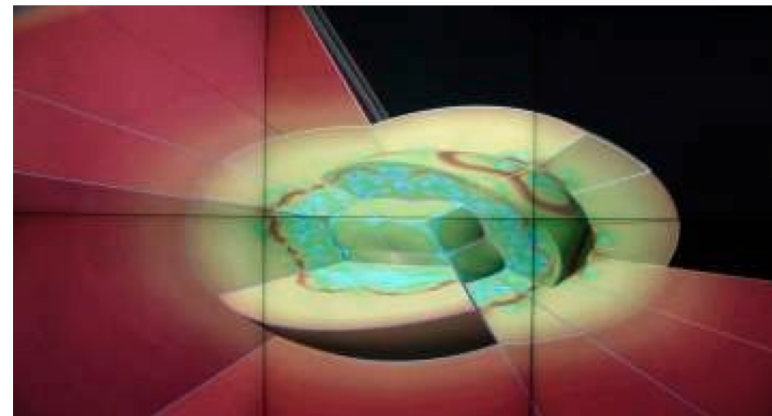
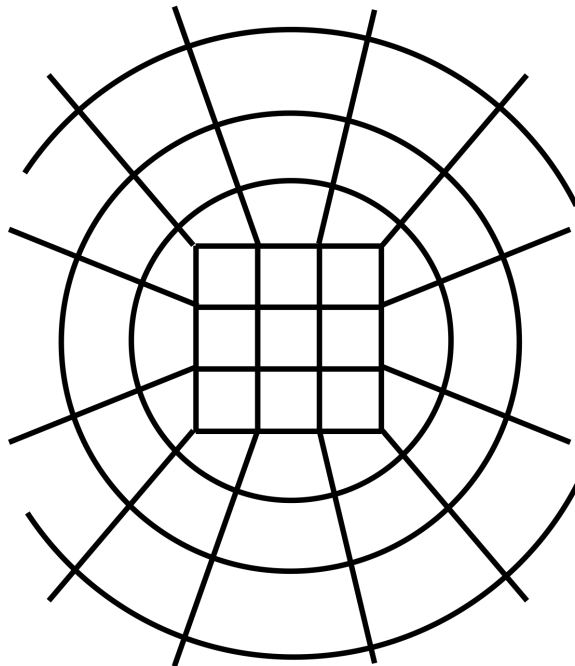
*(mesh moves arbitrarily fluid)*

= advantages:

- Lagrangian mesh where flow is irrotational
- Eulerian where mesh distortion is problematic

= disadvantages:

- difficult to handle...



DJHUTY code (Dearborn et al. 2002)

Solving for Gravity

- types of mesh refinement –  $p$  refinement

not in this course...

### Solving for Gravity

- types of mesh refinement –  $h$  refinement

- nested grids

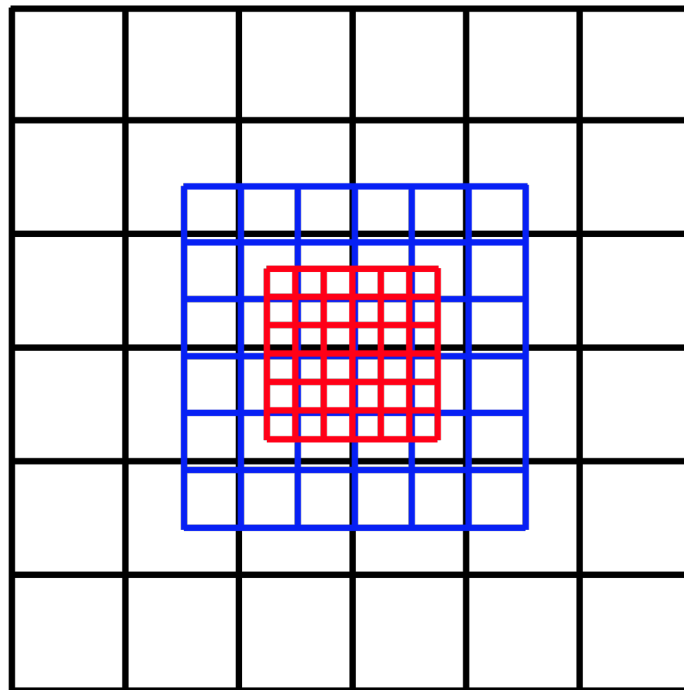
*(static meshes with different resolutions)*

= advantages:

- easy to handle boundaries between meshes

= disadvantages:

- refined region should not move



### Solving for Gravity

- types of mesh refinement –  $h$  refinement

- adaptive mesh refinement

*(refined patches are created and destroyed as needed)*

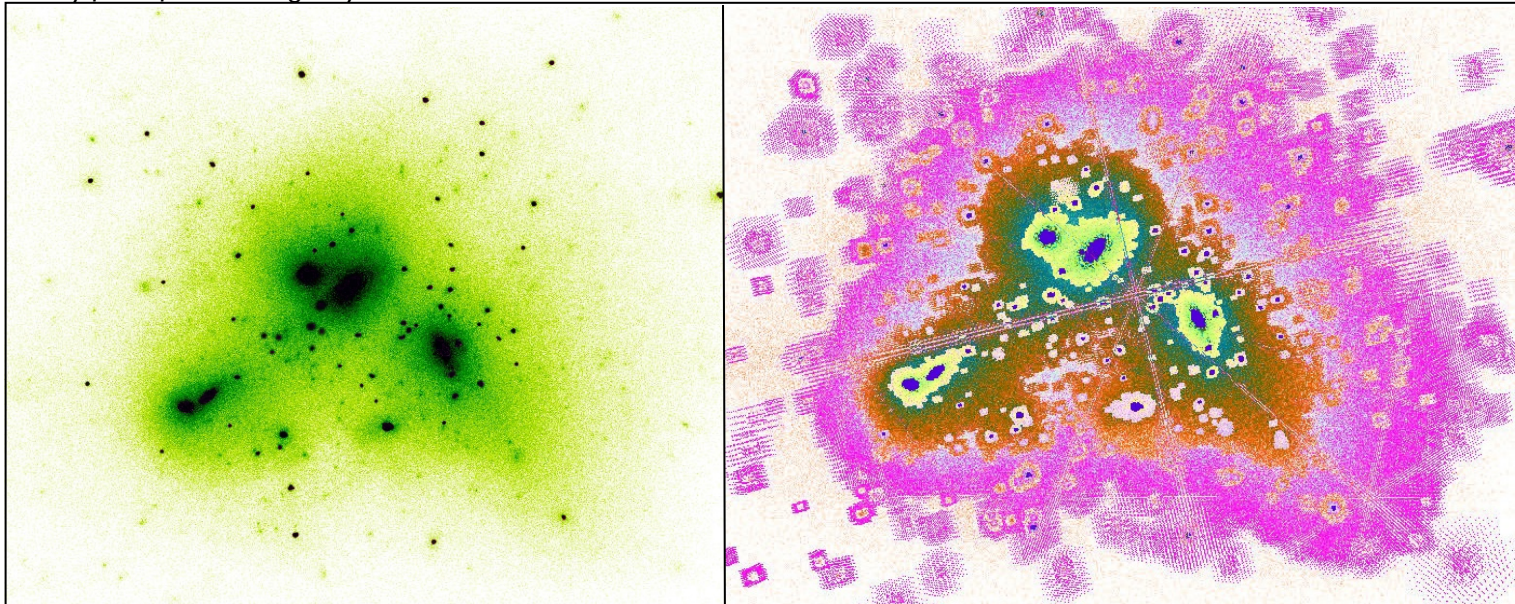
= advantages:

- fully flexible to problem

= disadvantages:

- serious book-keeping for grid hierarchy

*density field of simulated galaxy cluster*



AMIGA code (Doumler & Knebe 2010)

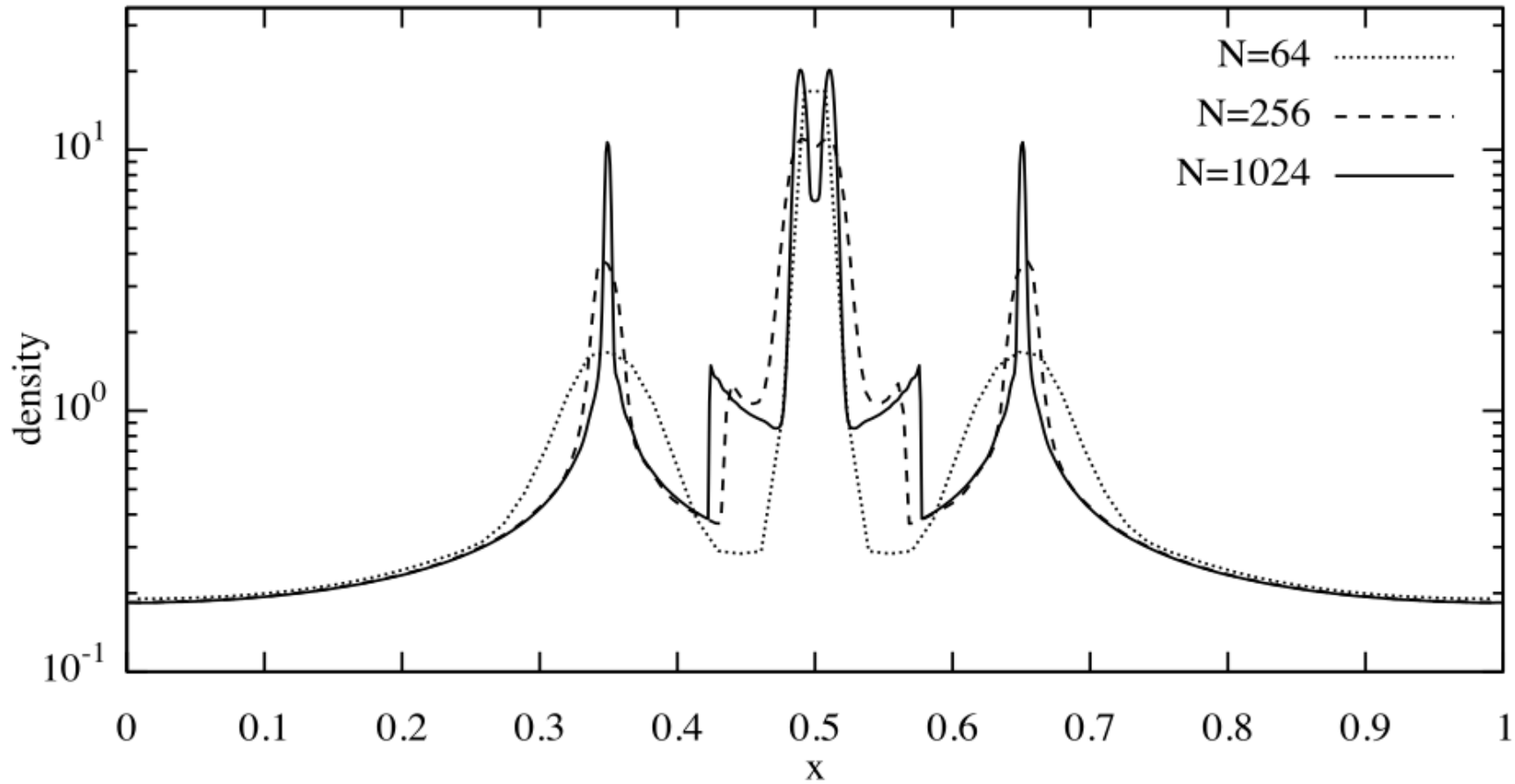
*adaptive grid hierarchy*

## Solving for Gravity

- mesh refinements
- **adaptive mesh refinement**
- adaptive mesh refinement for  $N$ -body codes
- handling irregular grids
- adaptive leap-frog integration

Solving for Gravity

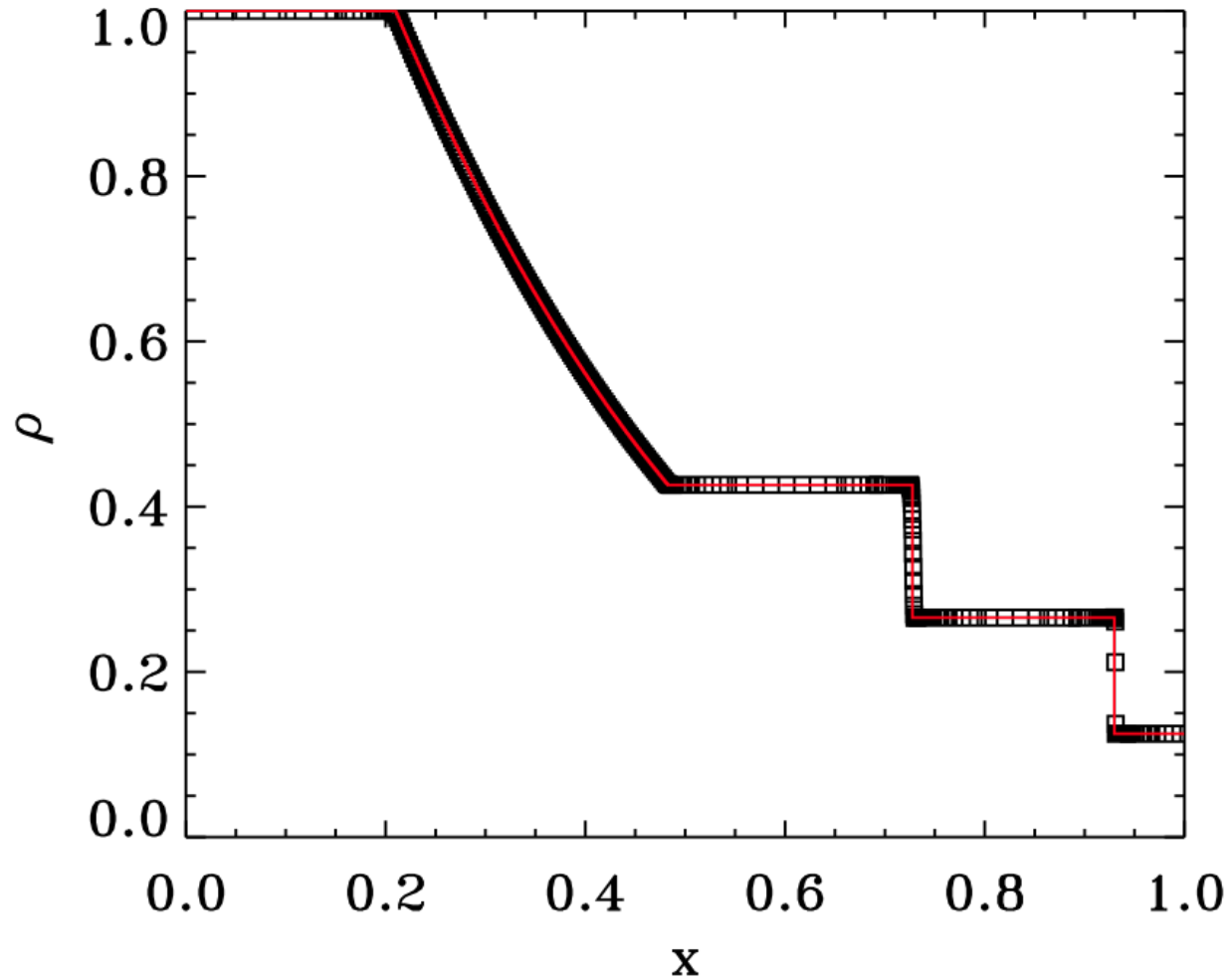
- adaptive mesh refinement – improvements using finer grids



double pancake test (Doumler & Knebe 2010)

Solving for Gravity

- adaptive mesh refinement – improvements using finer grids

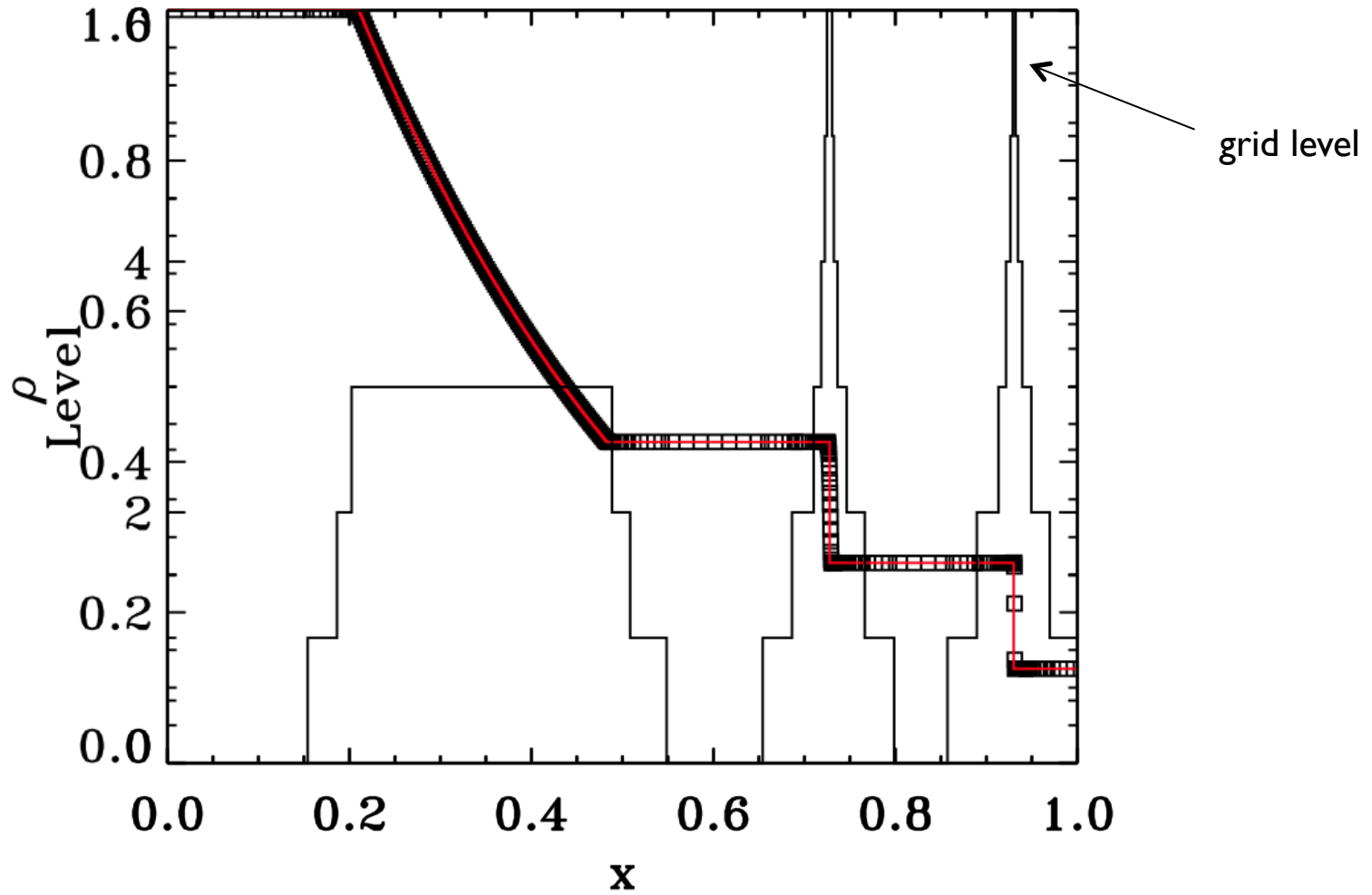


shock tube test (Teyssier 2002)



Solving for Gravity

- adaptive mesh refinement – improvements using finer grids

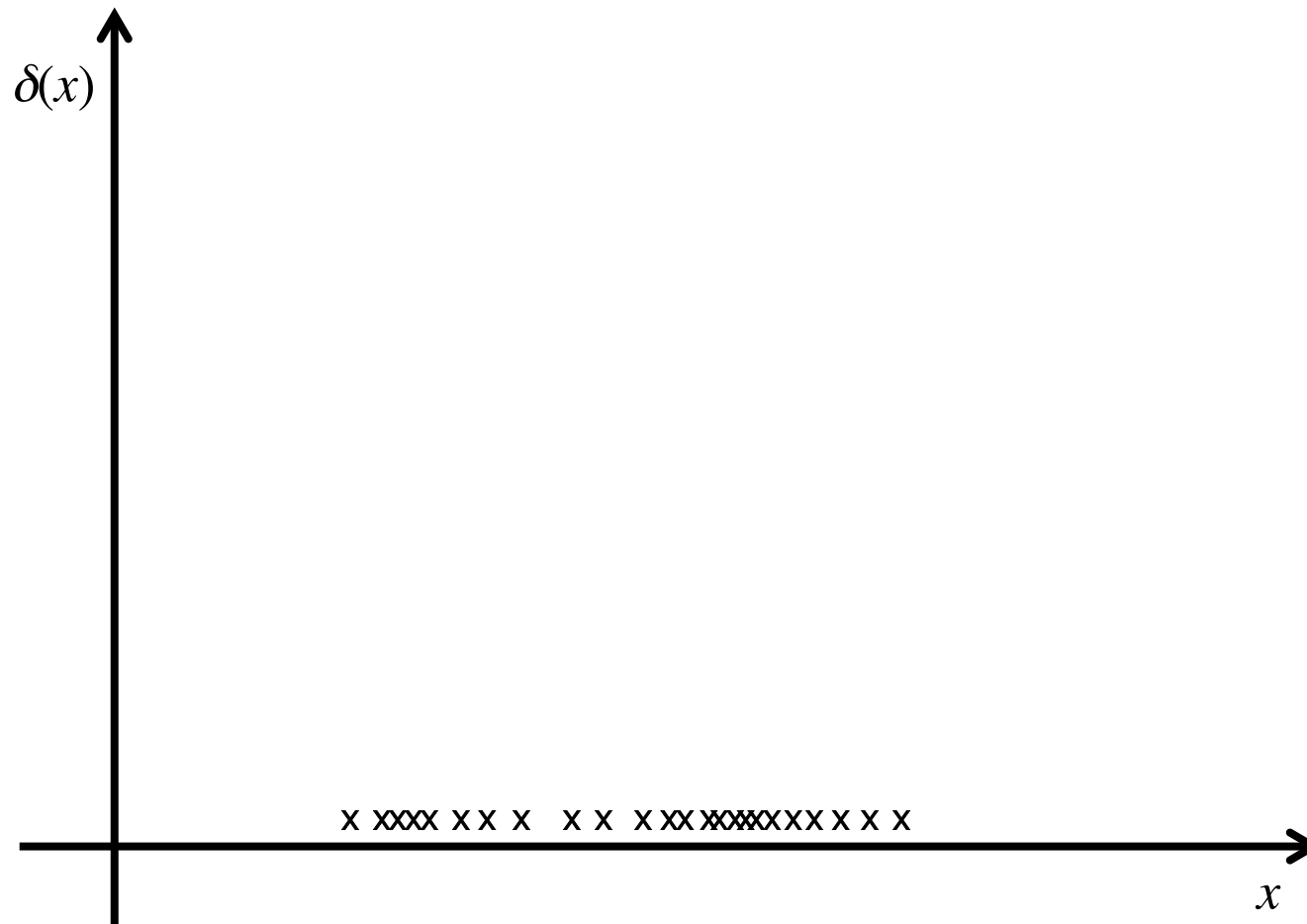


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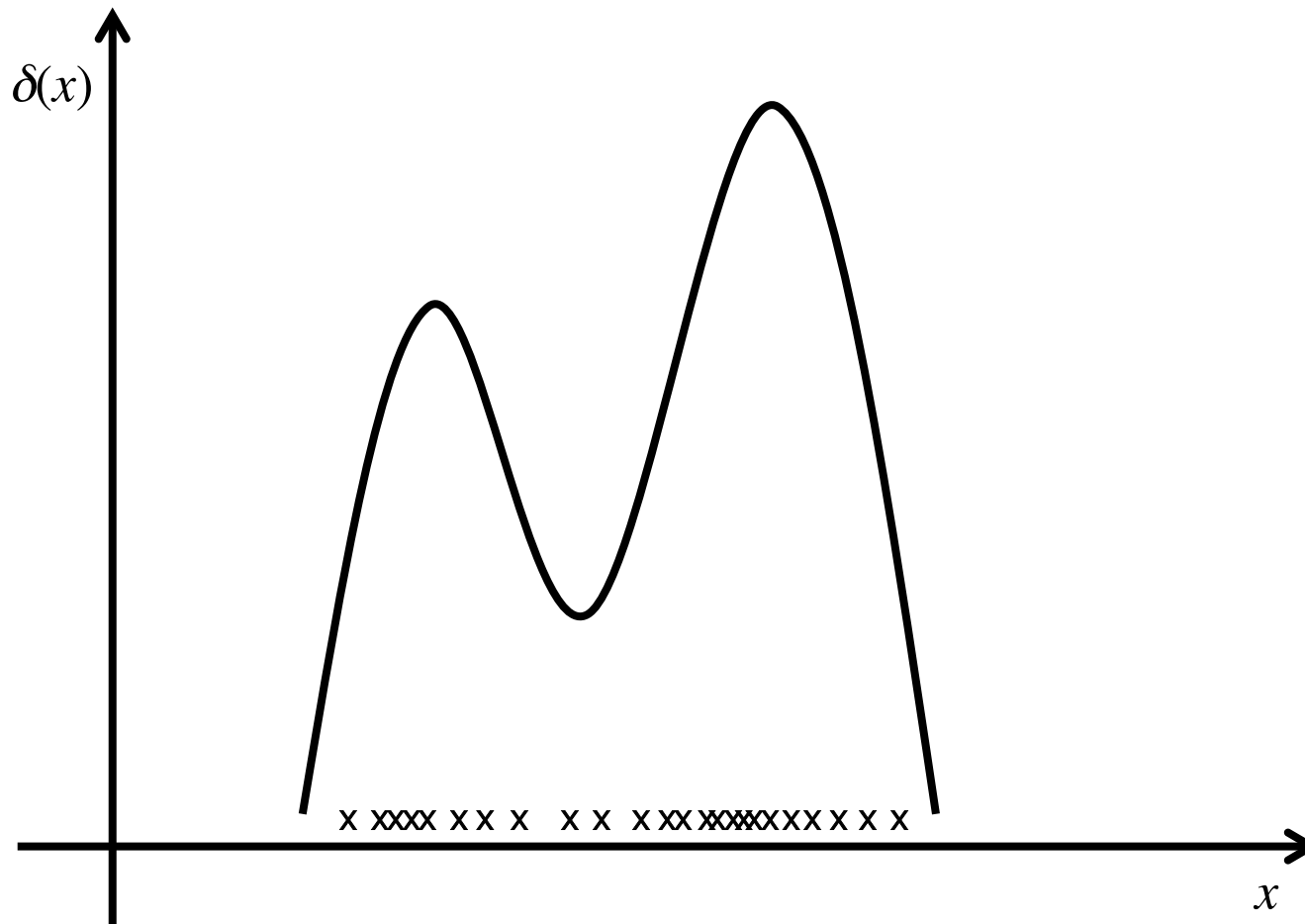
Solving for Gravity

- adaptive mesh refinement – refinement criterion
  - density – 1D density distribution



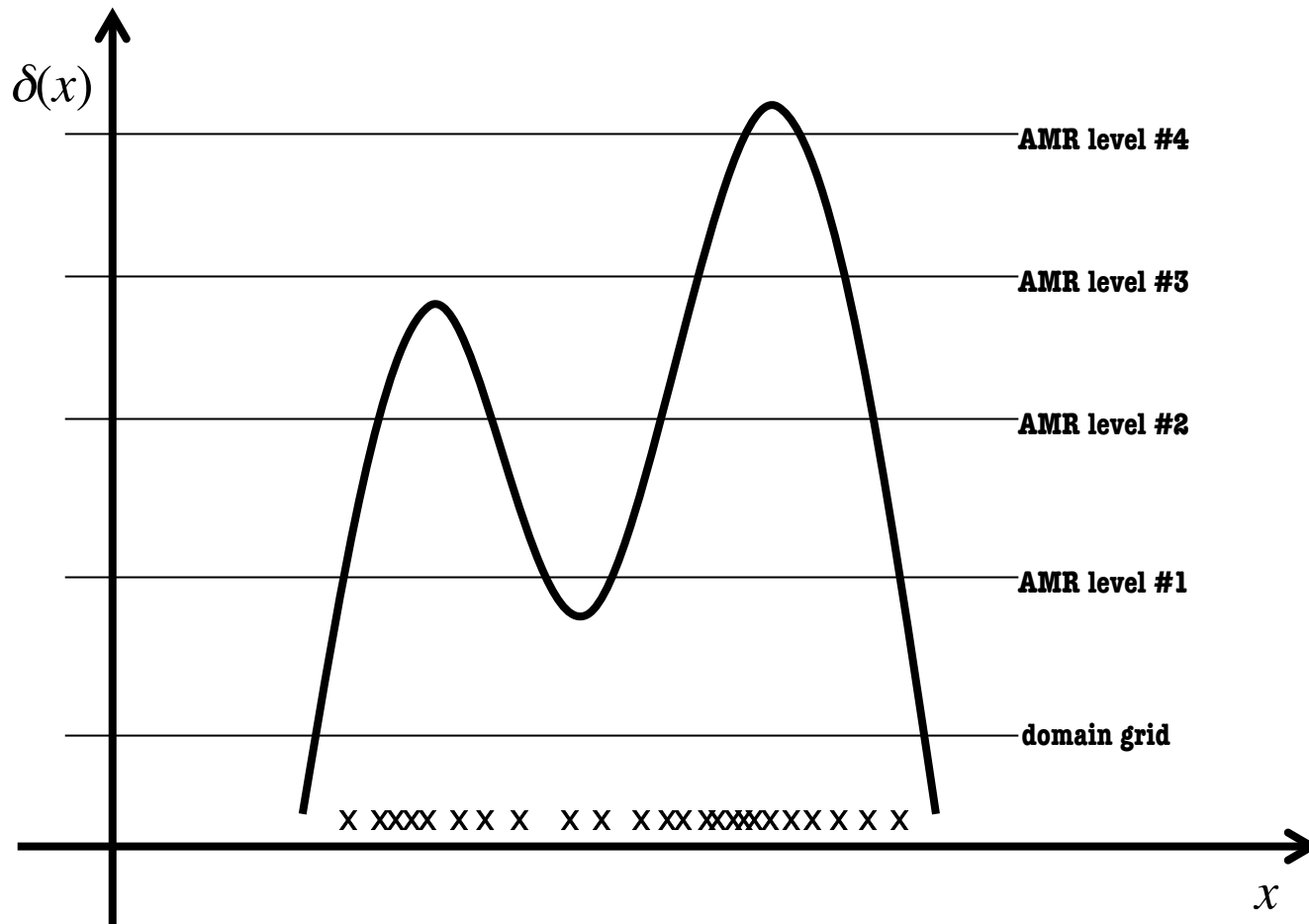
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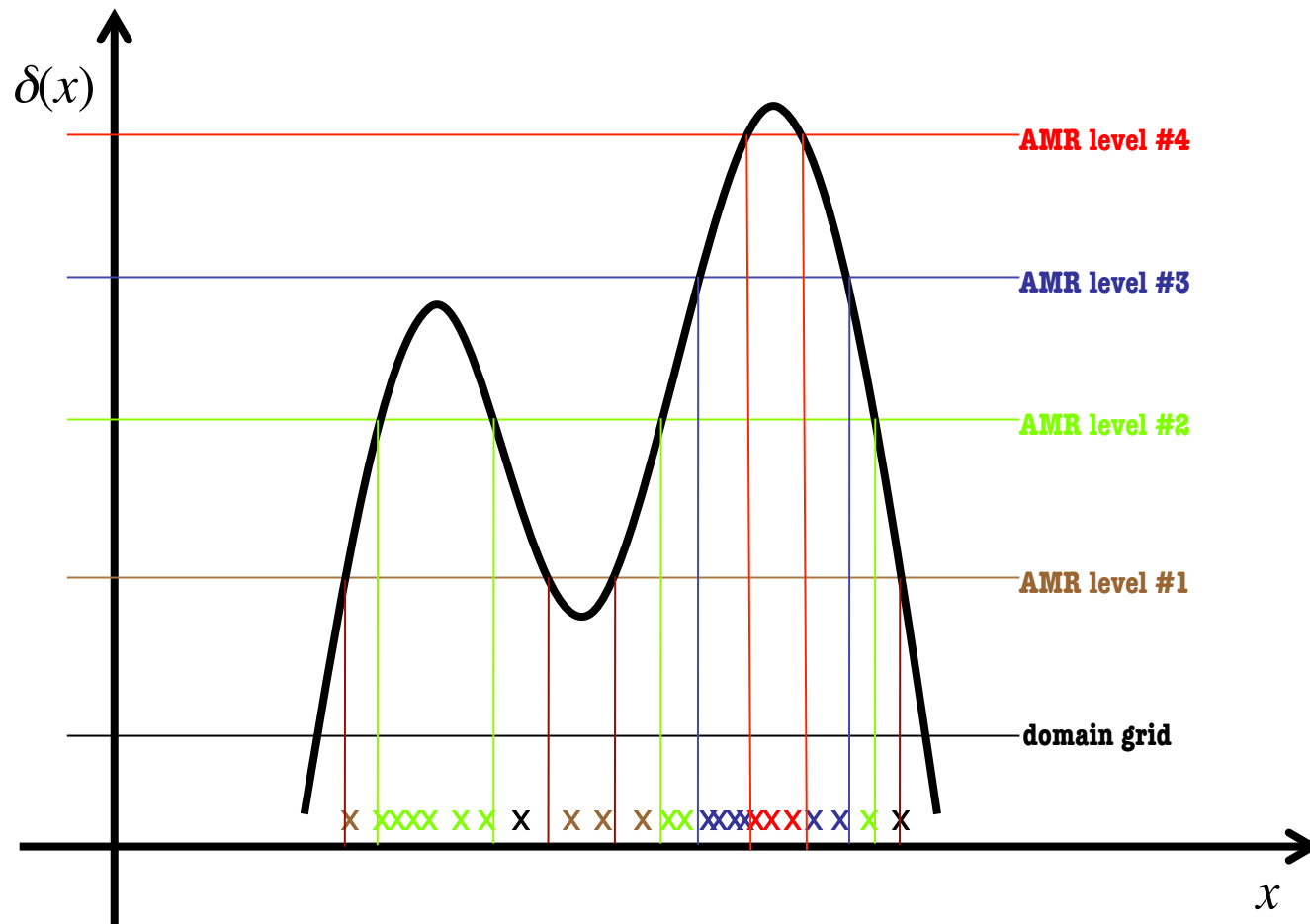
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Solving for Gravity

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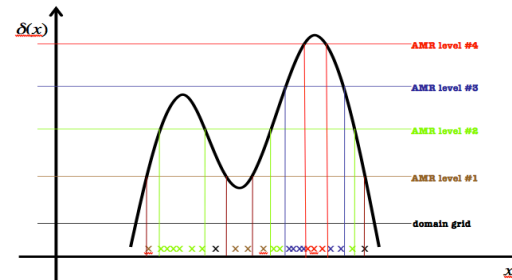


### Solving for Gravity

- adaptive mesh refinement – refinement criterion

- density:

- refine regions of high density



- truncation error:

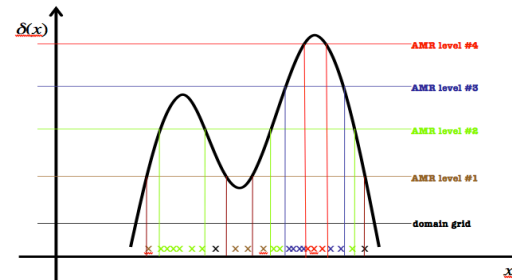
- physics:

Solving for Gravity

- adaptive mesh refinement – refinement criterion

- density:

- refine regions of high density



- truncation error:

- refine regions of large truncation errors

$$R_{k,l,m}^i = \Delta\Phi_{k,l,m}^i - \rho_{k,l,m} \leq \epsilon T_{k,l,m} \quad \text{with} \quad T_{k,l,m} = \mathcal{P}\left[\Delta\left(\mathcal{R}\Phi_{k,l,m}^i\right)\right] - \left(\Delta\Phi_{k,l,m}^i\right)$$

- physics:

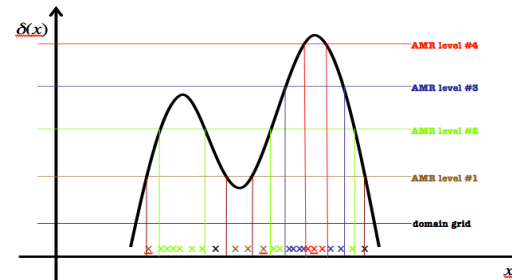


Solving for Gravity

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- physics:

- compare grid spacing against local critical wavelength

$$\Delta x < \epsilon \lambda \quad \text{with} \quad \lambda = c_s \sqrt{\frac{\pi}{G\rho}}$$

## Solving for Gravity

- mesh refinements
- adaptive mesh refinement
- **adaptive mesh refinement for  $N$ -body codes**
- handling irregular grids
- adaptive leap-frog integration

## Solving for Gravity

---

- mesh refinements
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- **adaptive mesh refinement for  $N$ -body codes**
  - gravity
  - generating refinements
  - density assignment
  - solving Poisson's equation
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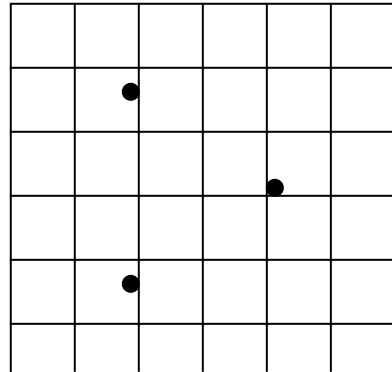
## Solving for Gravity

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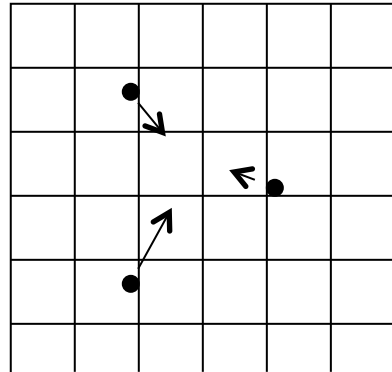
## Solving for Gravity

- gravity tends to clump matter together...



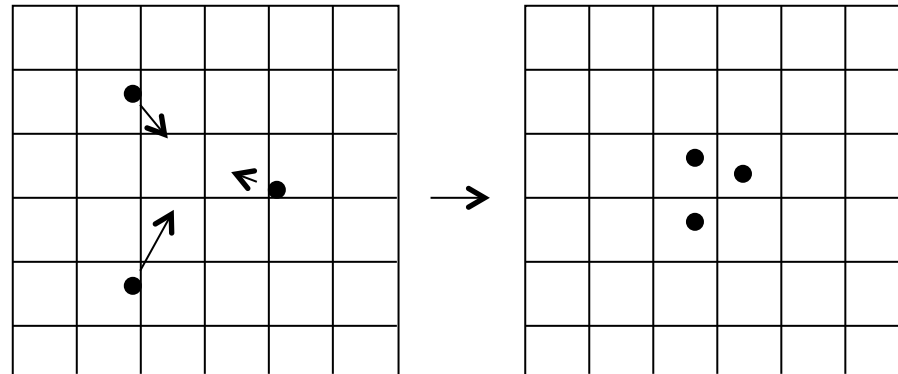
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## Solving for Gravity

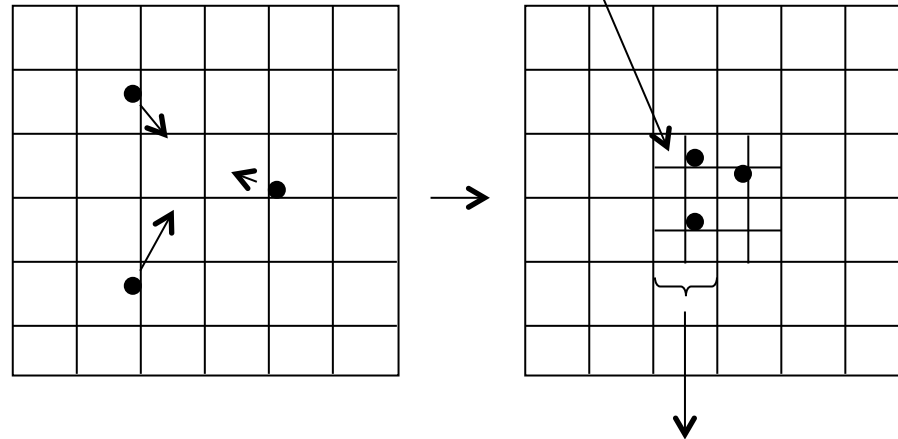
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## Solving for Gravity

- gravity tends to clump matter together...

introduce finer grids where needed...



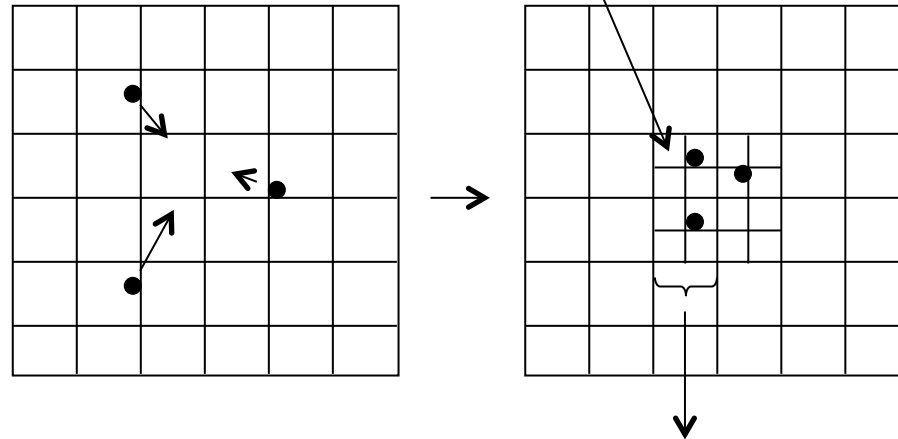
...and gain a factor of 2 in accuracy  
(in regions of interest)



## Solving for Gravity

- gravity tends to clump matter together...

introduce finer grids where needed...

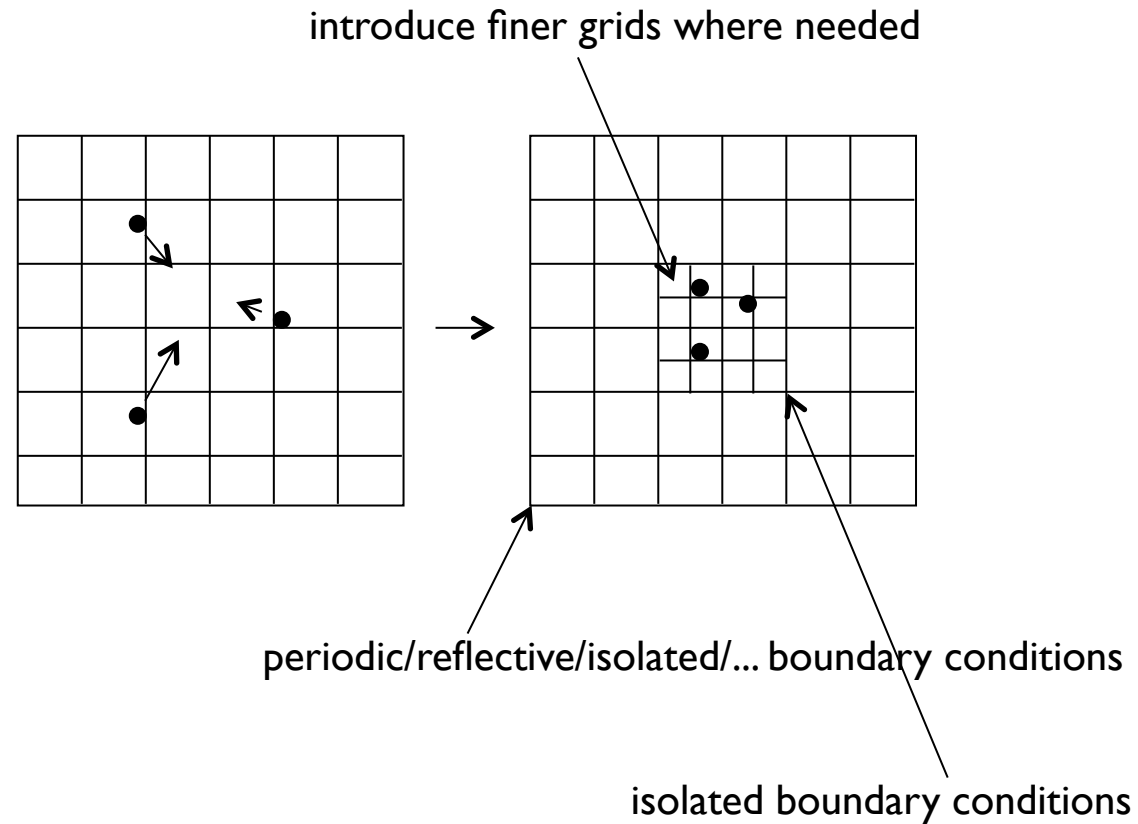


...and gain a factor of 2 in accuracy  
(in regions of interest)

**factor 2 not mandatory, but most common choice...**

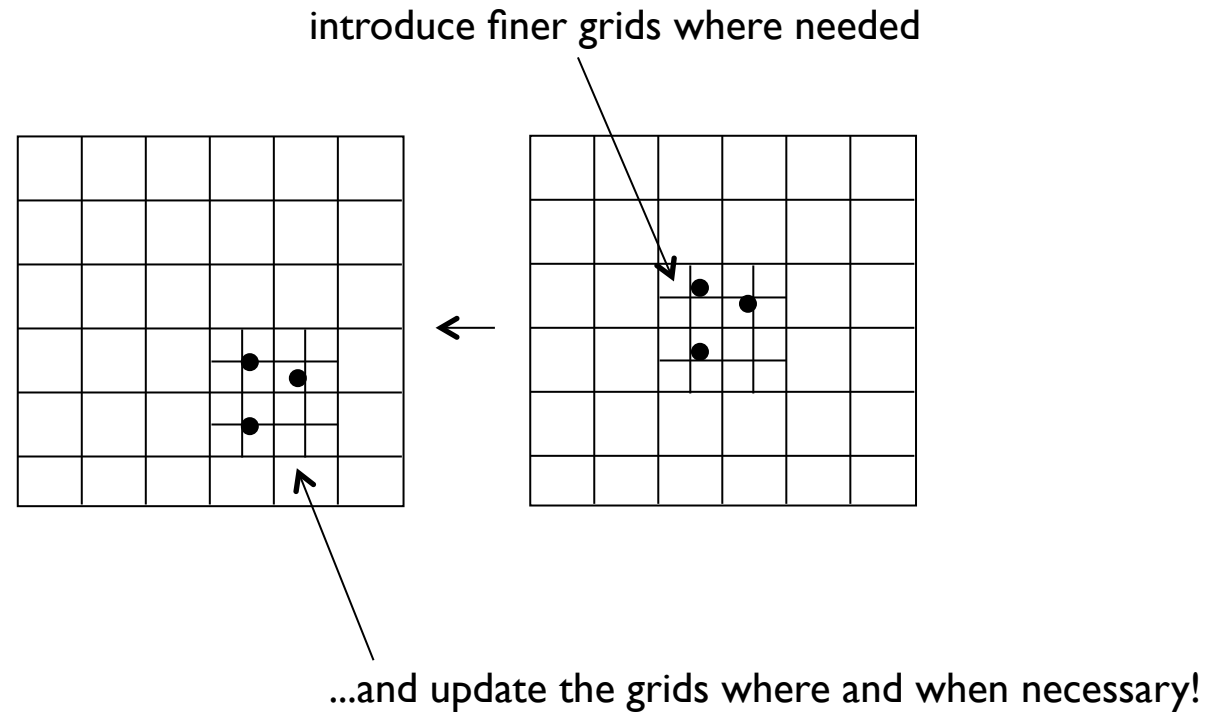
## Solving for Gravity

- gravity tends to clump matter together...



## Solving for Gravity

- gravity tends to clump matter together...



## Solving for Gravity

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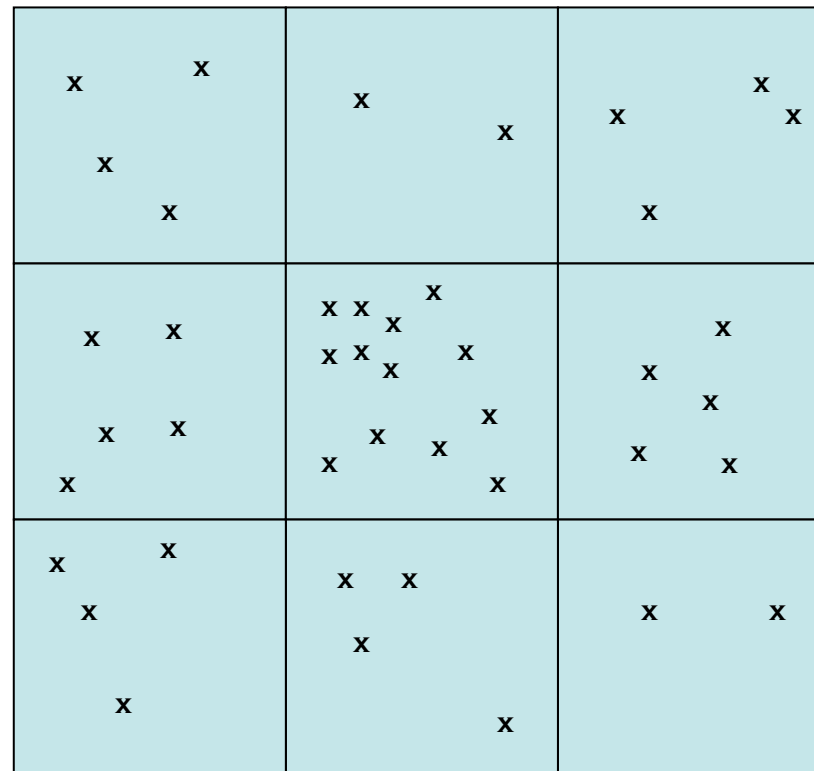
- mesh refinements
- adaptive mesh refinement
- **adaptive mesh refinement for  $N$ -body codes**
  - gravity
  - ***generating refinements***
  - density assignment
  - solving Poisson's equation
- handling irregular grids
- adaptive leap-frog integration

Solving for Gravity

- generating refinements

- *N*-body simulations:

number of particles per cell



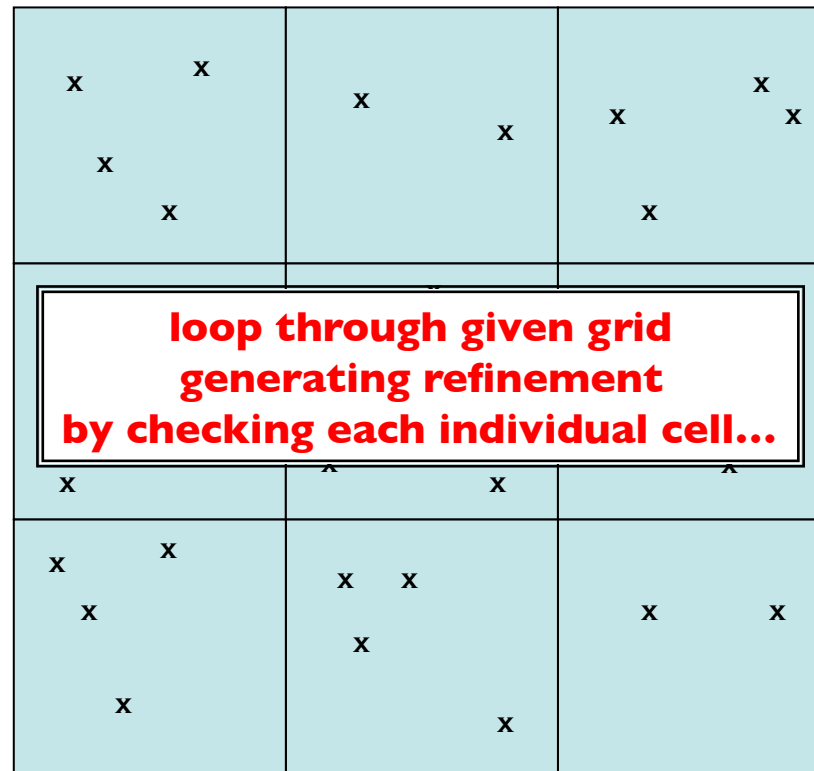
refinement criterion: 6 particles/cell

Solving for Gravity

- generating refinements

- *N*-body simulations:

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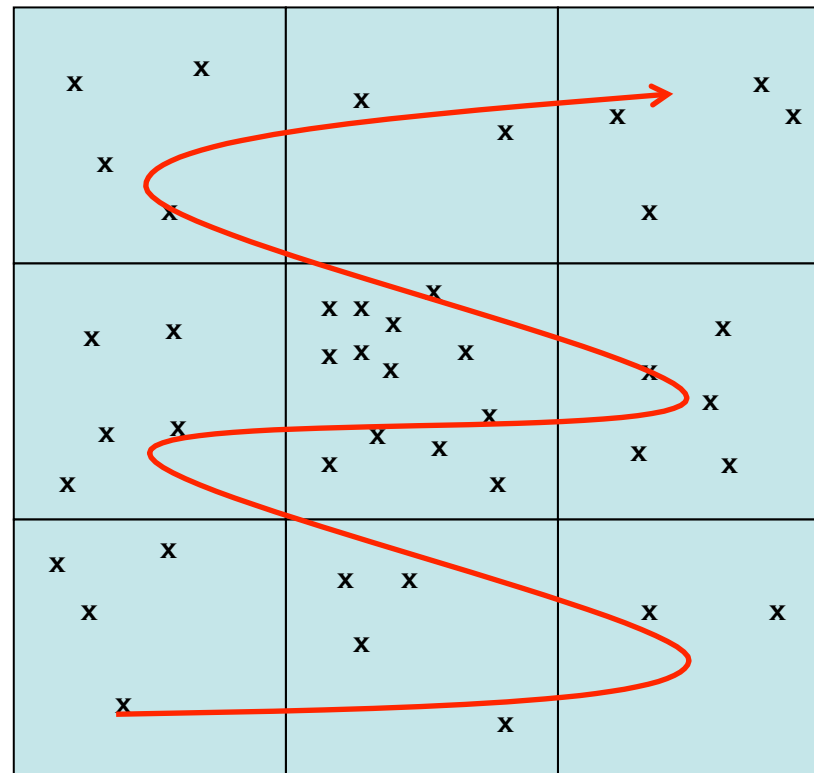
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Solving for Gravity

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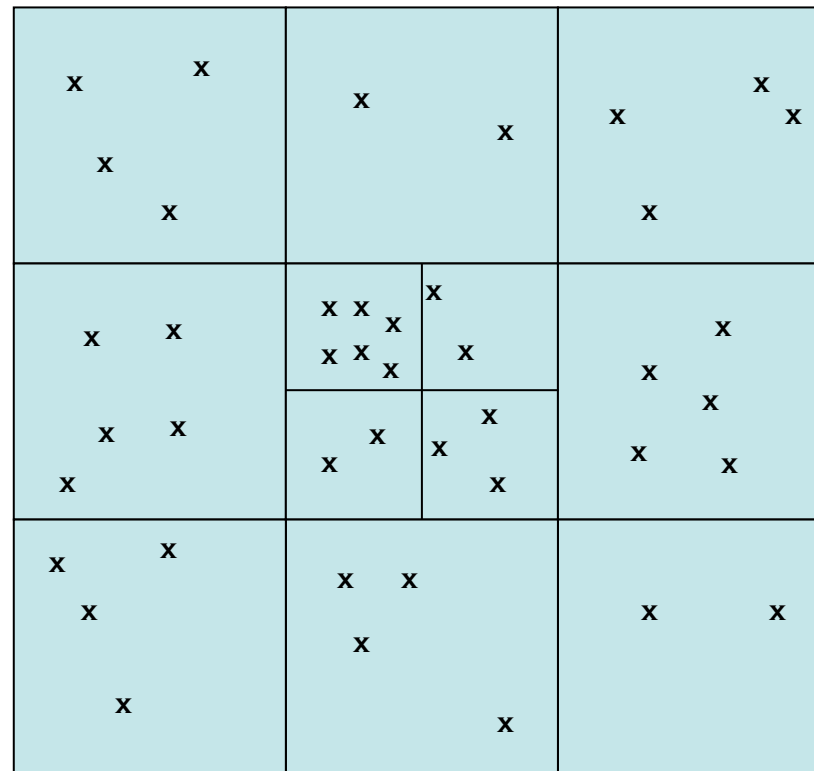
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Solving for Gravity

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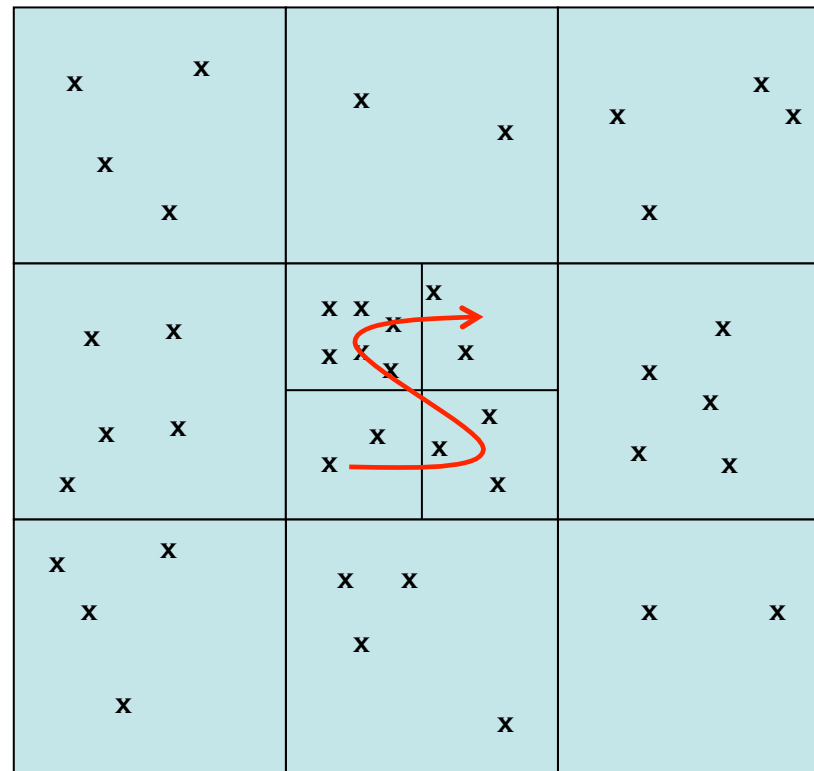


Solving for Gravity

- generating refinements

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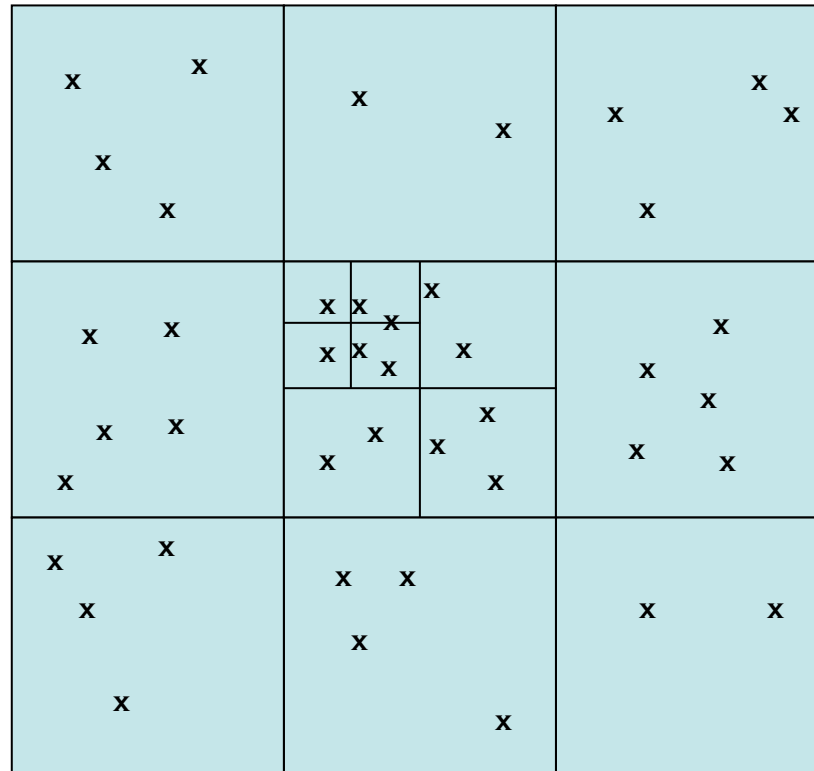
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Solving for Gravity

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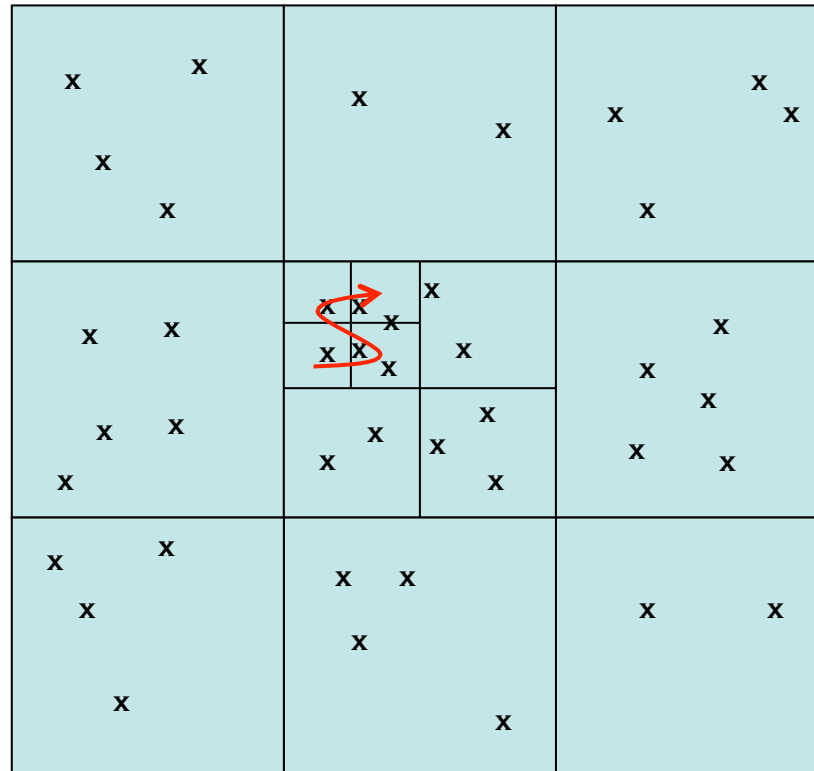
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Solving for Gravity

- generating refinements

- *N*-body simulations:

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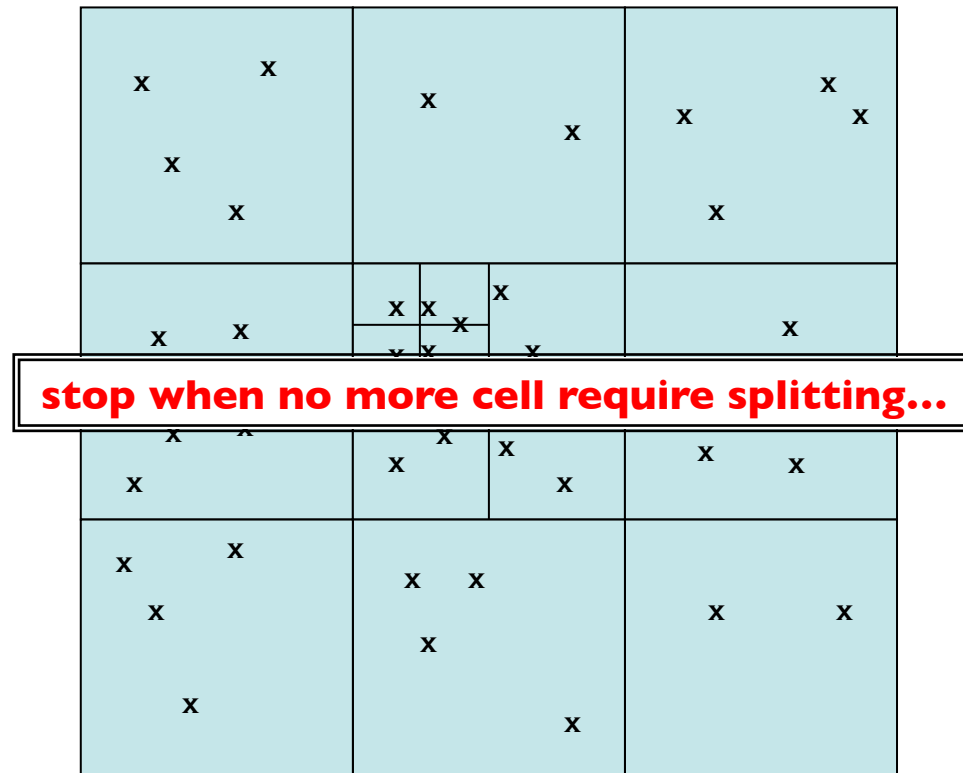
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Solving for Gravity

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- *N*-body simulations:

number of particles per cell

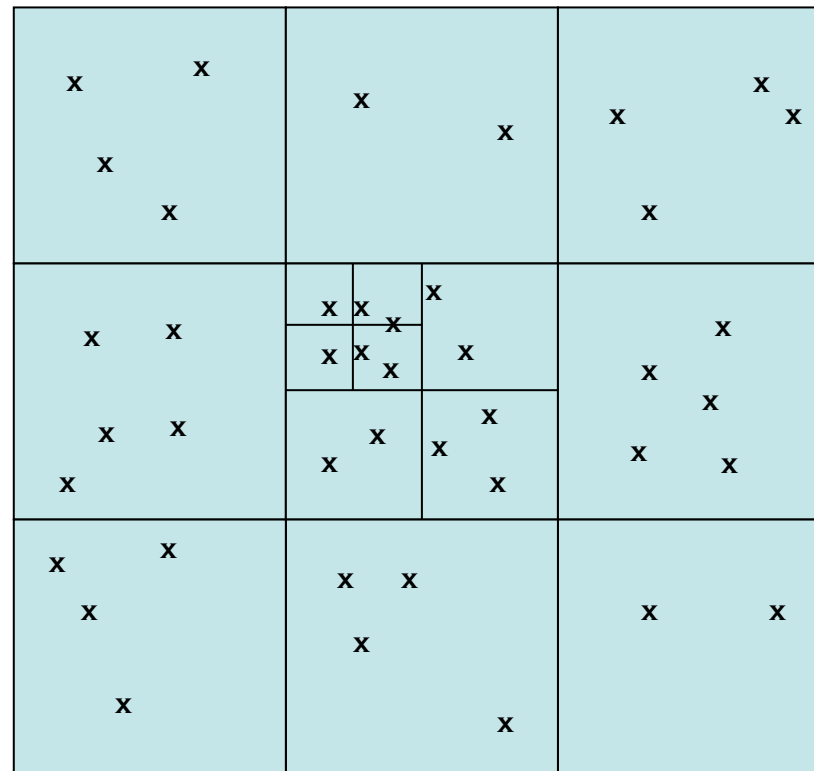


refinement criterion: 6 particles/cell

Solving for Gravity

- generating refinements
  - *N*-body simulations:

number of particles per cell



refinement criterion: 6 particles/cell

**Note:**

in this scheme we split the volume of a coarse cell into eight equal sub-cells...

=> **non-cospatial scheme!**

## Solving for Gravity

- generating refinements
  - interpolation between grids:

$$f(x_i) = F(x_i) + F'(x_i)\Delta x$$

$F$  = value on coarse grid

$f$  = value on fine grid

Solving for Gravity

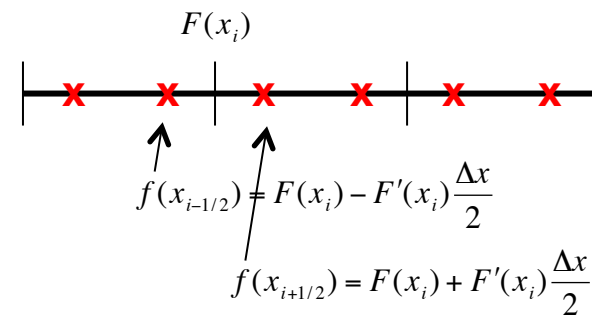
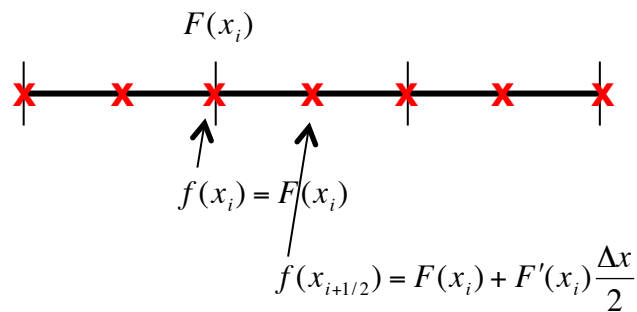
- generating refinements
  - interpolation between grids:

$$f(x_i) = F(x_i) + F'(x_i)\Delta x$$

co-spatial

vs.

non-cospatial



## Solving for Gravity

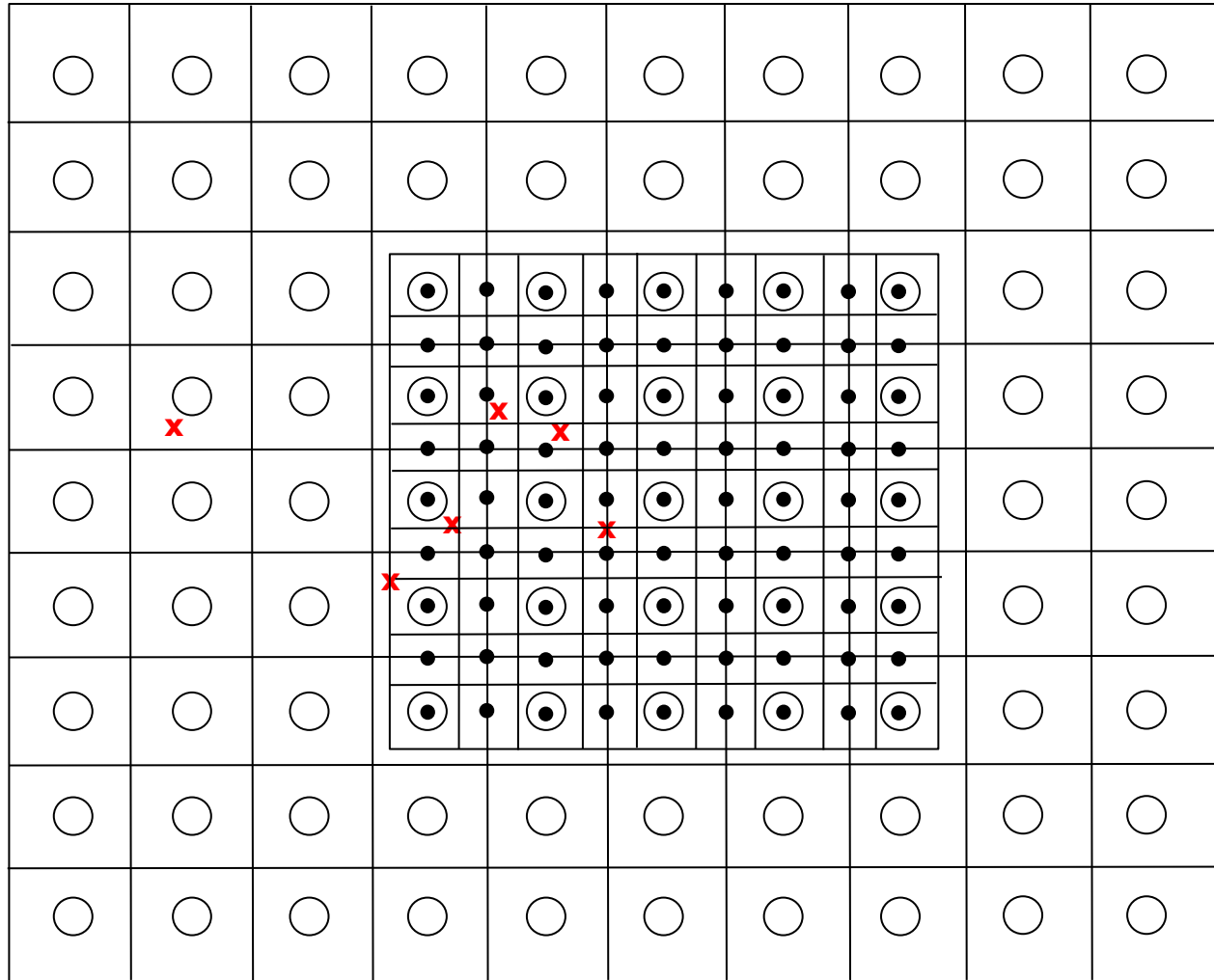
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- mesh refinements
- adaptive mesh refinement
- **adaptive mesh refinement for  $N$ -body codes**
  - gravity
  - generating refinements
  - **density assignment**
  - solving Poisson's equation
- handling irregular grids
- adaptive leap-frog integration



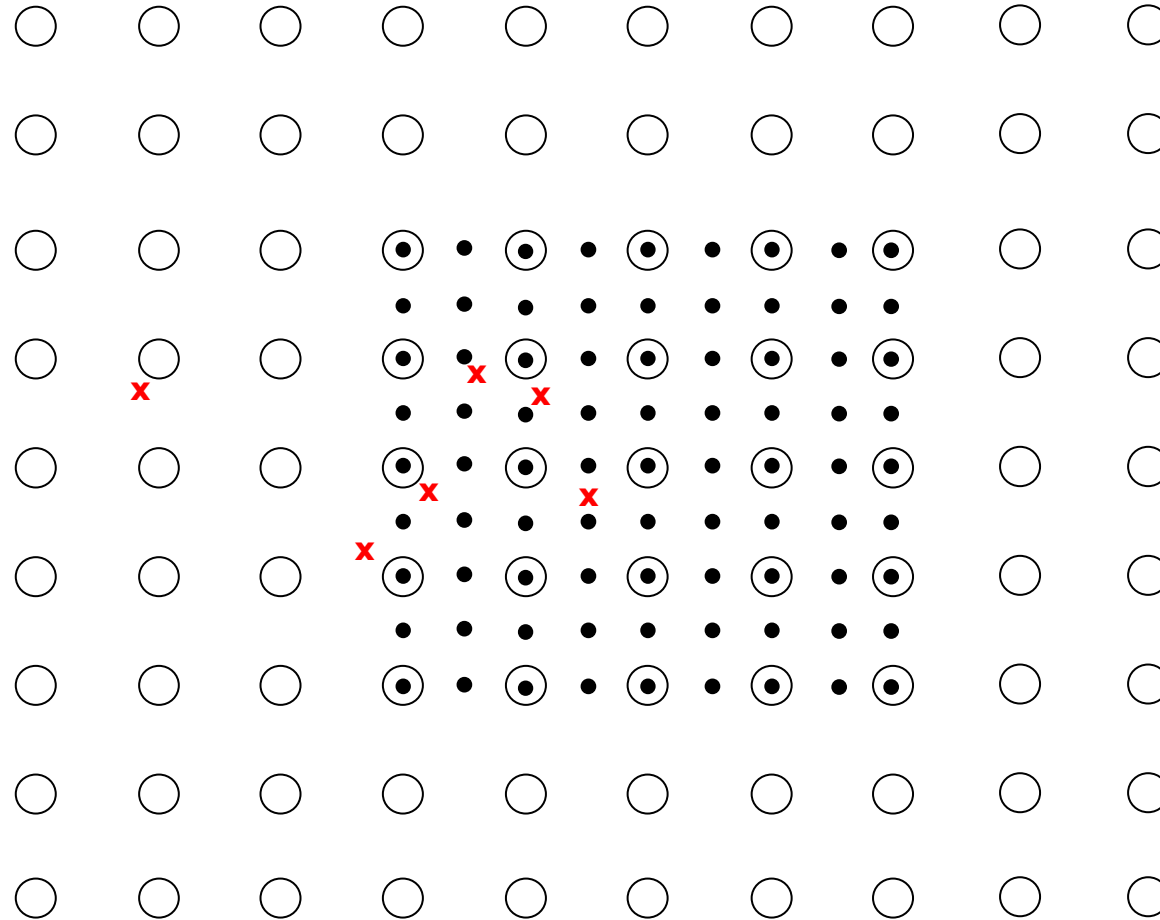
## Solving for Gravity

- density assignment (co-spatial scheme)



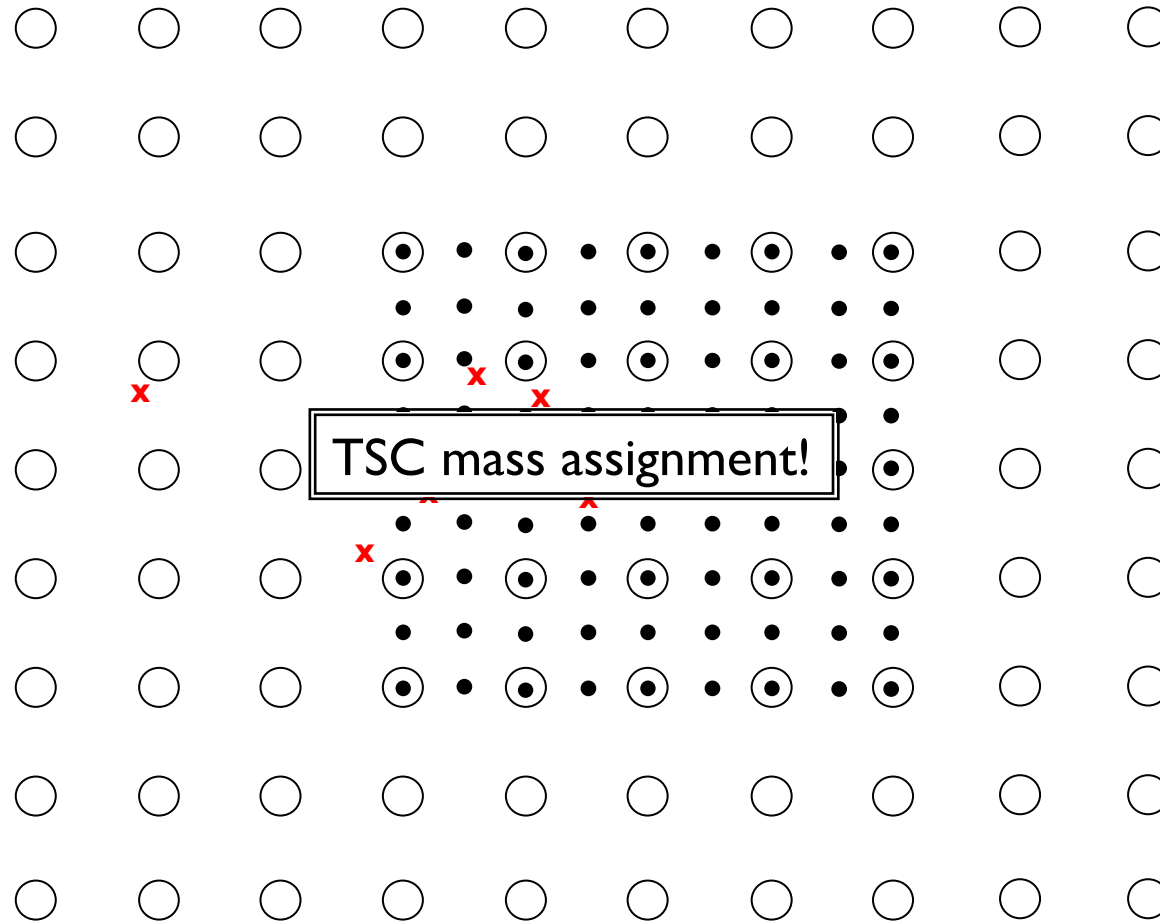
## Solving for Gravity

- density assignment (co-spatial scheme)



Solving for Gravity

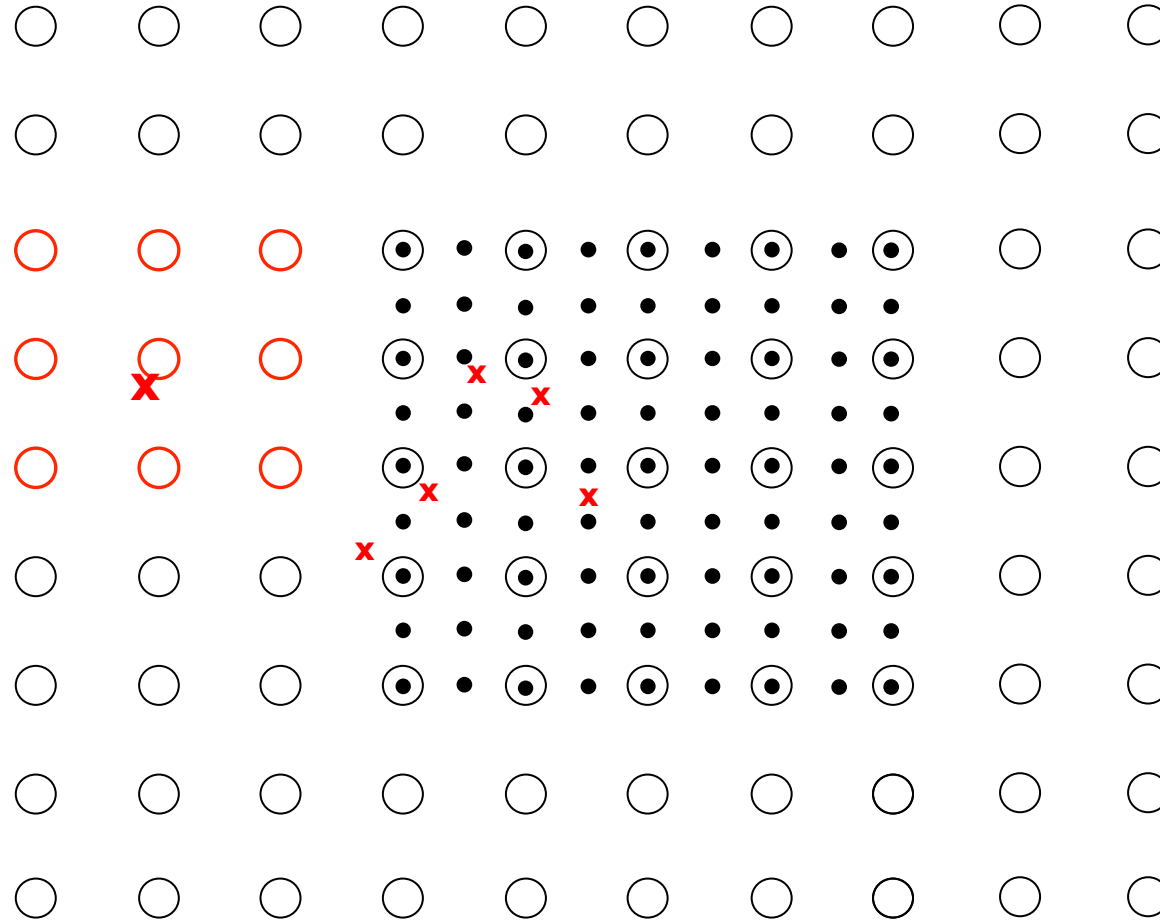
- density assignment (co-spatial scheme)



## Solving for Gravity

- density assignment (co-spatial scheme)

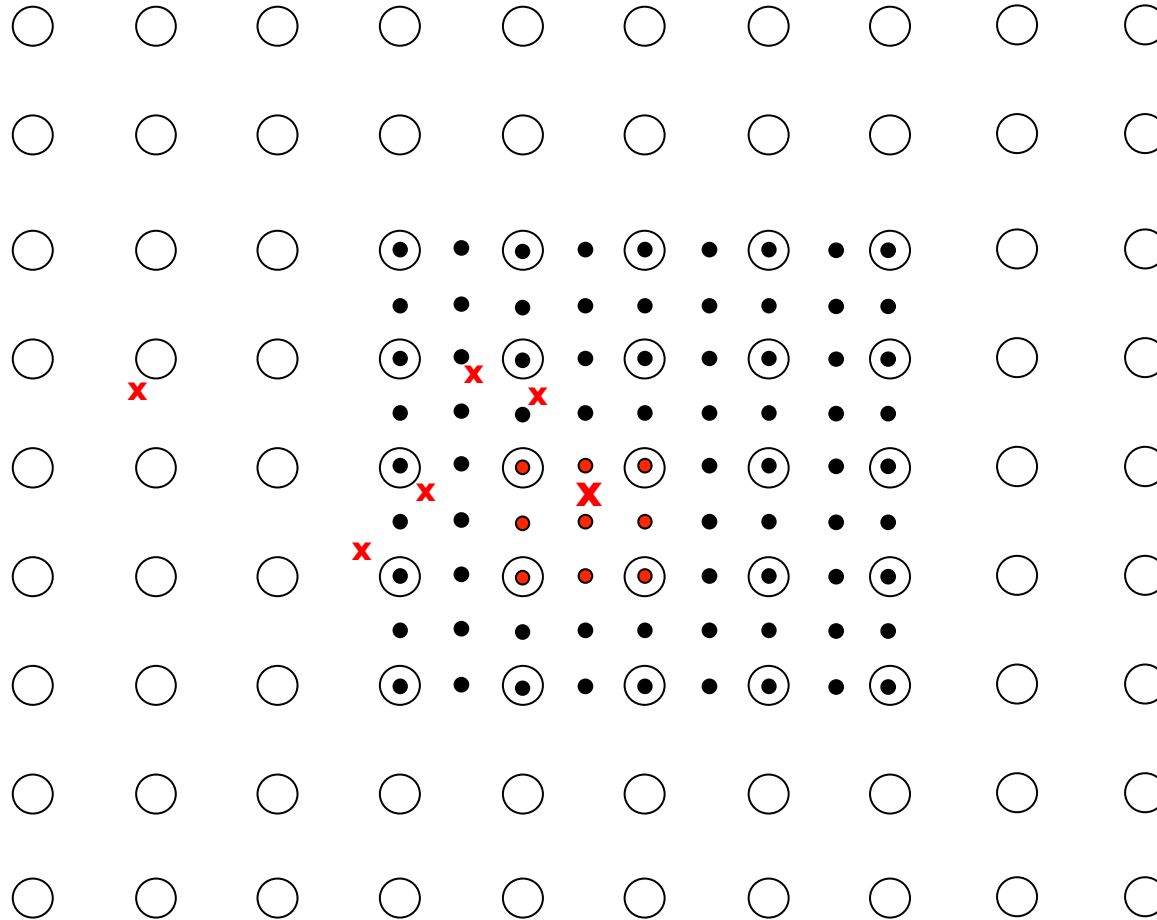
unproblematic:



## Solving for Gravity

- density assignment (co-spatial scheme)

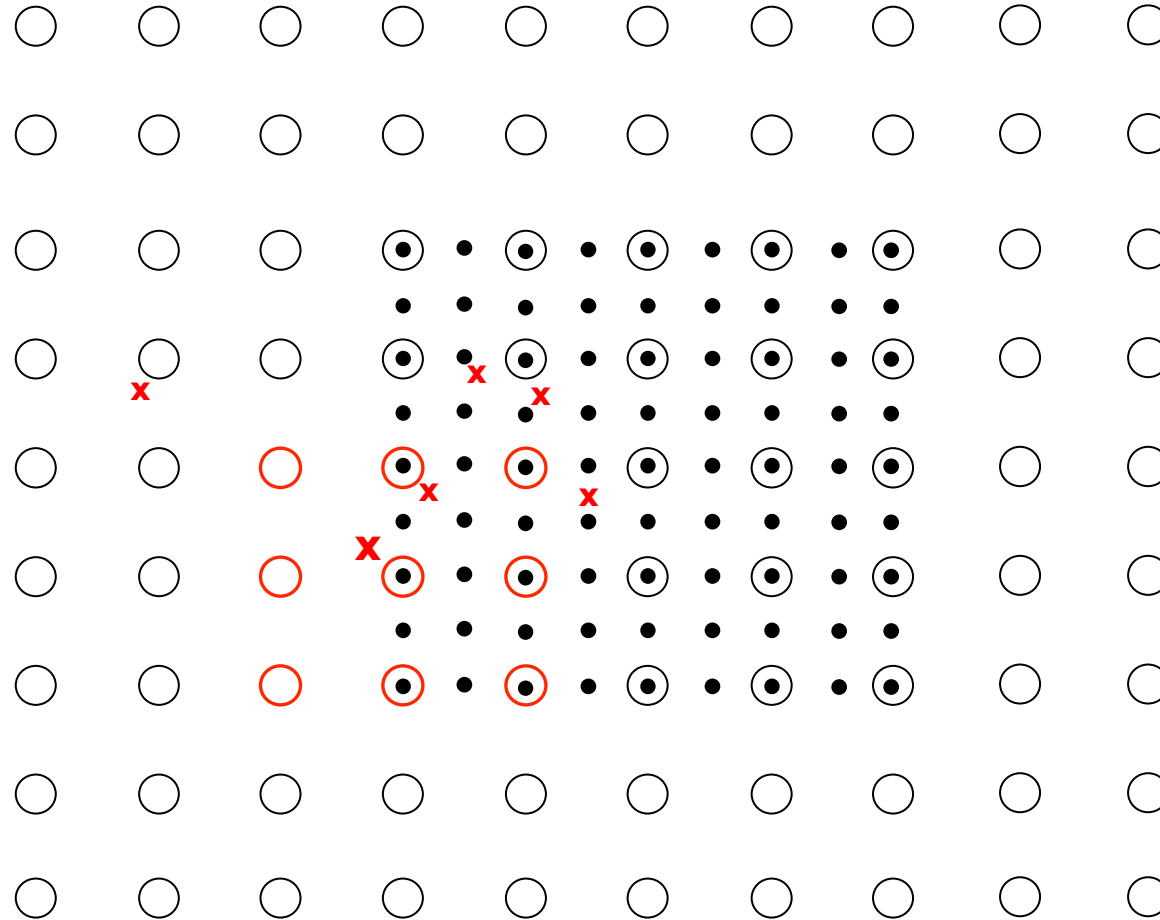
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## Solving for Gravity

- density assignment (co-spatial scheme)

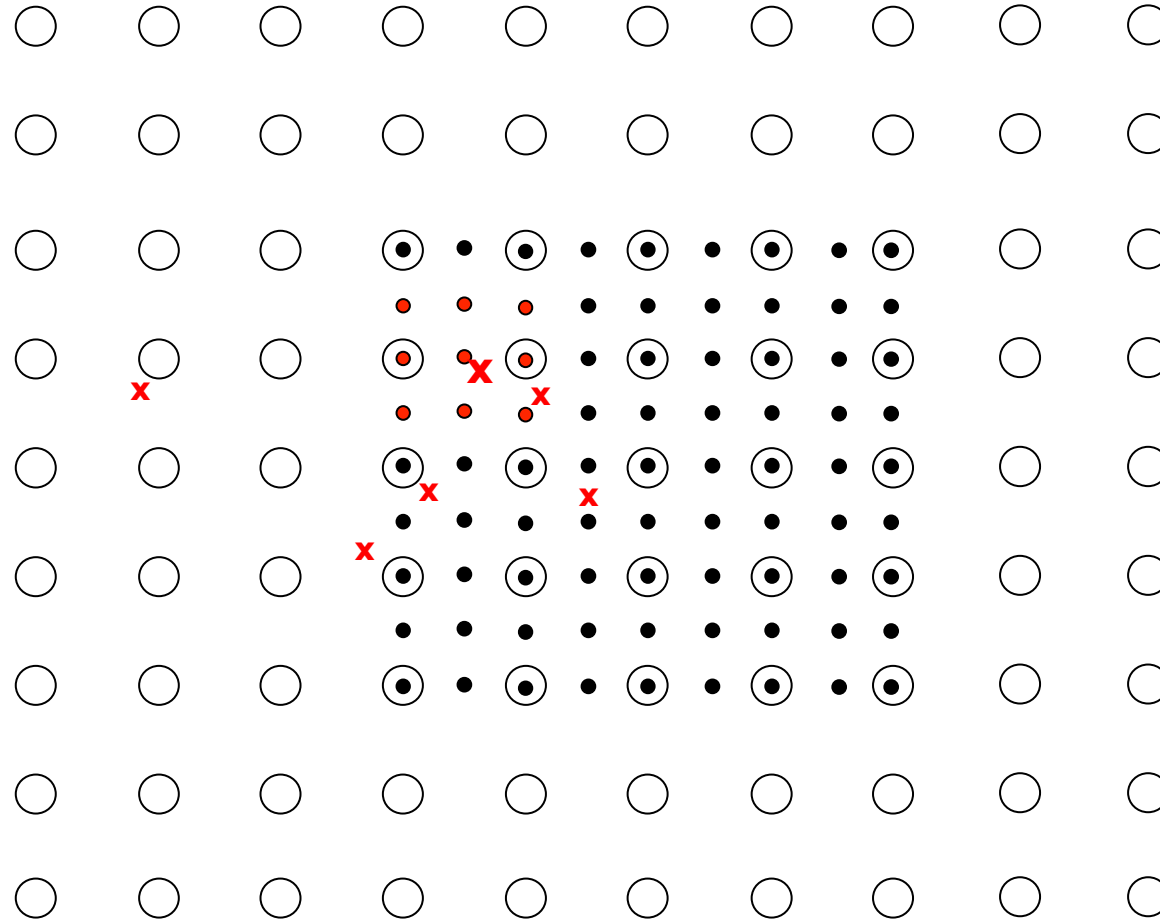
problematic:



## Solving for Gravity

- density assignment (co-spatial scheme)

problematic:



## Solving for Gravity

- **density assignment** (co-spatial scheme)

- steps required to get density correct on both coarse and fine grid...

1. transfer particles from coarse to fine grid
2. assign “coarse” particles to coarse grid
3. assign “fine” particles to refinement grid
4. temporarily store “borderline” density
5. inject refinement density to coarse grid
6. add “borderline” density to refinement



## Solving for Gravity

- **density assignment** (co-spatial scheme)

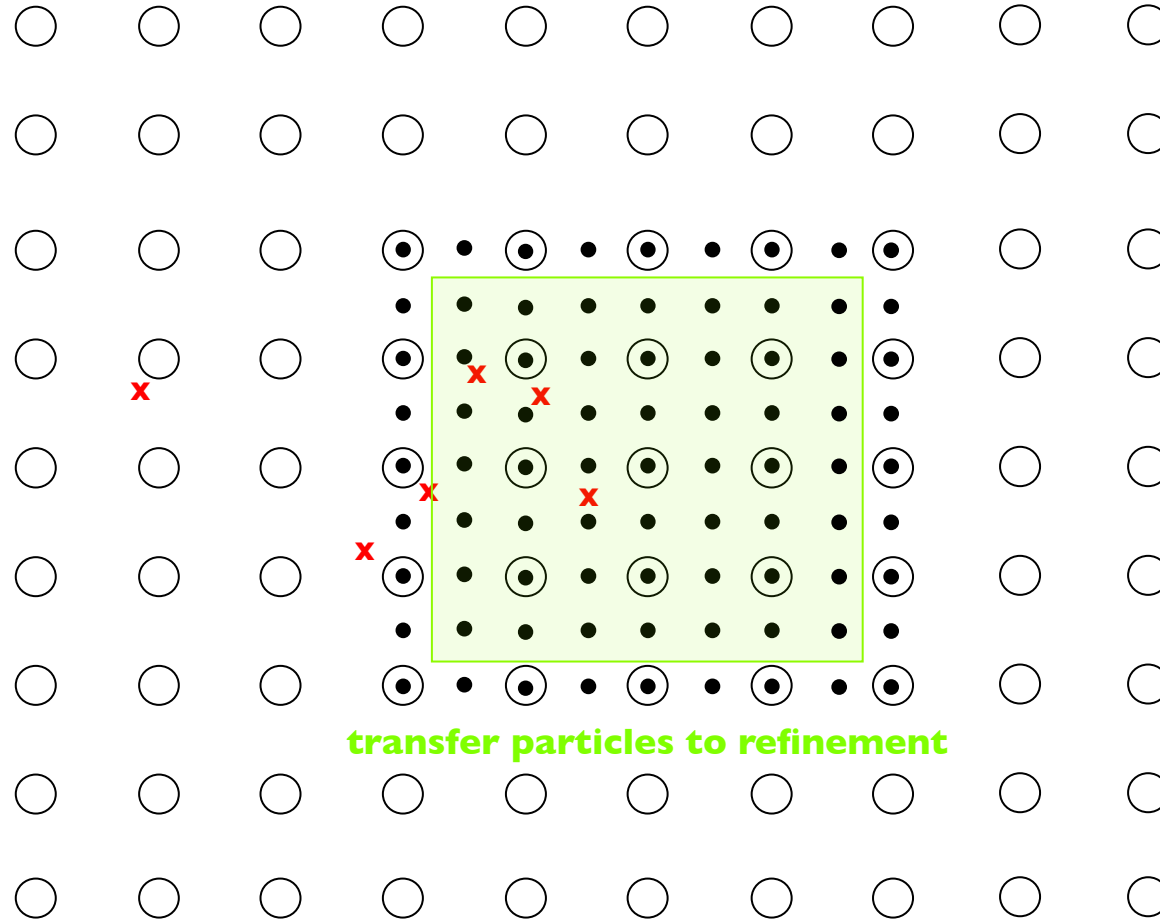
- steps required to get density correct on both coarse and fine grid...

- 1. transfer particles from coarse to fine grid**

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## Solving for Gravity

- density assignment (co-spatial scheme)



## Solving for Gravity

- **density assignment** (co-spatial scheme)

- steps required to get density correct on both coarse and fine grid...

1. transfer particles from coarse to fine grid

- 2. assign “coarse” particles to coarse grid**

3. assign “fine” particles to refinement grid

4. temporarily store “borderline” density

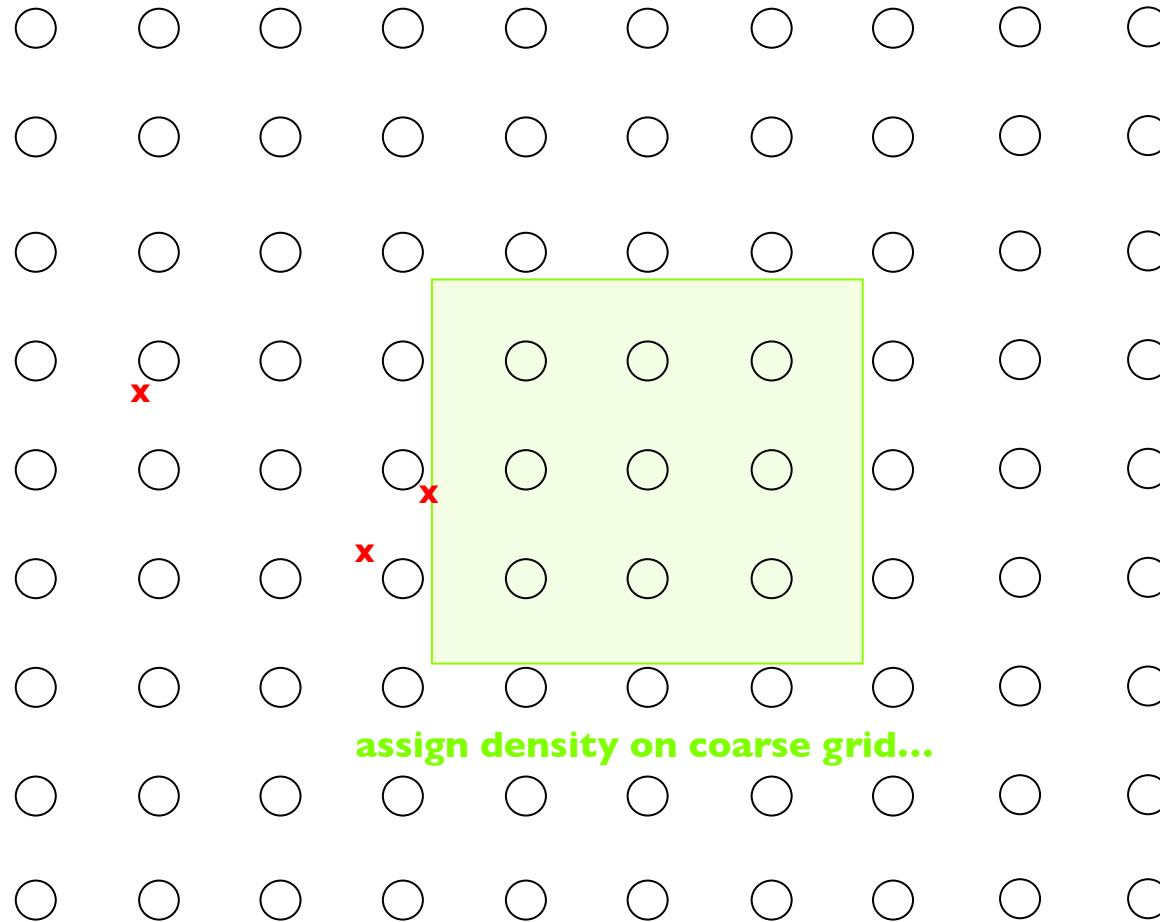
5. inject refinement density to coarse grid

6. add “borderline” density to refinement

Solving for Gravity

- density assignment (co-spatial scheme)

**density on coarse grid**

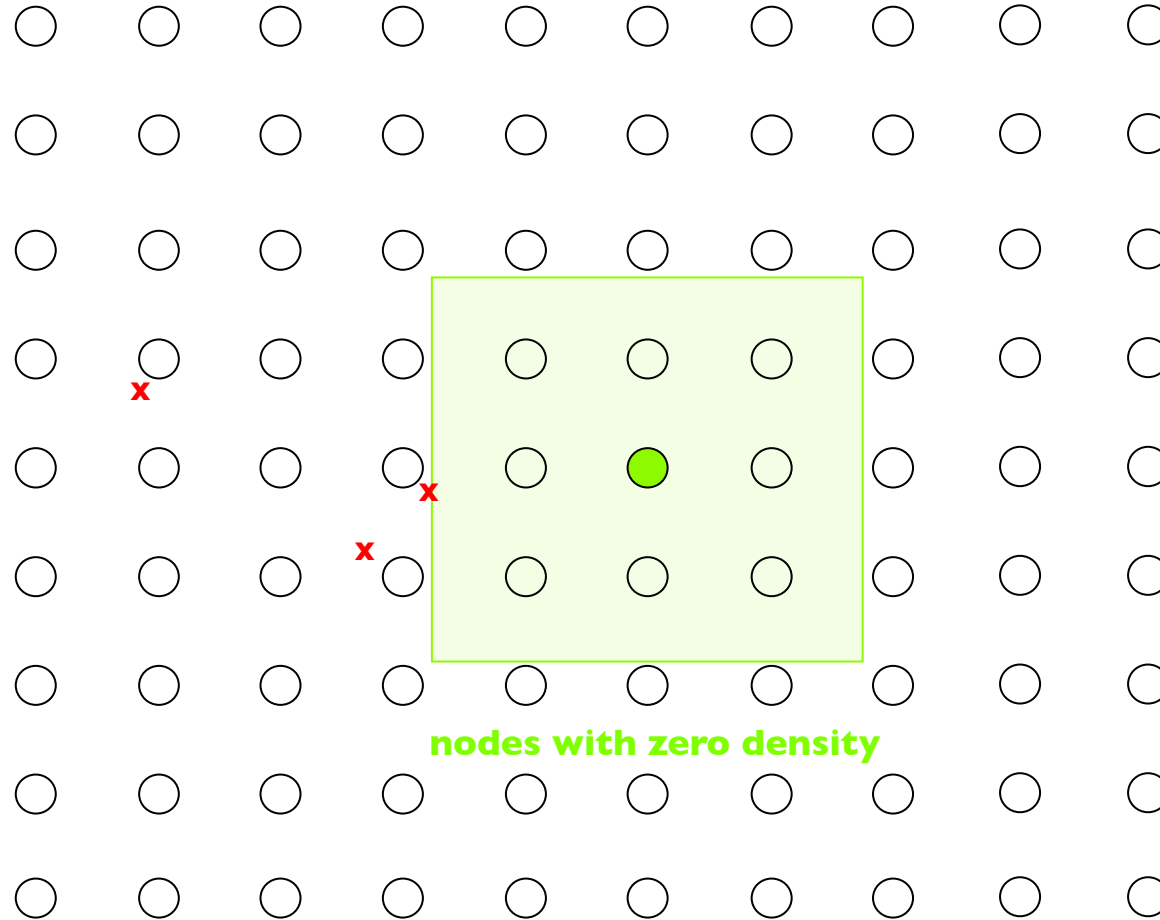


**assign density on coarse grid...**

Solving for Gravity

- density assignment (co-spatial scheme)

**density on coarse grid**

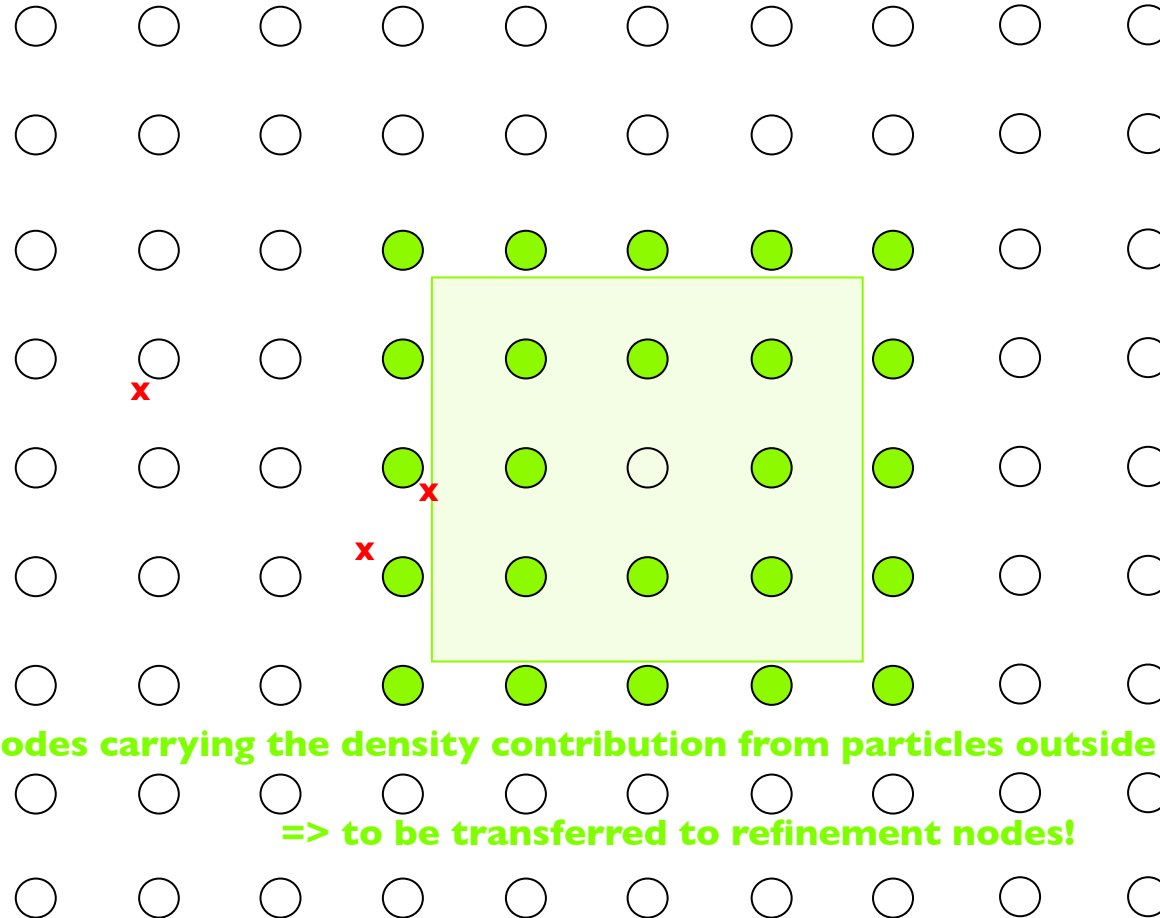


**nodes with zero density**

Solving for Gravity

- density assignment (co-spatial scheme)

**density on coarse grid**



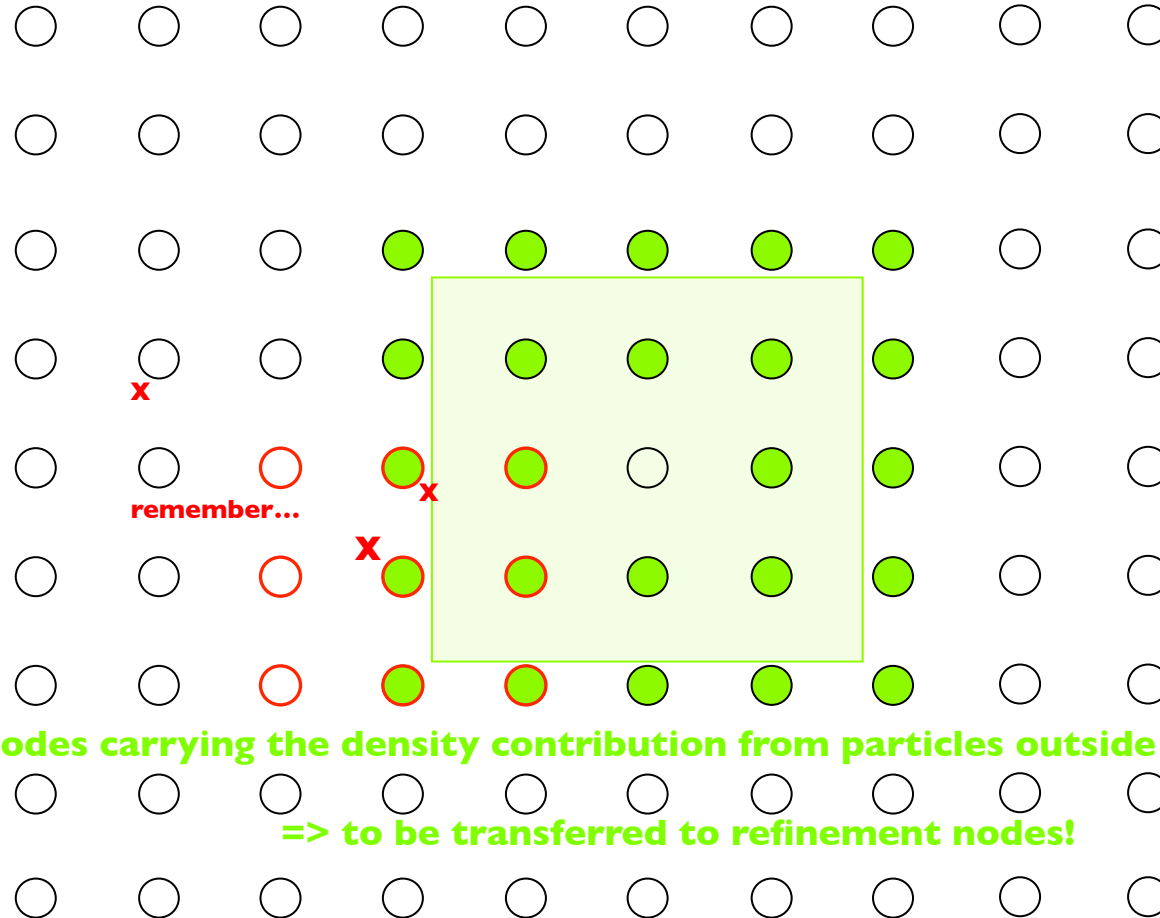
**nodes carrying the density contribution from particles outside refinement**

**=> to be transferred to refinement nodes!**

Solving for Gravity

- density assignment (co-spatial scheme)

density on coarse grid

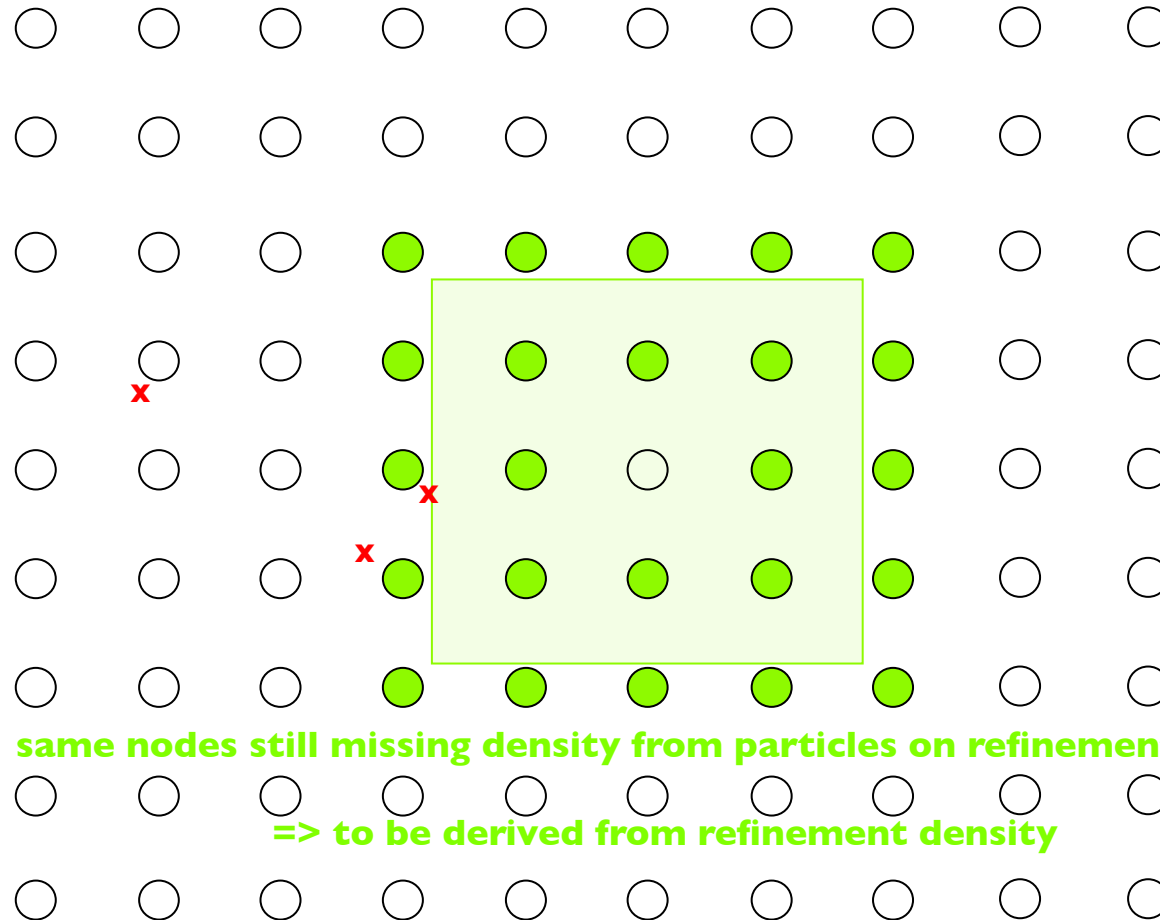


nodes carrying the density contribution from particles outside refinement  
=> to be transferred to refinement nodes!

Solving for Gravity

- density assignment (co-spatial scheme)

**density on coarse grid**

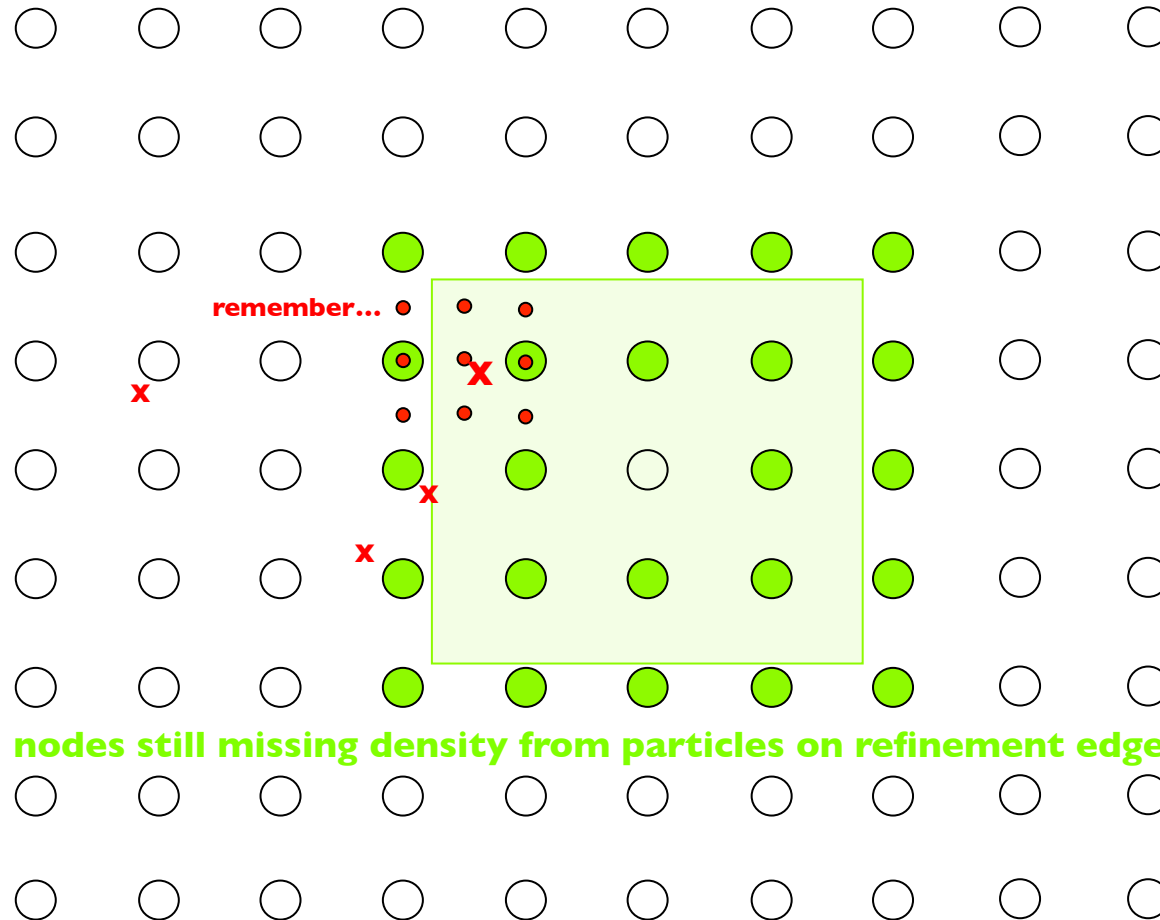




Solving for Gravity

- density assignment (co-spatial scheme)

density on coarse grid



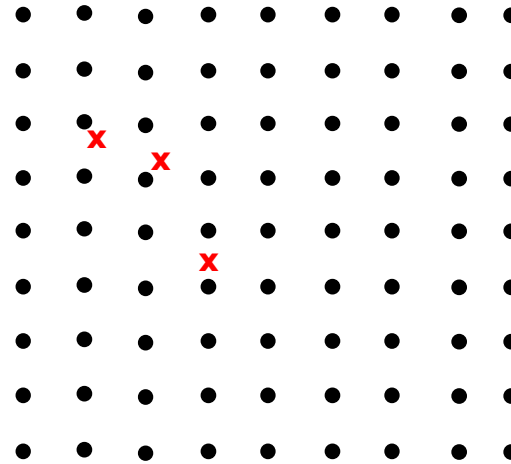
## Solving for Gravity

- **density assignment** (co-spatial scheme)
  - steps required to get density correct on both coarse and fine grid...
    1. transfer particles from coarse to fine grid
    2. assign “coarse” particles to coarse grid
    - 3. assign “fine” particles to refinement grid**
    4. temporarily store “borderline” density
    5. inject refinement density to coarse grid
    6. add “borderline” density to refinement

Solving for Gravity

- density assignment (co-spatial scheme)

**density on refinement grid**

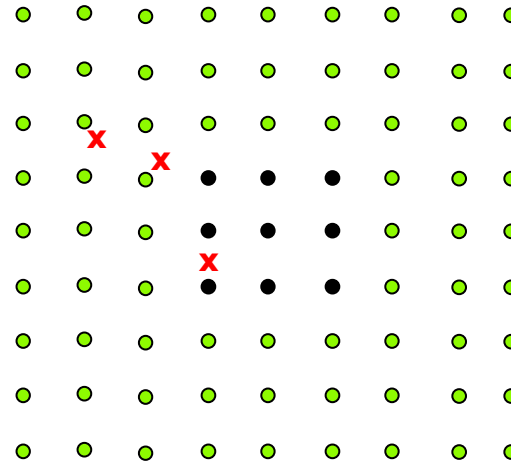


**assign density on refinement grid...**

## Solving for Gravity

- density assignment (co-spatial scheme)

### density on refinement grid

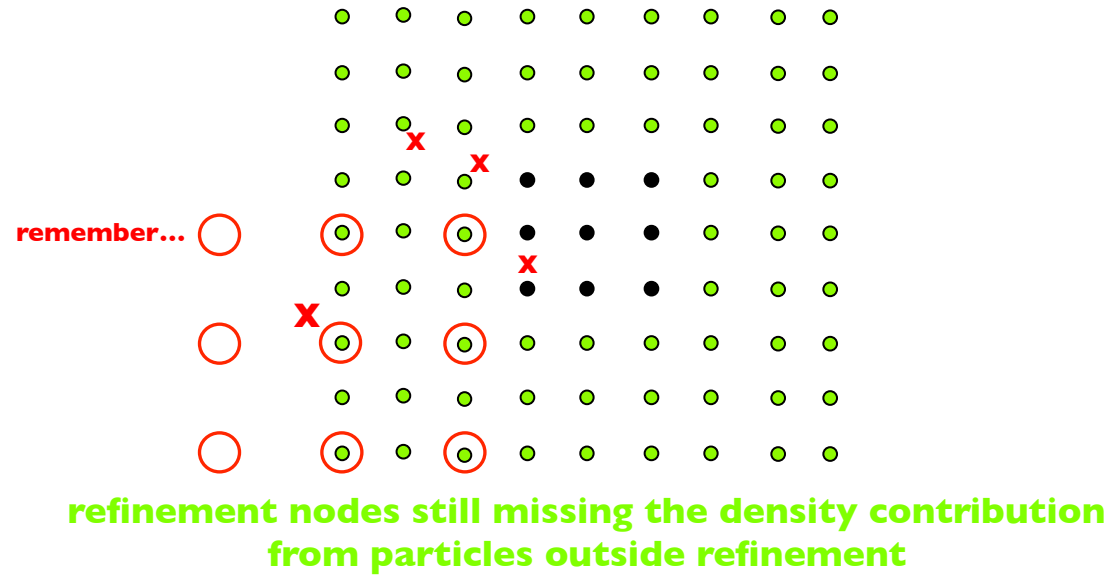


**refinement nodes still missing the density contribution  
from particles outside refinement**

Solving for Gravity

- density assignment (co-spatial scheme)

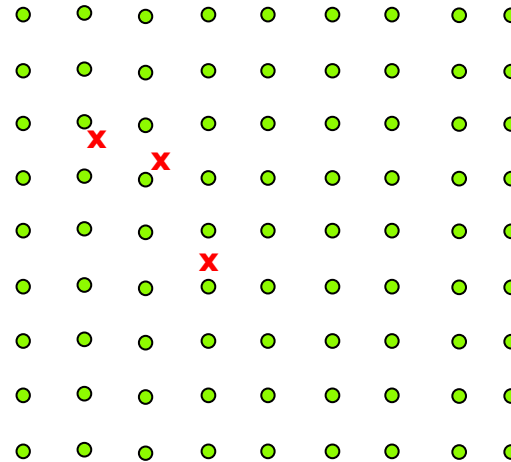
density on refinement grid



## Solving for Gravity

- density assignment (co-spatial scheme)

**density on refinement grid**



**all refinement nodes carry information required by coarse nodes...**

## Solving for Gravity

- **density assignment** (co-spatial scheme)

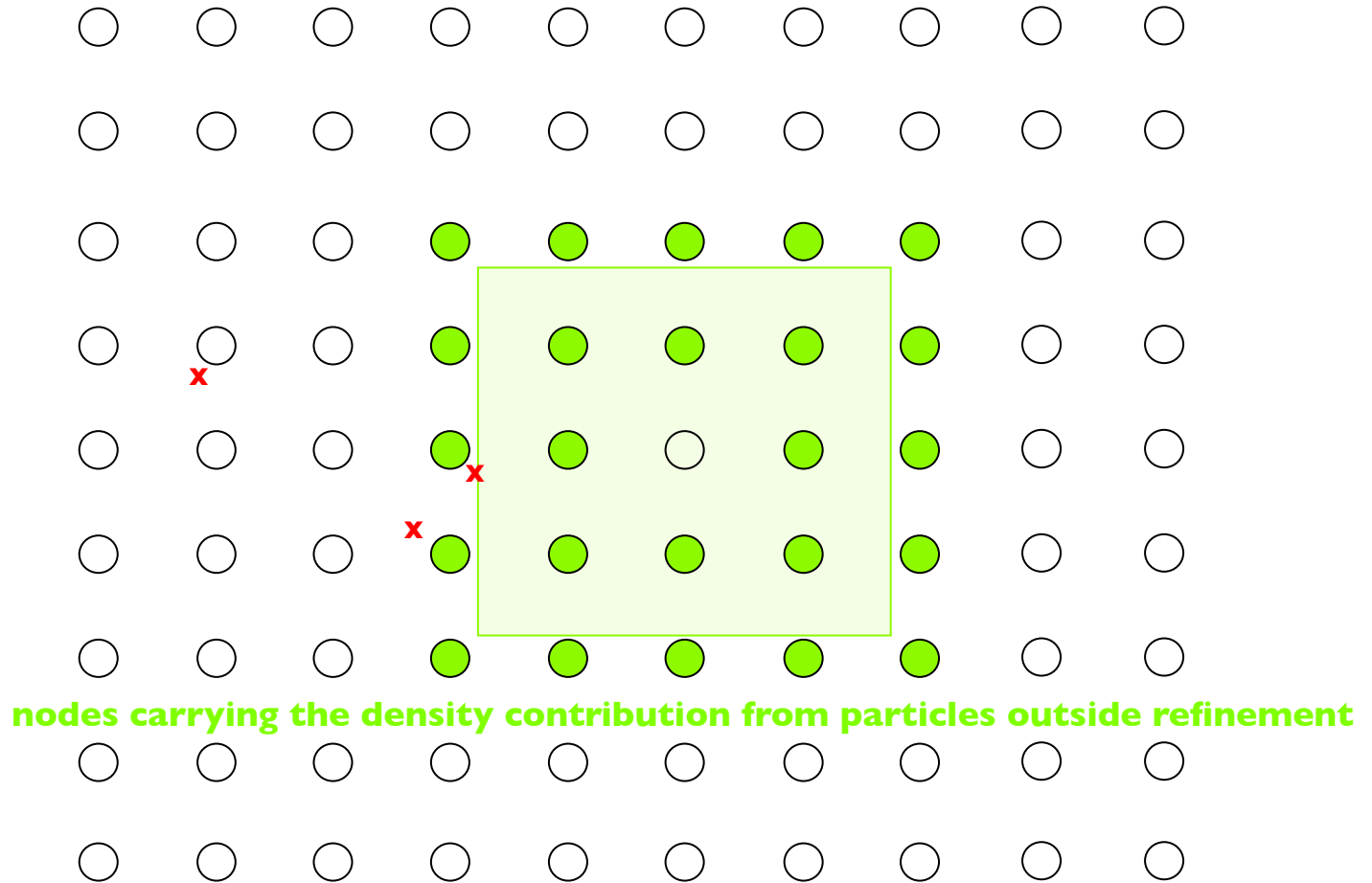
- steps required to get density correct on both coarse and fine grid...

1. transfer particles from coarse to fine grid
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- 4. temporarily store “borderline” density**
5. inject refinement density to coarse grid
6. add “borderline” density to refinement

Solving for Gravity

- density assignment (co-spatial scheme)

density on coarse grid





## Solving for Gravity

- **density assignment** (co-spatial scheme)

- steps required to get density correct on both coarse and fine grid...

1. transfer particles from coarse to fine grid

2. assign “coarse” particles to coarse grid

3. assign “fine” particles to refinement grid

4. temporarily store “borderline” density

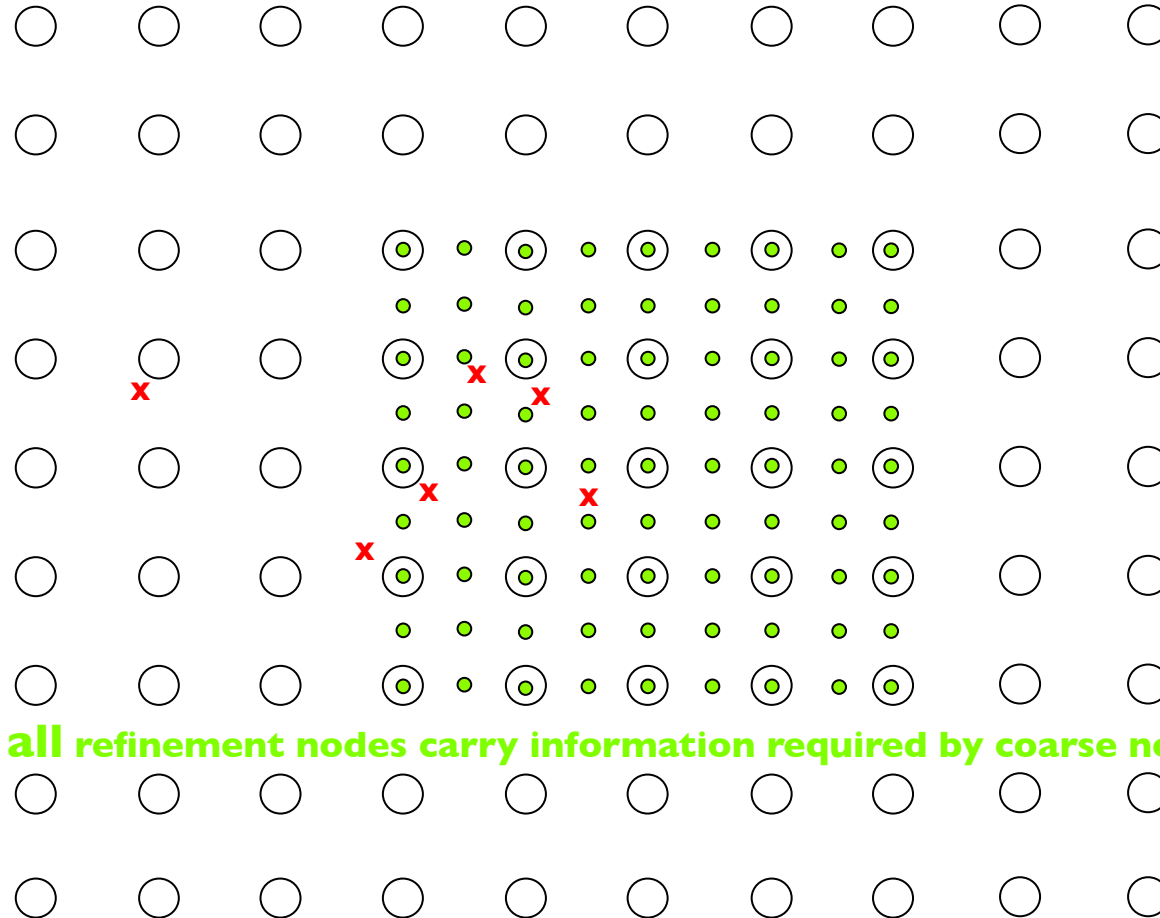
- 5. inject refinement density to coarse grid**

6. add “borderline” density to refinement

Solving for Gravity

- density assignment (co-spatial scheme)

density on coarse grid



all refinement nodes carry information required by coarse nodes...

## Solving for Gravity

- **density assignment** (co-spatial scheme)

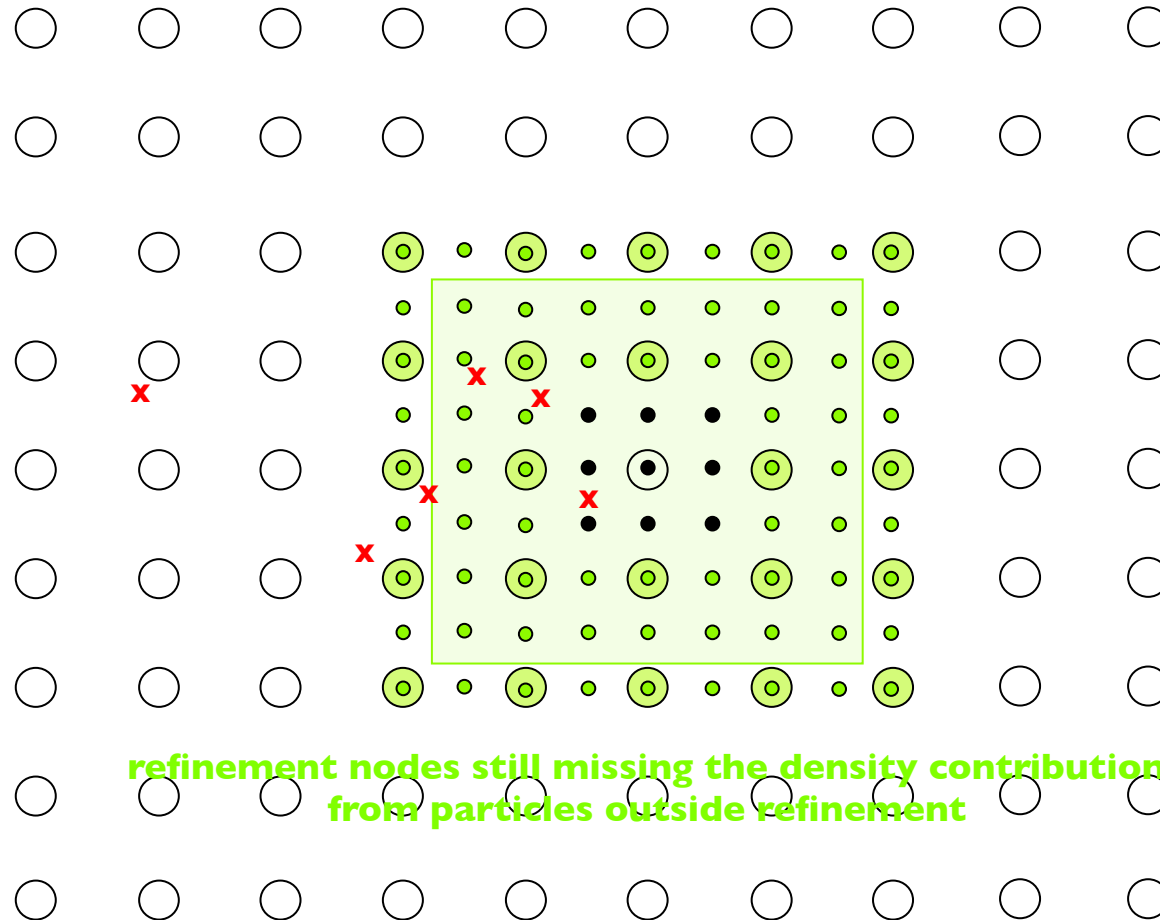
- steps required to get density correct on both coarse and fine grid...

1. transfer particles from coarse to fine grid
2. assign “coarse” particles to coarse grid
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5. inject refinement density to coarse grid
- 6. add “borderline” density to refinement**

Solving for Gravity

- density assignment (co-spatial scheme)

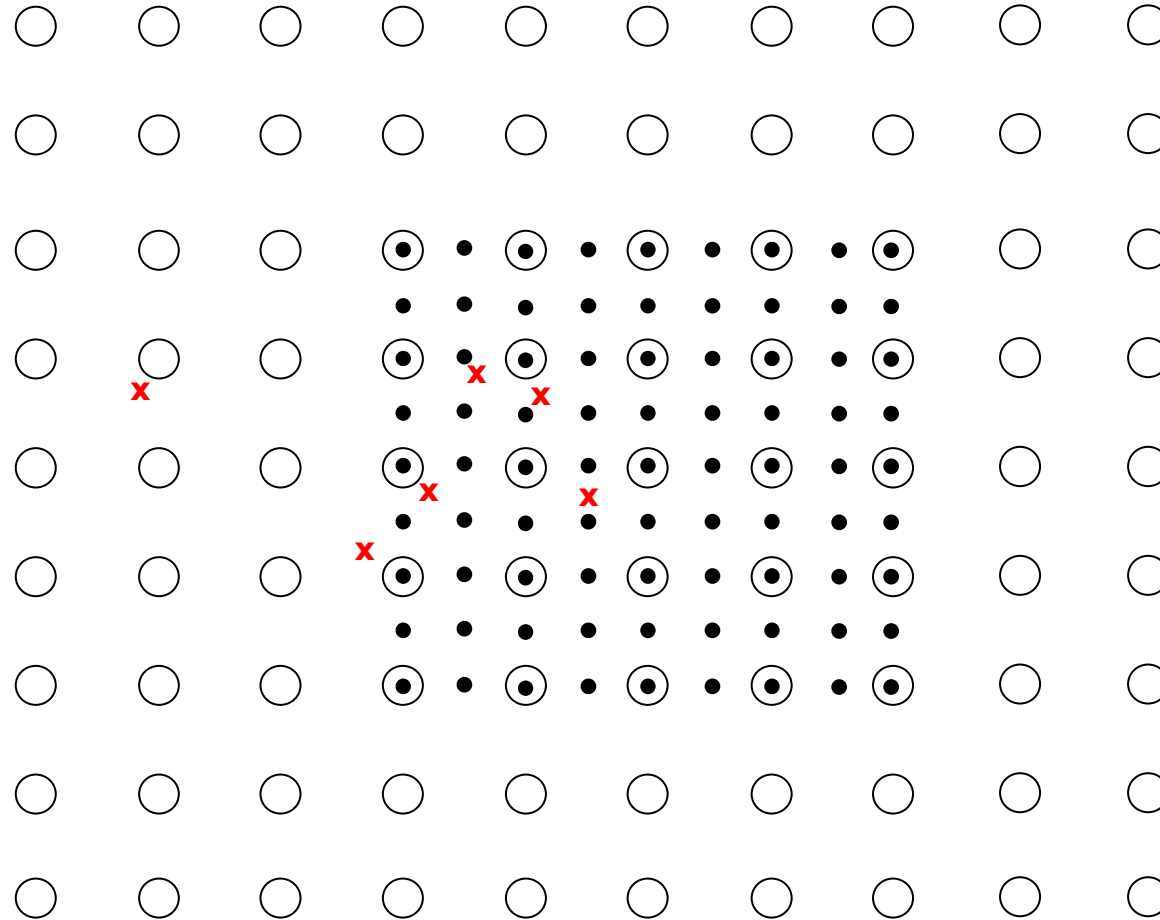
density on refinement grid



Solving for Gravity

- density assignment (co-spatial scheme)

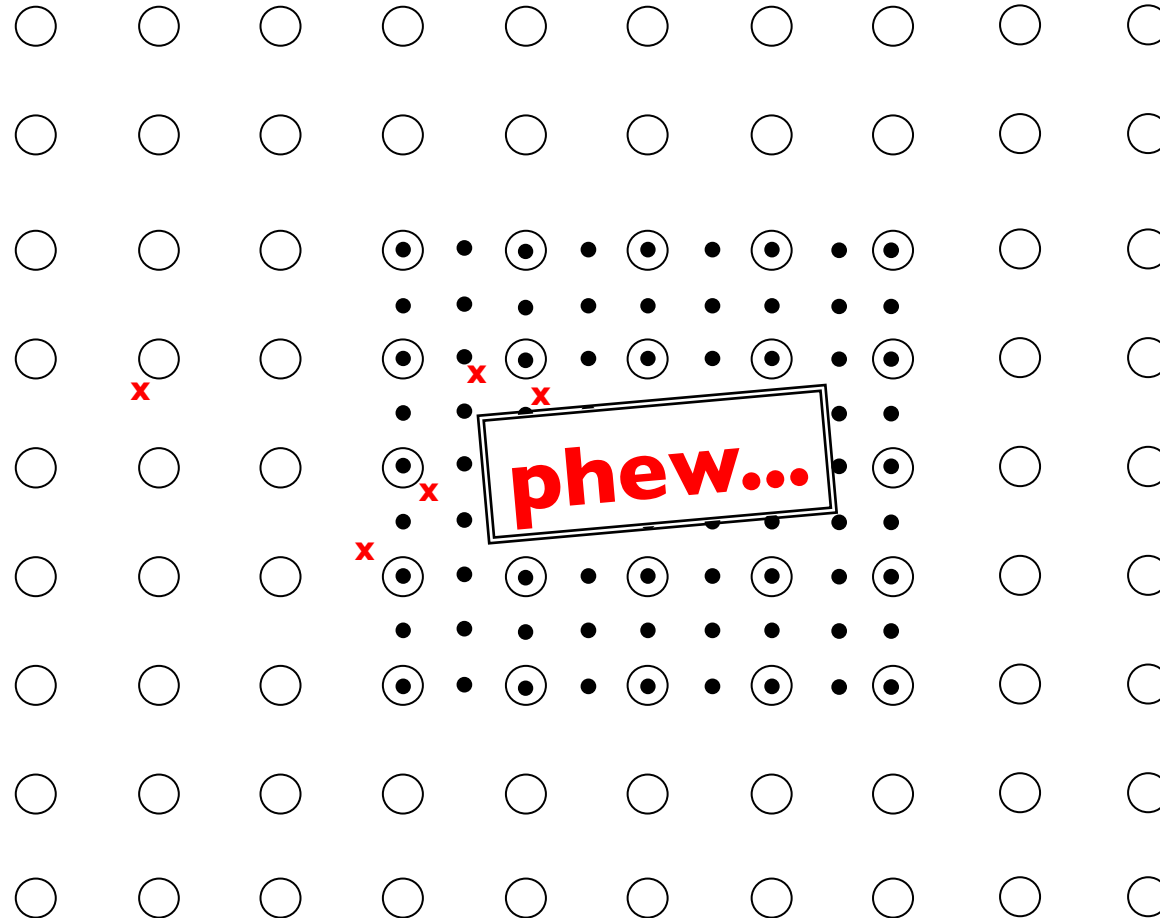
density finally correct on both levels...



Solving for Gravity

- density assignment (co-spatial scheme)

density finally correct on both levels...



## Solving for Gravity

---

- mesh refinements
- adaptive mesh refinement
- **adaptive mesh refinement for  $N$ -body codes**
  - gravity
  - generating refinements
  - density assignment
  - ***solving Poisson's equation***
- handling irregular grids
- adaptive leap-frog integration

Solving for Gravity

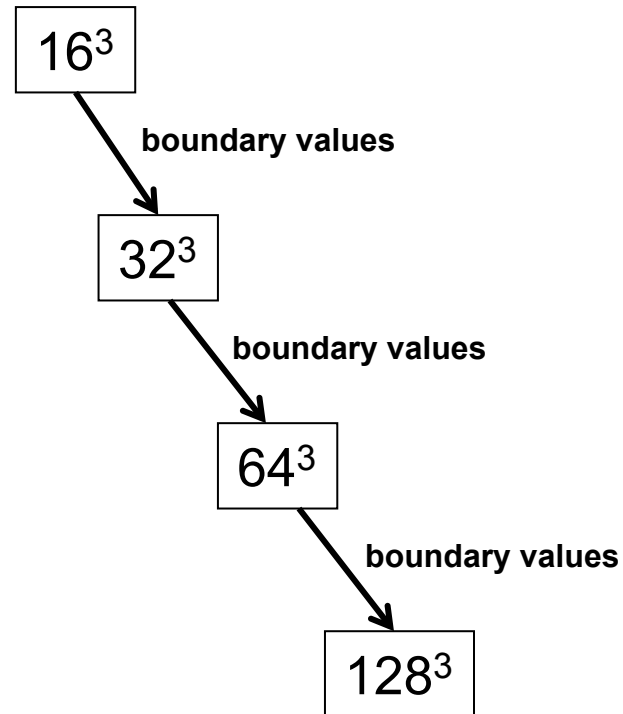
- solving Poisson's equation

1. the domain grid:

- relaxation, FFT, ...

2. the refinement grids:

- brute force relaxation!





## Solving for Gravity

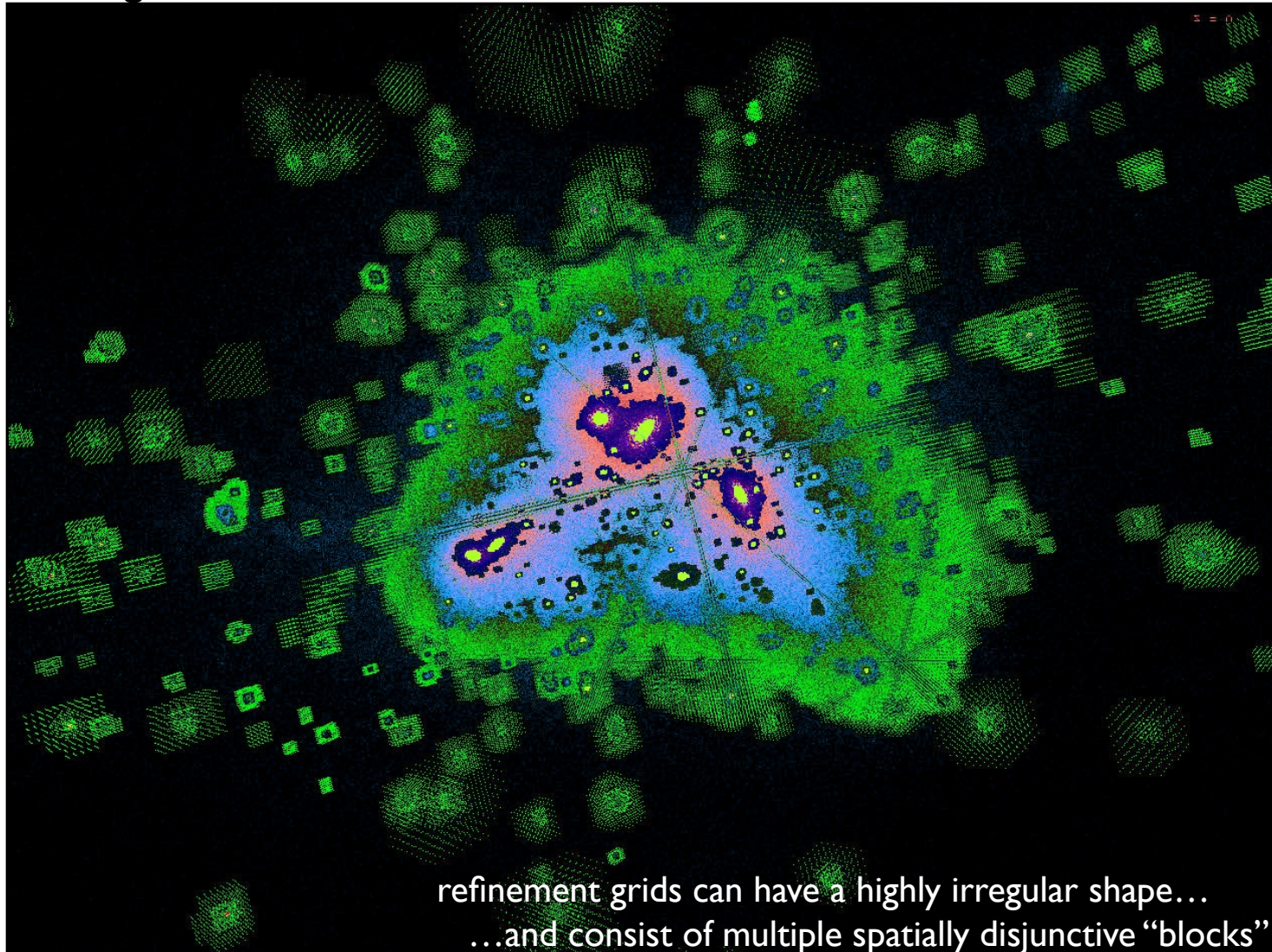
- adaptive mesh refinement
  - cover simulation with regular domain grid
  - create AMR hierarchy:
    - generate fine grid by comparing each node against some refinement criterion...
      - recursive procedure!
  - assign density on all grids
  - solve Poisson's equation on regular domain grid (FFT is fastest...)
  - loop over all refinement levels:
    - interpolate potential down from parent level
    - relax potential until converged (keeping boundary values fixed)
      - this will give the correct potential on all (refinement) grids

## Solving for Gravity

- mesh refinements
- adaptive mesh refinement
- adaptive mesh refinement for  $N$ -body codes
- **handling irregular grids**
- adaptive leap-frog integration

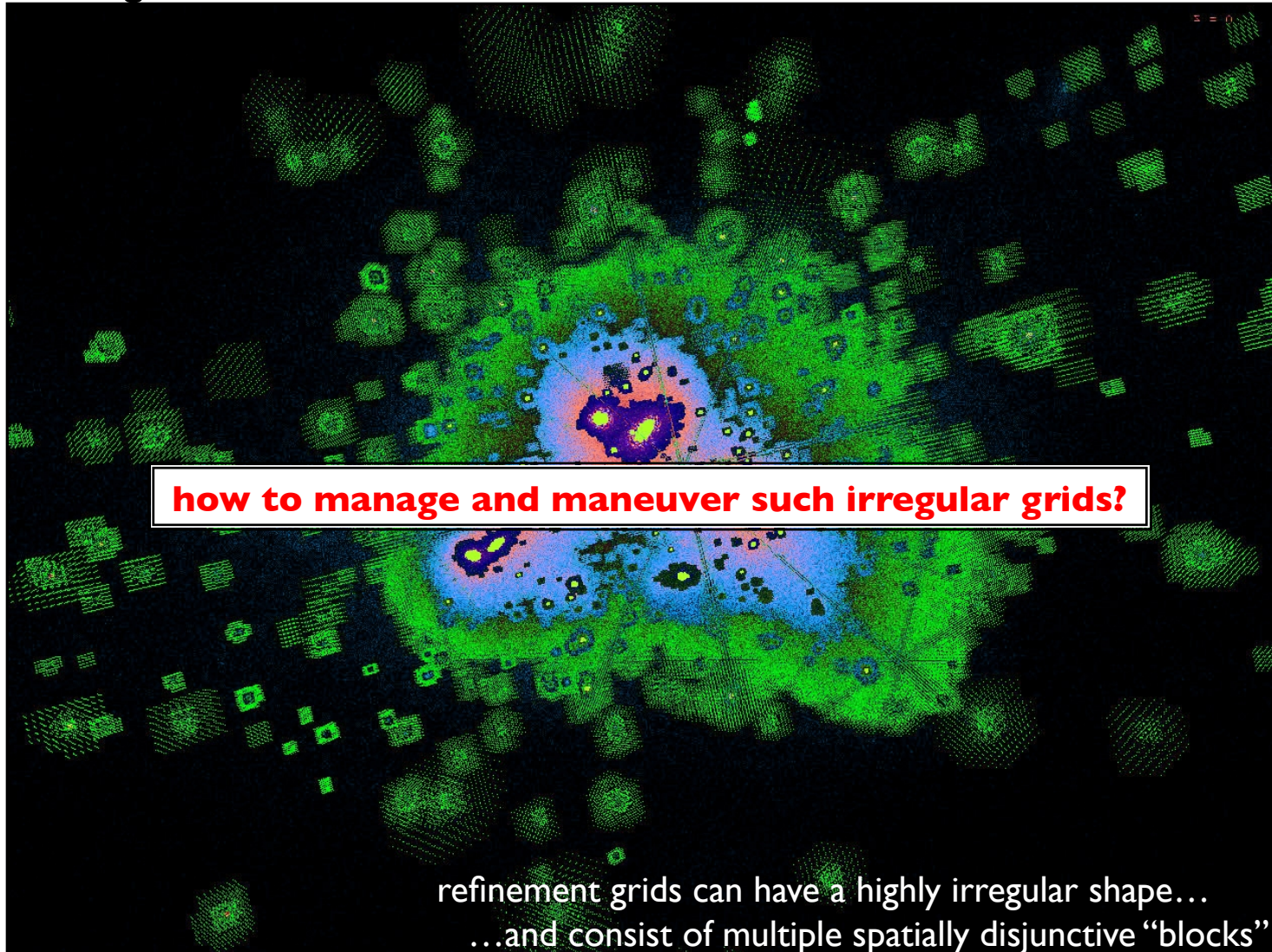
### Solving for Gravity

- handling refinements



### Solving for Gravity

- handling refinements



### Solving for Gravity

- handling regular grids (1D)



N = 16

```
struct {  
    float rho;  
    ...  
} node;
```

```
node[0].rho,    x=3  
node[1].rho,    x=6  
...  
node[N-1].rho,  x=48
```

### Solving for Gravity

- handling regular grids (1D)



N = 16

```
struct {  
    float rho;  
    ...  
} node;
```

```
node[0].rho, x=3  
node[1].rho, x=6  
...  
node[N-1].rho, x=48
```

**unique mapping between array index  $i$  and spatial position  $x$  possible**

### Solving for Gravity

- handling irregular grids (ID)



N = 9

```
struct {  
    float rho;  
    ...  
} node;
```

### Solving for Gravity

- handling irregular grids (ID)



N = 9

node[0].x = 12  
node[1].x = 15  
node[2].x = 18  
node[3].x = 21  
node[4].x = 24  
node[5].x = 27

node[6].x = 36  
node[7].x = 39  
node[8].x = 42

```
struct {  
    long x;  
    float rho;  
    ...  
} node;
```



### Solving for Gravity

- handling irregular grids (ID)



N = 9

node[0].x = 12  
node[1].x = 15  
node[2].x = 18  
node[3].x = 21  
node[4].x = 24  
node[5].x = 27

node[6].x = 36  
node[7].x = 39  
node[8].x = 42

```
struct {  
    long x;  
    float rho;  
    ...  
} node;
```

**NO unique mapping between array index  $i$  and spatial position  $x$  possible**

### Solving for Gravity

- handling irregular grids (ID)



N = 9

node[0].x = 12  
node[1].x = 15  
node[2].x = 18  
node[3].x = 21  
node[4].x = 24  
node[5].x = 27

node[6].x = 36  
node[7].x = 39  
node[8].x = 42

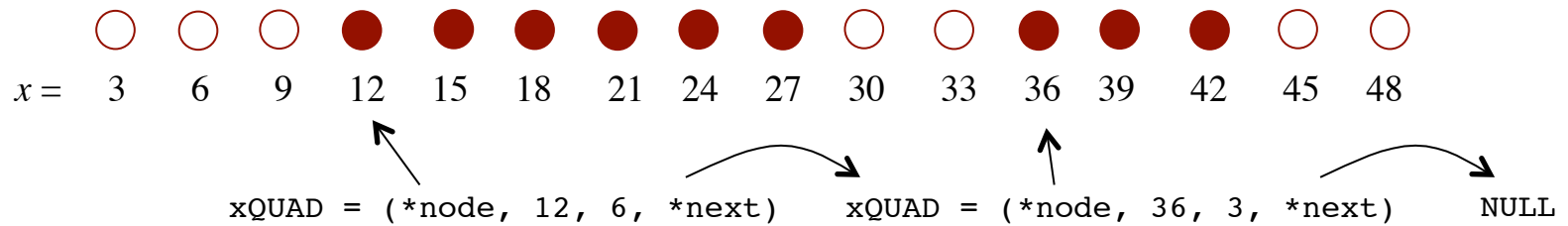
```
struct {  
  long x;  
  float rho;  
  ...  
} node;
```

**no** generate a meta-structure storing the geometry of the grid **x possible**

### Solving for Gravity

- handling irregular grids (ID)

*quad's*

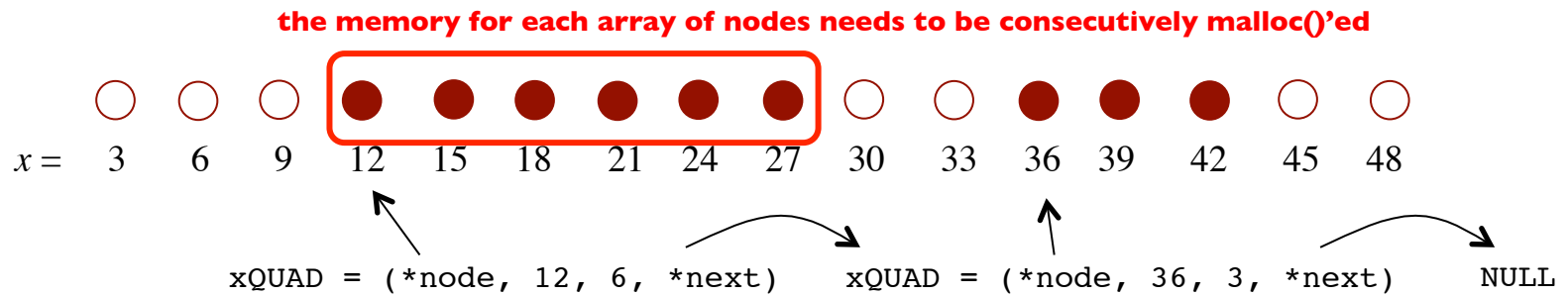


```
struct {  
    float rho;  
    ...  
} node;
```

### Solving for Gravity

- handling irregular grids (ID)

*quad's*



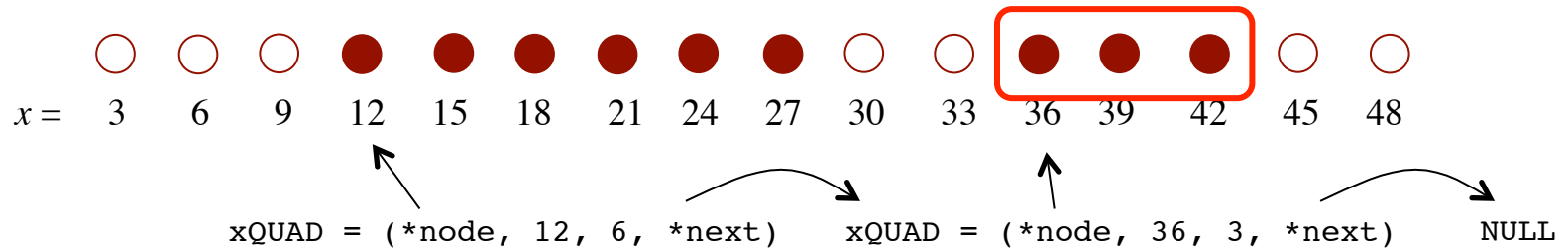
```
struct {  
    float rho;  
    ...  
} node;
```

Solving for Gravity

- handling irregular grids (ID)

*quad's*

the memory for each array of nodes needs to be consecutively malloc()'ed



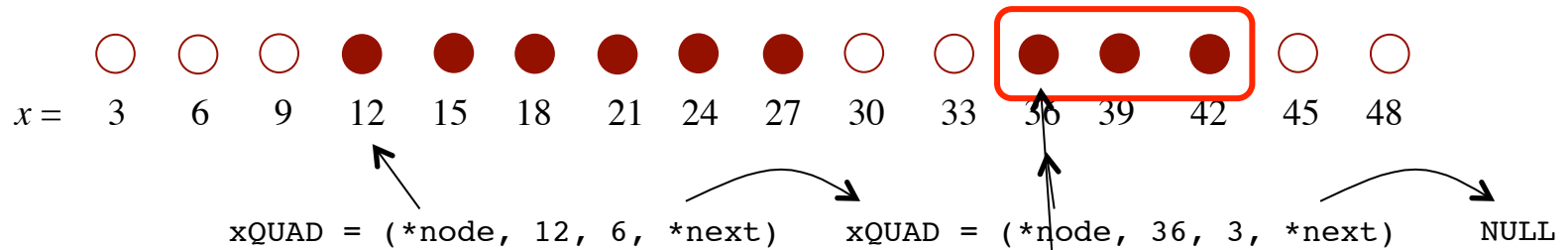
```
struct {  
    float rho;  
    ...  
} node;
```

Solving for Gravity

- handling irregular grids (ID)

*quad's*

the memory for each array of nodes needs to be consecutively malloc()'ed



this node is addressed via (xQUAD.node)+0

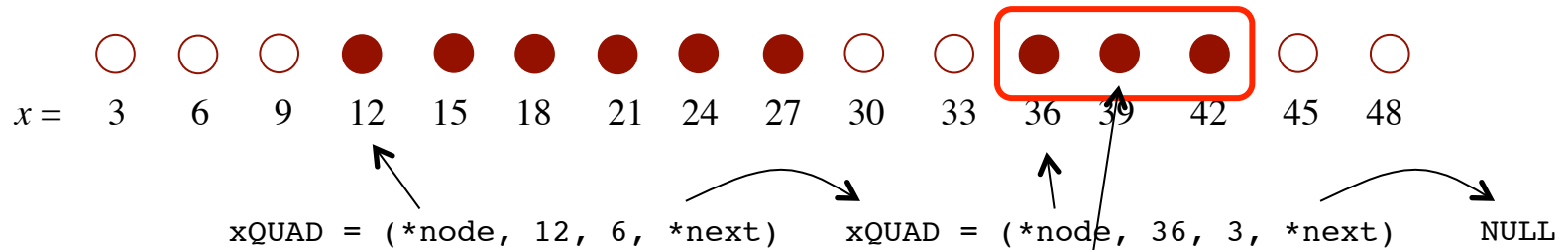
```
struct {  
    float rho;  
    ...  
} node;
```

Solving for Gravity

- handling irregular grids (ID)

*quad's*

the memory for each array of nodes needs to be consecutively malloc()'ed



```
struct {  
    float rho;  
    ...  
} node;
```

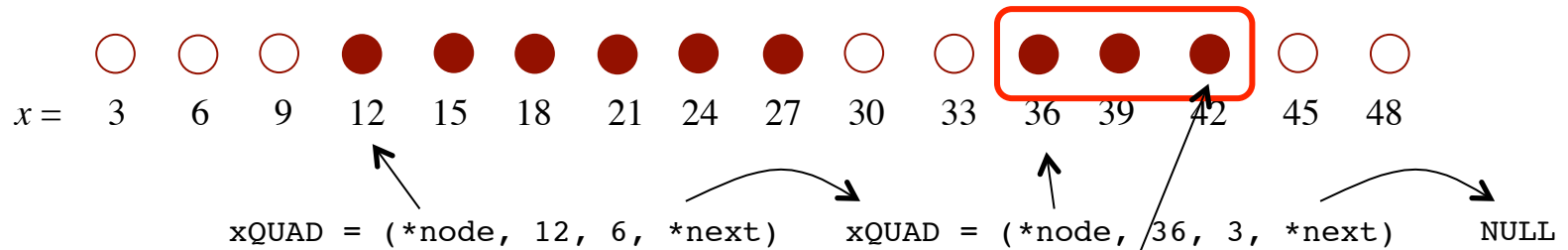
this node is addressed via (xQUAD.node)+1

Solving for Gravity

- handling irregular grids (ID)

*quad's*

the memory for each array of nodes needs to be consecutively malloc()'ed



```
struct {  
    float rho;  
    ...  
} node;
```

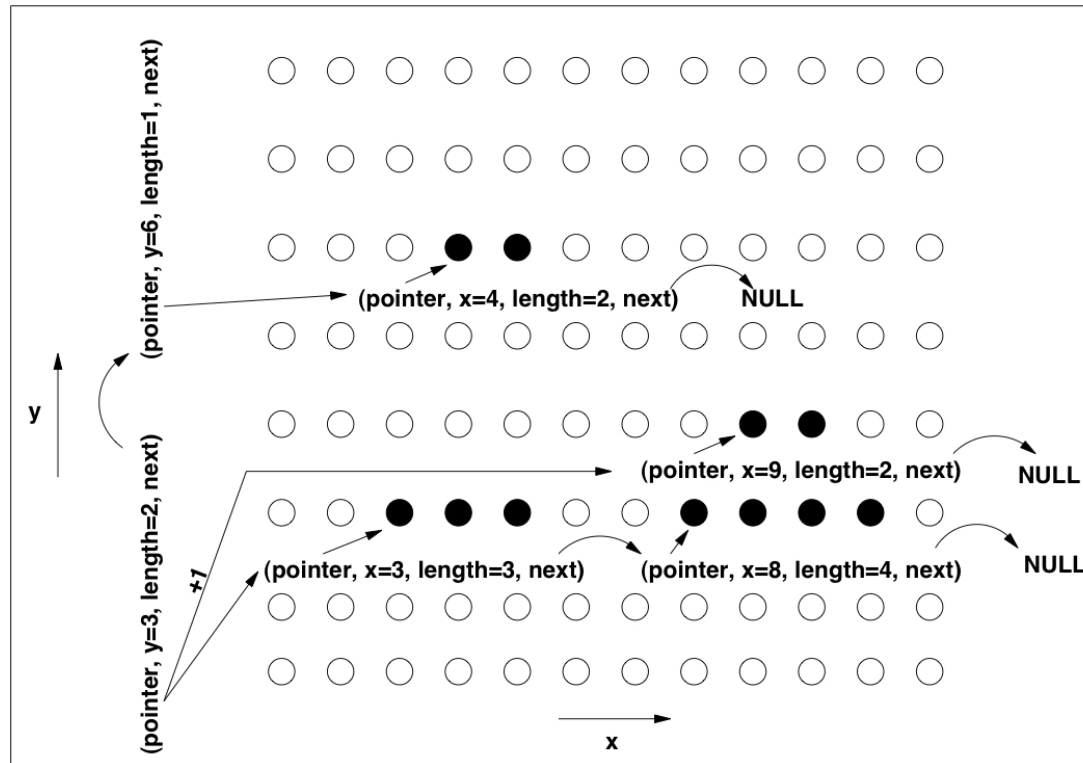
this node is addressed via  $(xQUAD.node)+2$



### Solving for Gravity

- handling irregular grids (2D)

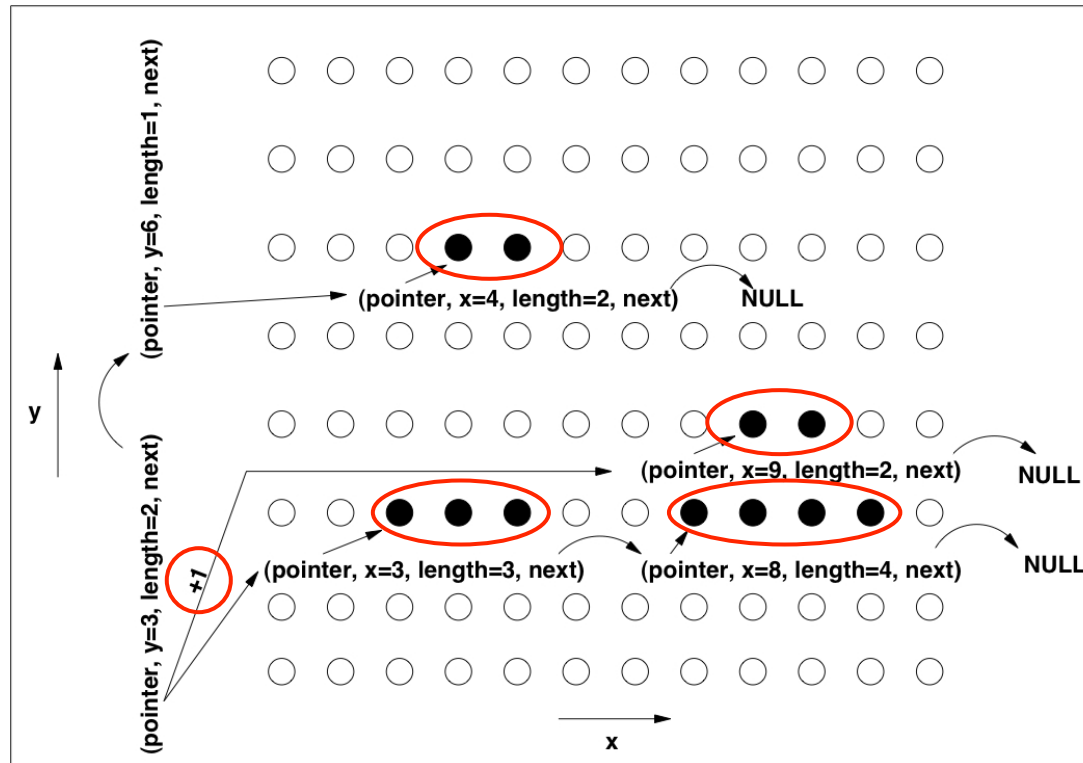
*quad's*



Solving for Gravity

- handling irregular grids (2D)

*quad's*

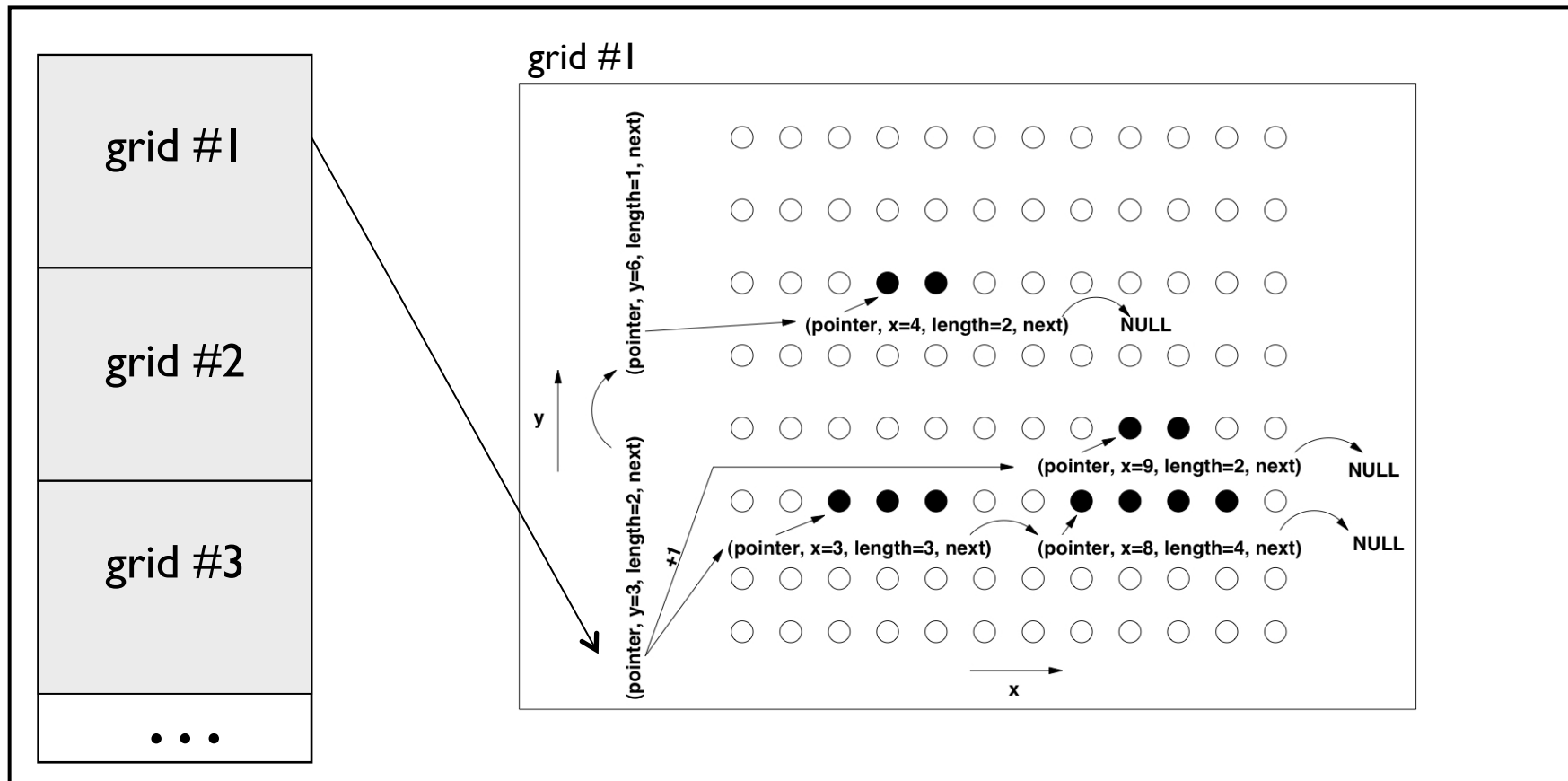


**the memory for each quad array  
needs to be malloc()'ed consecutively!**

Solving for Gravity

- handling irregular grids (2D)
  - store “grid structures” as a consecutive memory block
  - each “grid” points to the first yQUAD which in turns gives access to all nodes

*quad's*

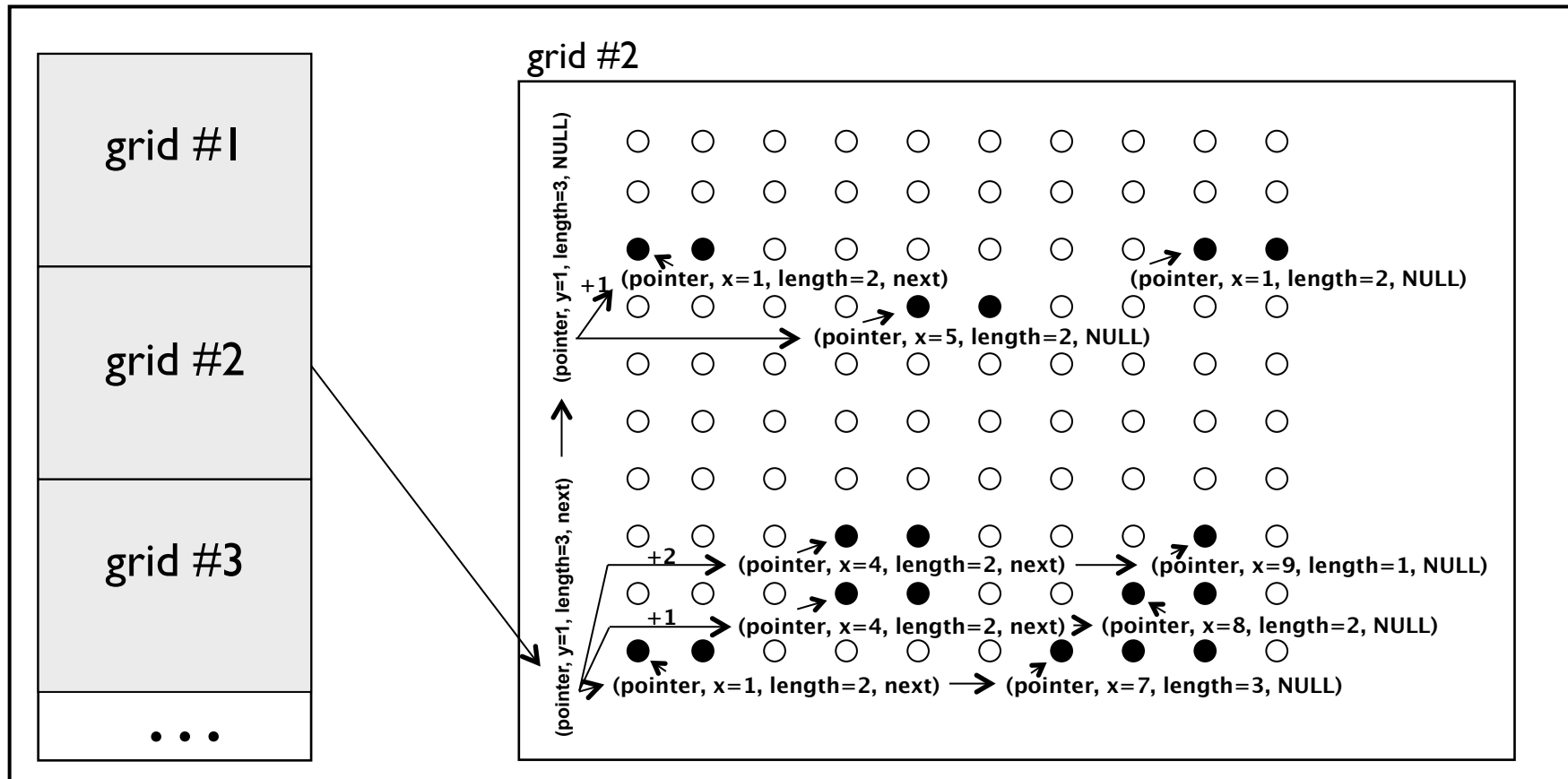


Solving for Gravity

- handling irregular grids (2D)

*quad's*

- store “grid structures” as a consecutive memory block
- each “grid” points to the first yQUAD which in turns gives access to all nodes



Solving for Gravity

- handling irregular grids (3D)

***quad's***

too complicated to sketch...

## Solving for Gravity

- handling irregular grids (3D)

*quad's*

- C-code example of how to loop over all nodes attached to a “grid”

```

for (zquad=grid.first_zquad; zquad != NULL; zquad=zquad->next) {
    for (yquad=zquad->first_yquad; yquad < yquad->pointer+yquad->length; yquad++)

        for (iyquad=yquad; iyquad != NULL; iyquad=iyquad->next) {
            for (xquad=yquad->first_xquad; xquad < xquad->pointer+xquad->length; xquad++)

                for (ixquad=xquad; ixquad != NULL; ixquad=ixquad->next) {
                    for (node=ixquad->pointer; node < ixquad->x+ixquad->length; node++) {

                        /* the node is at your disposal */
                        density      = node->density;
                        potential    = node->potential;
                        forceX      = node->force[X];

                        for(part=node->first_particle; part != NULL; part=part->next)
                            /* use particle structure to access particle position, velocity, etc. */ }}}

```

loc = location of first quad

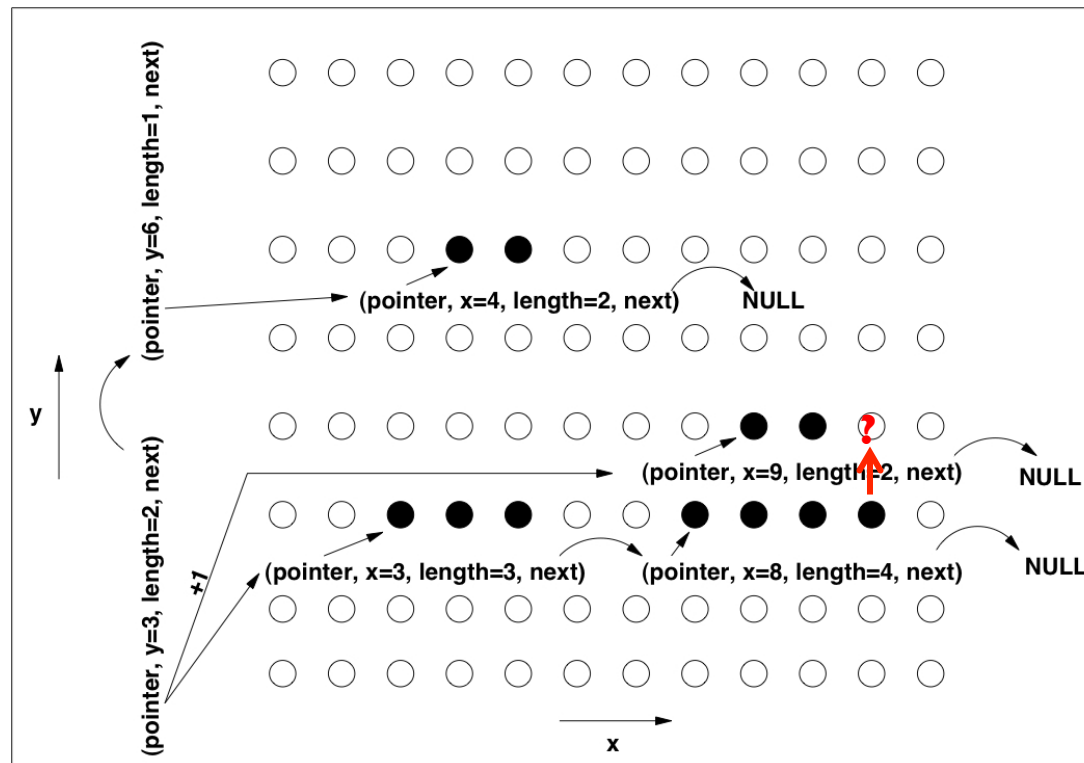
Solving for Gravity

- handling irregular grids

*quad's*

- drawback:

no direct access to neighbouring nodes...



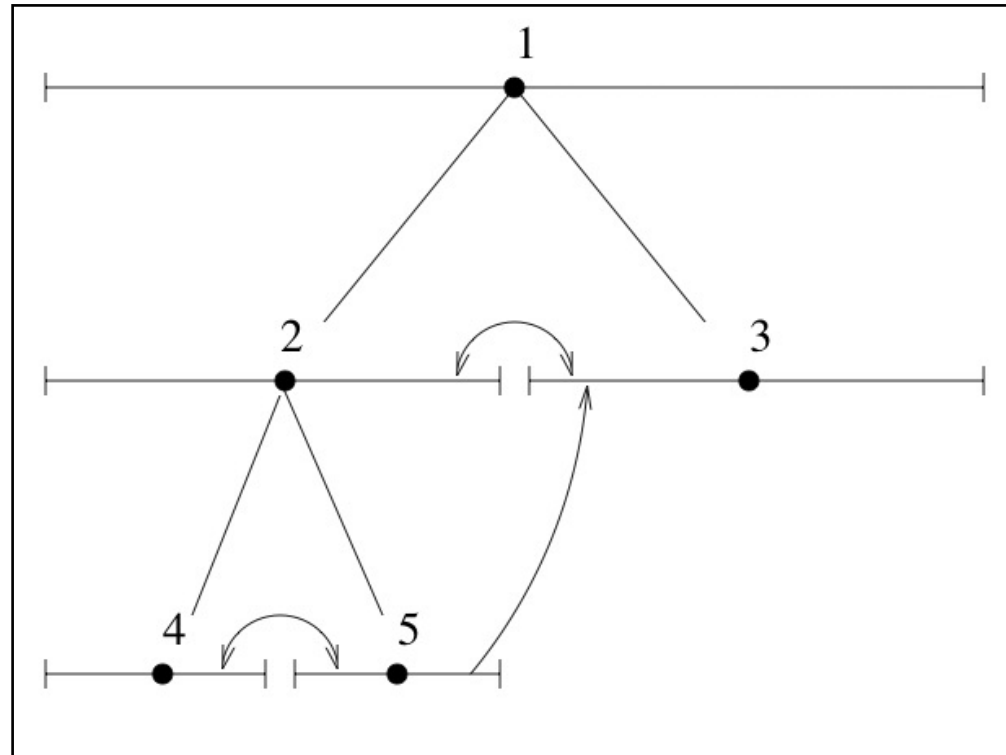
Solving for Gravity

- handling irregular grids

**FTT**

- other schemes possible:

```
struct {  
    NODE *daughter;  
    float rho;  
    ...  
} node;
```



Fully-Threaded-Tree (FTT) by Khokhlov, 1998, J. Comp. Phy. 143, 519

(used with Andrey Kravtsov's ART code...)



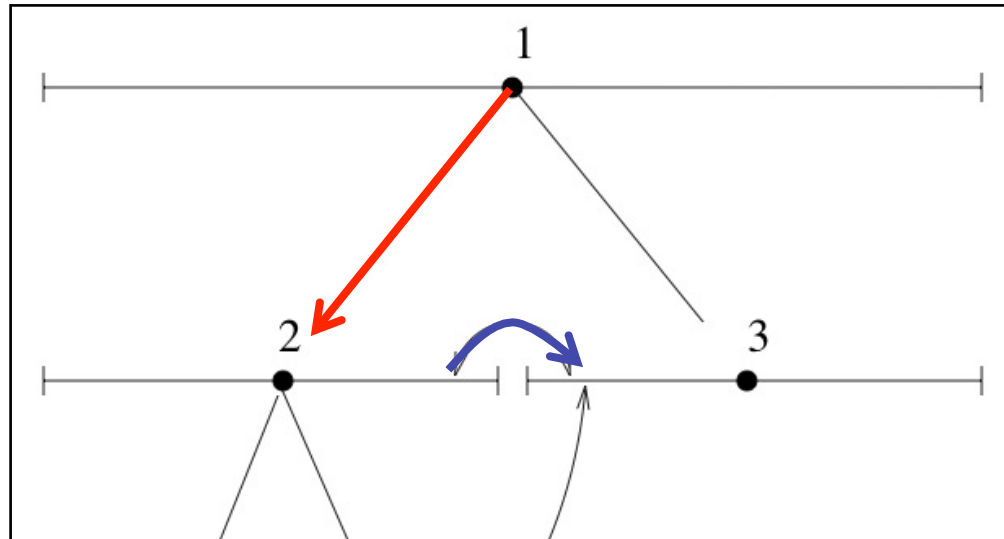
Solving for Gravity

- handling irregular grids

**FTT**

- other schemes possible:

```
struct {  
    NODE *daughter;  
    float rho;  
    ...  
} node;
```



- each cell stores pointers to 1<sup>st</sup> daughter
- daughters are malloc()'ed consecutively

Fully-Threaded-Tree (FTT) by Khokhlov, 1998, J. Comp. Phy. 143, 519

(used with Andrey Kravtsov's ART code...)

## Solving for Gravity

- mesh refinements
- adaptive mesh refinement
- adaptive mesh refinement for  $N$ -body codes
- handling irregular grids
- **adaptive leap-frog integration**

### Solving for Gravity

- full set of equations

- collisionless matter (e.g. dark matter)

$$\frac{d\vec{x}_{DM}}{dt} = \vec{v}_{DM}$$

$$\frac{d\vec{v}_{DM}}{dt} = -\nabla\phi$$

**leap-frog integration**

**AMR solver**

- Poisson's equation

$$\Delta\phi = 4\pi G\rho_{tot}$$

- collisional matter (e.g. gas)

$$\frac{\partial\rho}{\partial t} + \nabla\cdot(\rho\vec{v}) = 0$$

$$\frac{\partial(\rho\vec{v})}{\partial t} + \nabla\cdot\left(\rho\vec{v}\otimes\vec{v} + \left(p + \frac{1}{2\mu}B^2\right)\vec{1} - \frac{1}{\mu}\vec{B}\otimes\vec{B}\right) = \rho(-\nabla\phi)$$

$$\frac{\partial(\rho E)}{\partial t} + \nabla\cdot\left(\left[\rho E + p + \frac{1}{2\mu}B^2\right]\vec{v} - \frac{1}{\mu}[\vec{v}\cdot\vec{B}]\vec{B}\right) = \rho\vec{v}\cdot(-\nabla\phi) + (\Gamma - L)$$

- ideal gas equations

$$p = (\gamma - 1)\rho\varepsilon$$

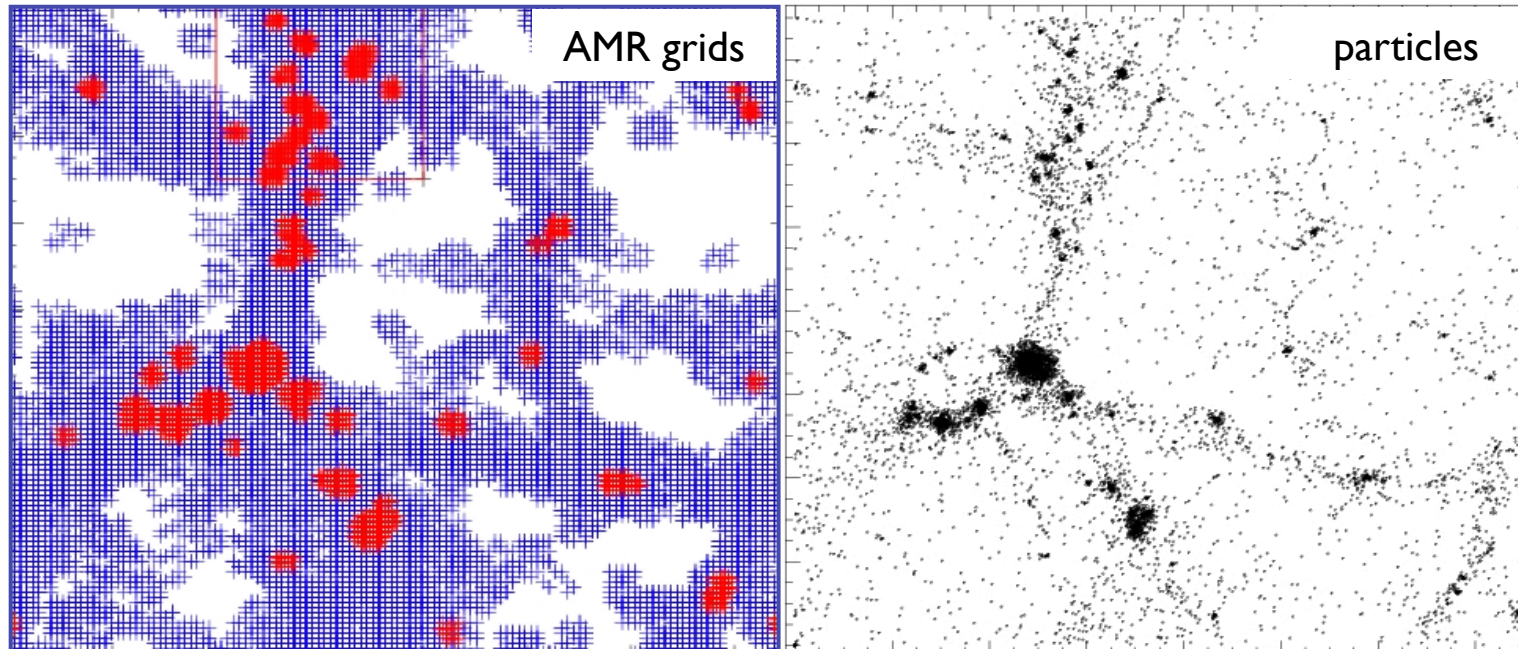
$$\rho\varepsilon = \rho E - \frac{1}{2}\rho v^2$$

- Maxwell's equation

$$\frac{\partial\vec{B}}{\partial t} = -\nabla\times(\vec{v}\times\vec{B})$$

### Solving for Gravity

- moving particles on the AMR hierarchy



$$\Delta\phi = 4\pi G\rho_{tot}$$

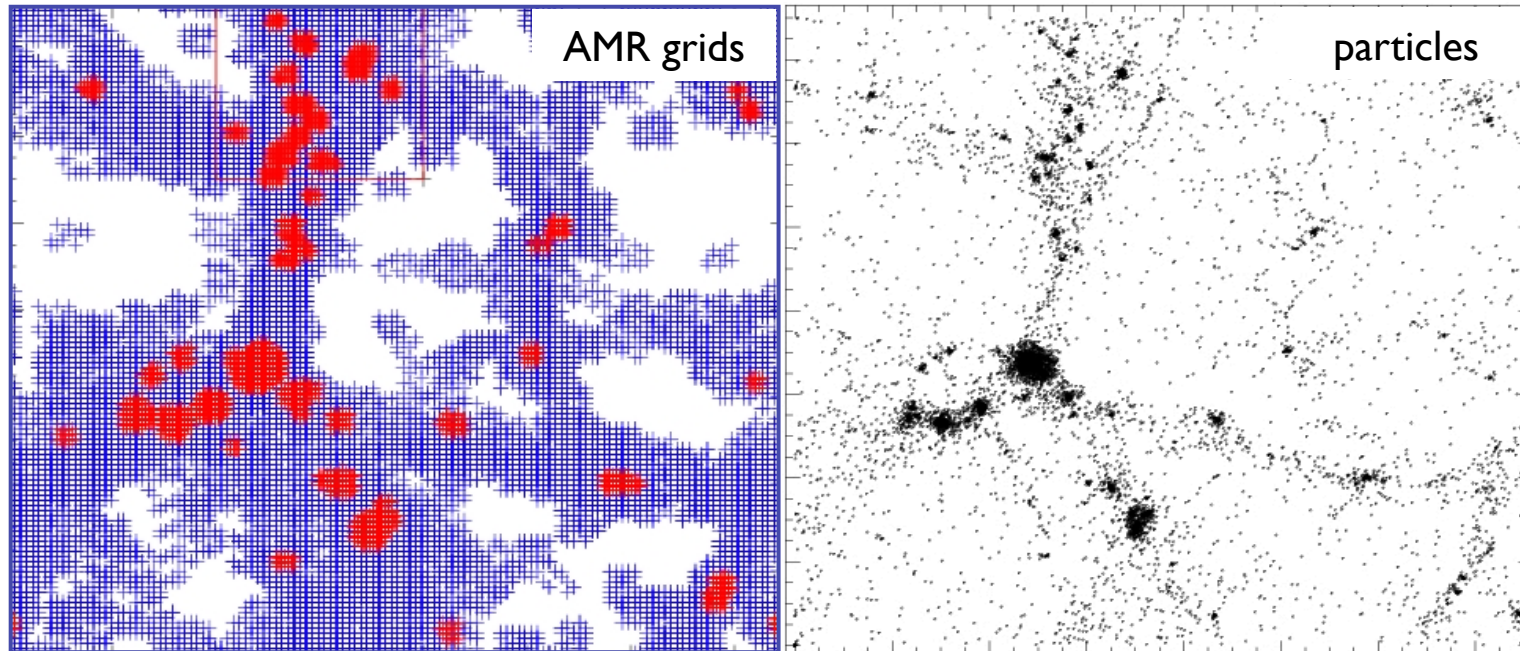
$$\frac{d\vec{x}_{DM}}{dt} = \vec{v}_{DM}$$

$$\frac{d\vec{v}_{DM}}{dt} = -\nabla\phi$$

Solving for Gravity

- moving particles on the AMR hierarchy

***move particles on fine grids with smaller time step  
to better resolve the dynamics, too!***



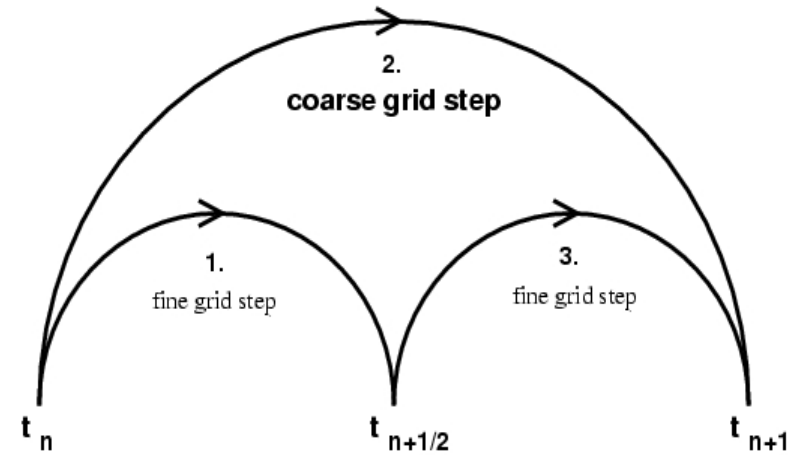
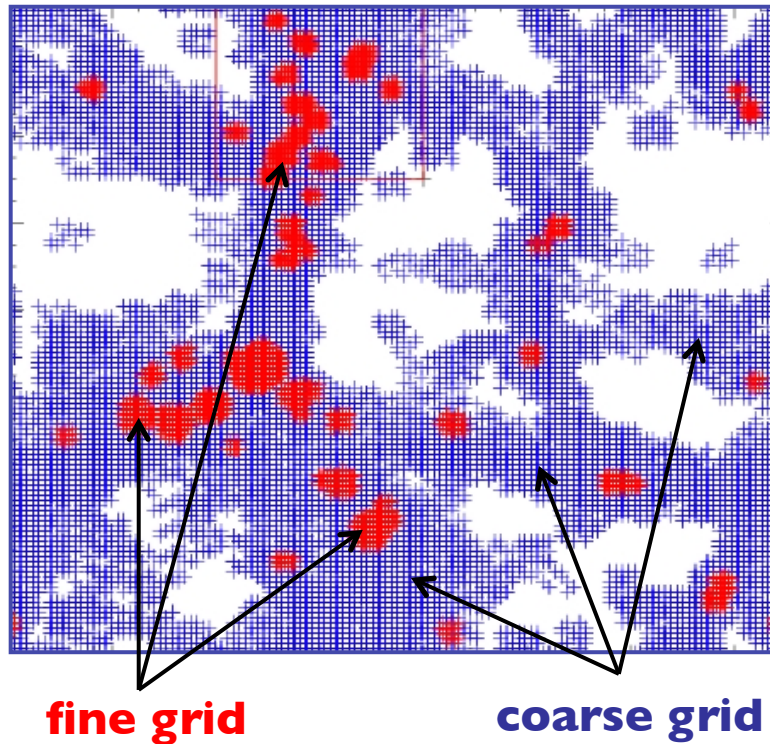
$$\Delta\phi = 4\pi G\rho_{tot}$$

$$\frac{d\vec{x}_{DM}}{dt} = \vec{v}_{DM}$$

$$\frac{d\vec{v}_{DM}}{dt} = -\nabla\phi$$

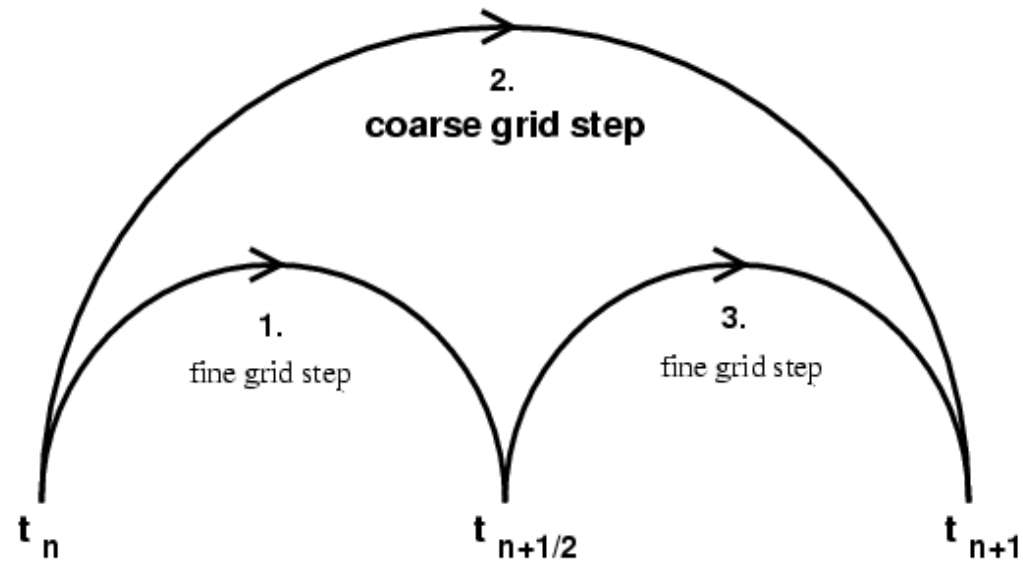
Solving for Gravity

- moving particles on the AMR hierarchy
  - fully recursive approach:



Solving for Gravity

- moving particles on the AMR hierarchy
  - fully recursive approach:



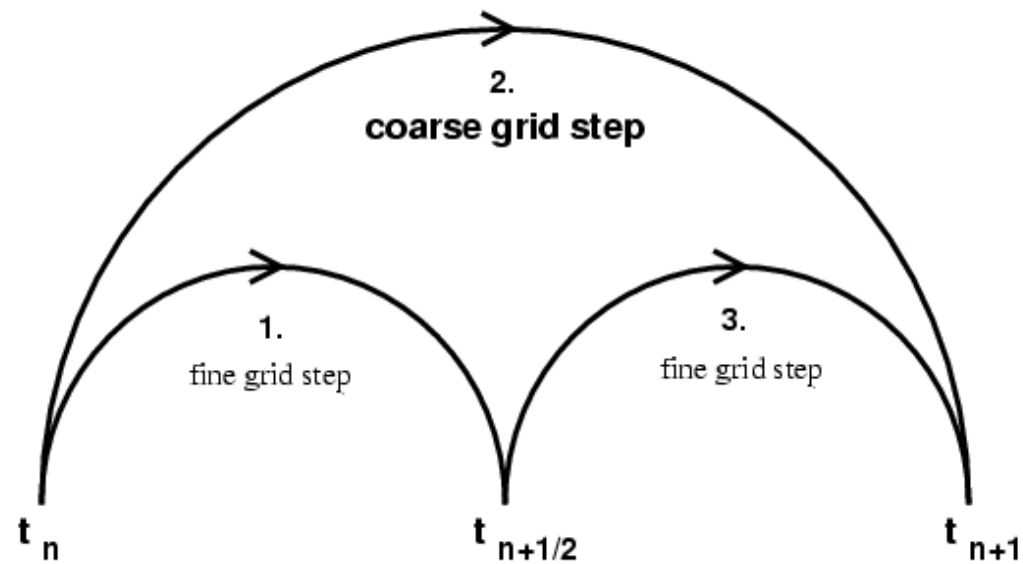
Drift-Kick-Drift variant of the leap-frog integrator:

**time synchronisation between different grid levels  
rather than “leap-frogging”!**

Solving for Gravity

- moving particles on the AMR hierarchy

- fully recursive approach:



I. fine grid step:

$$\text{Drift : } \vec{x}^{n+1/4} = \vec{x}^n + \vec{p}^n \int_{t_n}^{t_n+\Delta t/4} dt$$

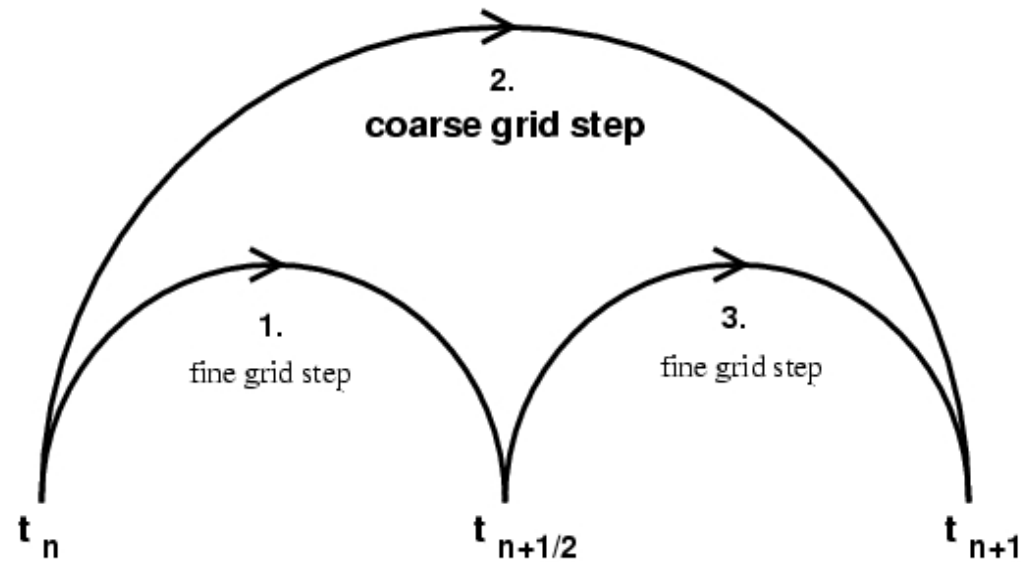
$$\leftarrow \text{Kick : } \vec{p}^{n+1/2} = \vec{p}^n - \vec{\nabla}\Phi^{n+1/4} \int_{t_n}^{t_n+\Delta t/2} dt \rightarrow$$

$$\text{Drift : } \vec{x}^{n+1/2} = \vec{x}^{n+1/4} + \vec{p}^{n+1/2} \int_{t_n+\Delta t/4}^{t_n+\Delta t/2} dt$$



Solving for Gravity

- moving particles on the AMR hierarchy
  - fully recursive approach:



2. coarse grid step:

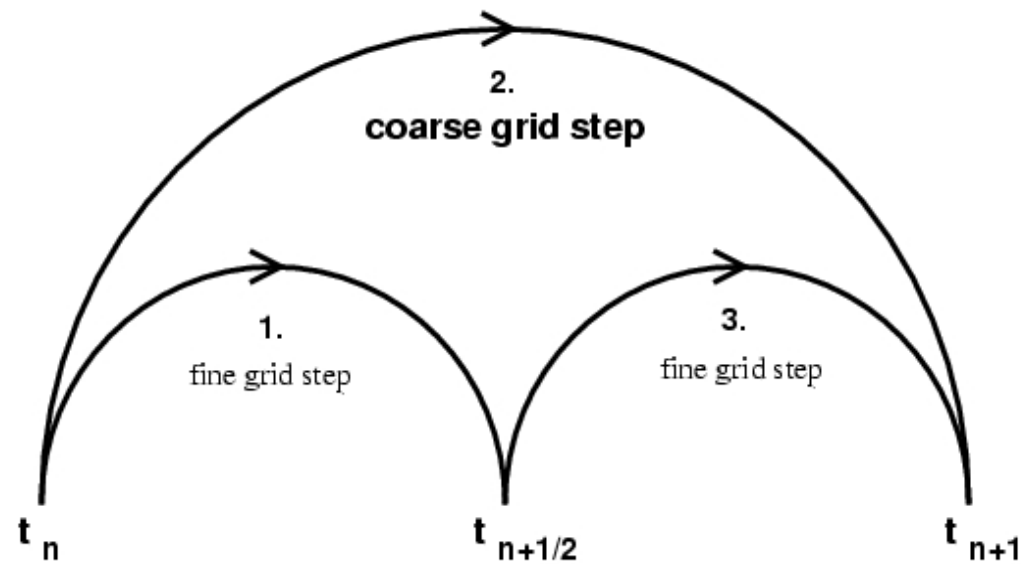
$$\text{Drift: } \vec{x}^{n+1/2} = \vec{x}^n + \vec{p}^n \int_{t_n}^{t_n + \Delta t / 2} dt$$

$$\leftarrow \text{Kick: } \vec{p}^{n+1} = \vec{p}^n - \vec{\nabla} \Phi^{n+1/2} \int_{t_n}^{t_n + \Delta t} dt \rightarrow$$

$$\text{Drift: } \vec{x}^{n+1} = \vec{x}^{n+1/2} + \vec{p}^{n+1} \int_{t_n + \Delta t / 2}^{t_n + \Delta t} dt$$

Solving for Gravity

- moving particles on the AMR hierarchy
  - fully recursive approach:

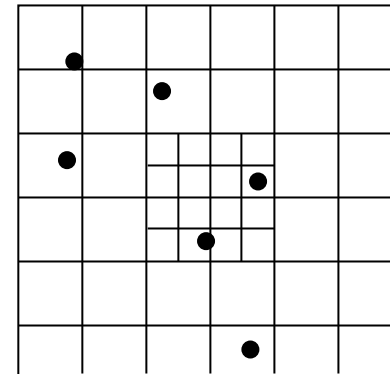


3. fine grid step:

$$\begin{aligned}
 \text{Drift: } \bar{x}^{n+3/4} &= \bar{x}^{n+1/2} + \bar{p}^n \int_{t_n+\Delta t/2}^{t_n+3\Delta t/4} dt \\
 \leftarrow \text{Kick: } \bar{p}^{n+1} &= \bar{p}^{n+1/2} - \bar{\nabla}\Phi^{n+3/4} \int_{t_n+\Delta t/2}^{t_n+\Delta t} dt \rightarrow \\
 \text{Drift: } \bar{x}^{n+1} &= \bar{x}^{n+3/4} + \bar{p}^{n+1} \int_{t_n+3\Delta t/4}^{t_n+\Delta t} dt
 \end{aligned}$$

Solving for Gravity

- moving particles on the AMR hierarchy



Solving for Gravity

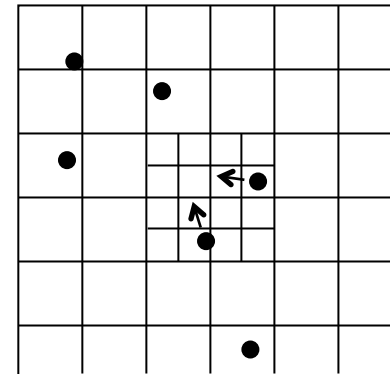
- moving particles on the AMR hierarchy

I. fine grid DKD step:

$$\text{Drift: } \vec{x}^{n+1/4} = \vec{x}^n + \vec{p}^n \frac{\Delta t}{4}$$

$$\text{Kick: } \vec{p}^{n+1/2} = \vec{p}^n - \vec{\nabla}\Phi^{n+1/4} \frac{\Delta t}{2}$$

$$\text{Drift: } \vec{x}^{n+1/2} = \vec{x}^{n+1/4} + \vec{p}^{n+1/2} \frac{\Delta t}{4}$$



Solving for Gravity

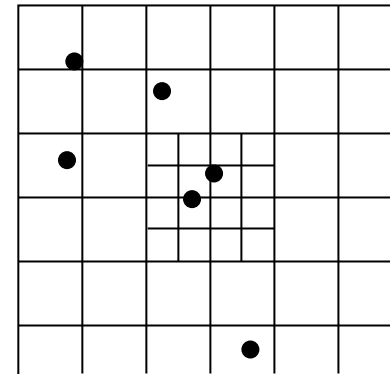
- moving particles on the AMR hierarchy

I. fine grid DKD step:

$$\text{Drift: } \vec{x}^{n+1/4} = \vec{x}^n + \vec{p}^n \frac{\Delta t}{4}$$

$$\text{Kick: } \vec{p}^{n+1/2} = \vec{p}^n - \vec{\nabla}\Phi^{n+1/4} \frac{\Delta t}{2}$$

$$\text{Drift: } \vec{x}^{n+1/2} = \vec{x}^{n+1/4} + \vec{p}^{n+1/2} \frac{\Delta t}{4}$$



Solving for Gravity

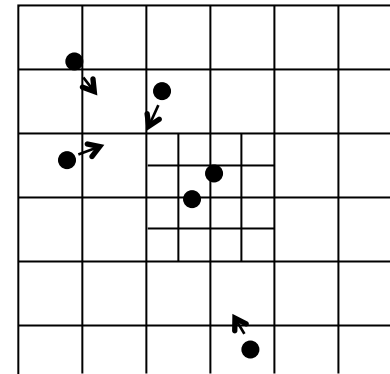
- moving particles on the AMR hierarchy

2. coarse grid DKD step:

$$\text{Drift: } \vec{x}^{n+1/2} = \vec{x}^n + \vec{p}^n \frac{\Delta t}{2}$$

$$\text{Kick: } \vec{p}^{n+1} = \vec{p}^n - \vec{\nabla}\Phi^{n+1/2} \Delta t$$

$$\text{Drift: } \vec{x}^{n+1} = \vec{x}^{n+1/2} + \vec{p}^{n+1} \frac{\Delta t}{2}$$



Solving for Gravity

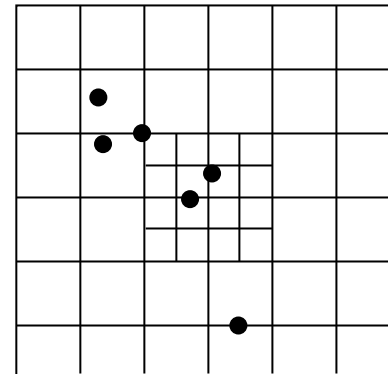
- moving particles on the AMR hierarchy

2. coarse grid DKD step:

$$\text{Drift: } \vec{x}^{n+1/2} = \vec{x}^n + \vec{p}^n \frac{\Delta t}{2}$$

$$\text{Kick: } \vec{p}^{n+1} = \vec{p}^n - \vec{\nabla}\Phi^{n+1/2} \Delta t$$

$$\text{Drift: } \vec{x}^{n+1} = \vec{x}^{n+1/2} + \vec{p}^{n+1} \frac{\Delta t}{2}$$



Solving for Gravity

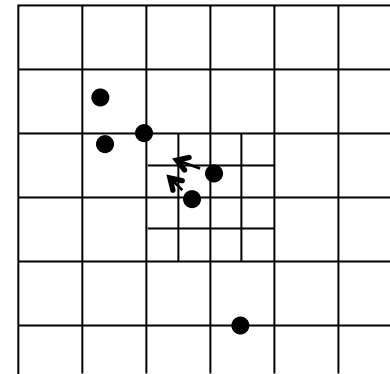
- moving particles on the AMR hierarchy

3. fine grid DKD step:

$$\text{Drift: } \vec{x}^{n+3/4} = \vec{x}^{n+1/2} + \vec{p}^n \frac{\Delta t}{4}$$

$$\text{Kick: } \vec{p}^{n+1} = \vec{p}^{n+1/2} - \vec{\nabla}\Phi^{n+3/4} \frac{\Delta t}{2}$$

$$\text{Drift: } \vec{x}^{n+1} = \vec{x}^{n+3/4} + \vec{p}^{n+1} \frac{\Delta t}{4}$$





Solving for Gravity

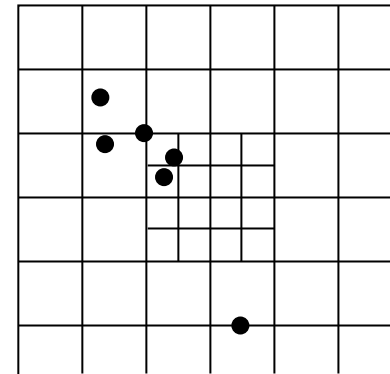
- moving particles on the AMR hierarchy

3. fine grid DKD step:

$$\text{Drift: } \vec{x}^{n+3/4} = \vec{x}^{n+1/2} + \vec{p}^n \frac{\Delta t}{4}$$

$$\text{Kick: } \vec{p}^{n+1} = \vec{p}^{n+1/2} - \vec{\nabla}\Phi^{n+3/4} \frac{\Delta t}{2}$$

$$\text{Drift: } \vec{x}^{n+1} = \vec{x}^{n+3/4} + \vec{p}^{n+1} \frac{\Delta t}{4}$$



Solving for Gravity

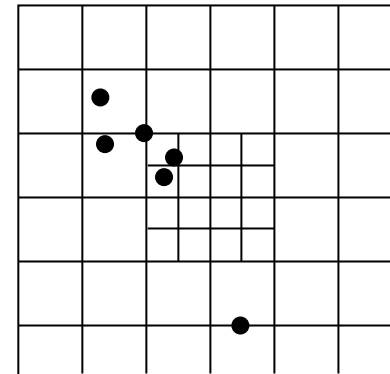
- moving particles on the AMR hierarchy

3. fine grid DKD step:

$$\text{Drift: } \vec{x}^{n+3/4} = \vec{x}^{n+1/2} + \vec{p}^n \frac{\Delta t}{4}$$

$$\text{Kick: } \vec{p}^{n+1} = \vec{p}^{n+1/2} - \vec{\nabla}\Phi^{n+3/4} \frac{\Delta t}{2}$$

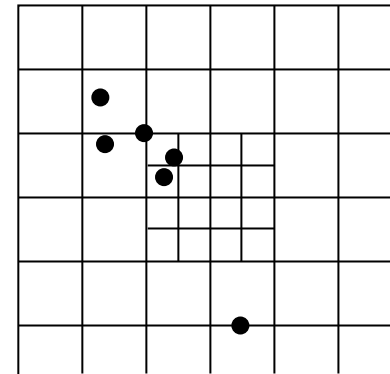
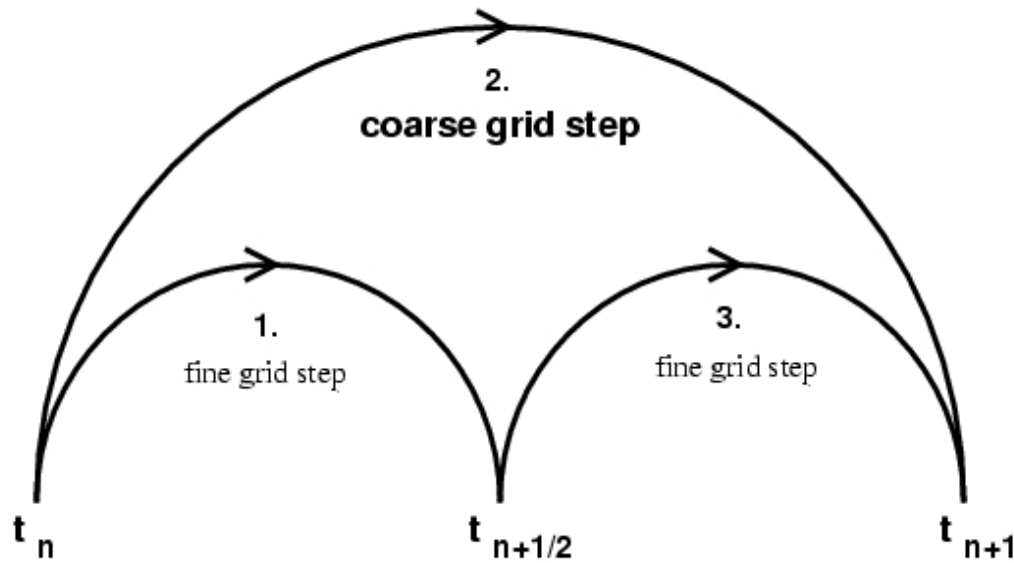
$$\text{Drift: } \vec{x}^{n+1} = \vec{x}^{n+3/4} + \vec{p}^{n+1} \frac{\Delta t}{4}$$



what about particles crossing grid boundaries?

### Solving for Gravity

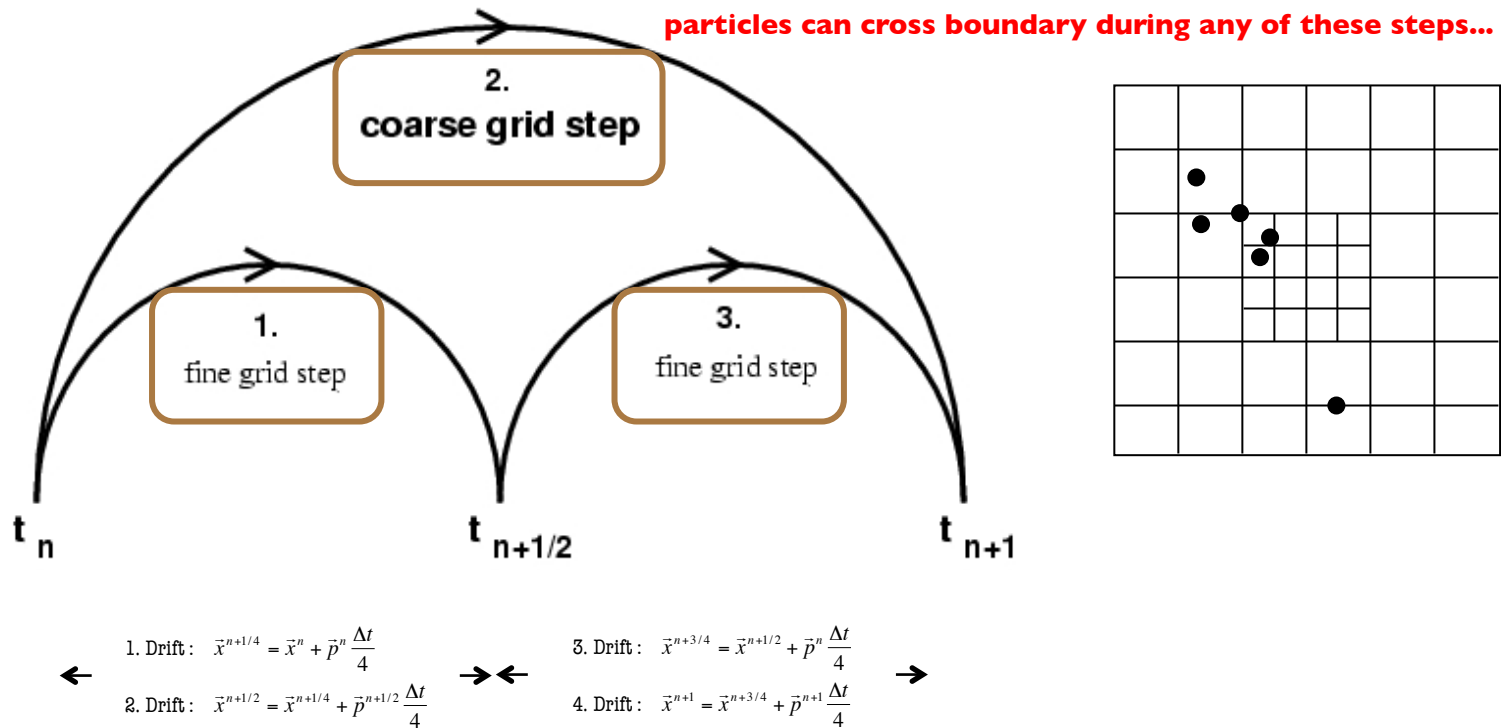
- moving particles on the AMR hierarchy
  - particles crossing grid boundaries



$$\begin{array}{l}
 \leftarrow 1. \text{ Drift: } \bar{x}^{n+1/4} = \bar{x}^n + \bar{p}^n \frac{\Delta t}{4} \\
 2. \text{ Drift: } \bar{x}^{n+1/2} = \bar{x}^{n+1/4} + \bar{p}^{n+1/2} \frac{\Delta t}{4} \\
 3. \text{ Drift: } \bar{x}^{n+3/4} = \bar{x}^{n+1/2} + \bar{p}^n \frac{\Delta t}{4} \\
 4. \text{ Drift: } \bar{x}^{n+1} = \bar{x}^{n+3/4} + \bar{p}^{n+1} \frac{\Delta t}{4} \rightarrow
 \end{array}$$

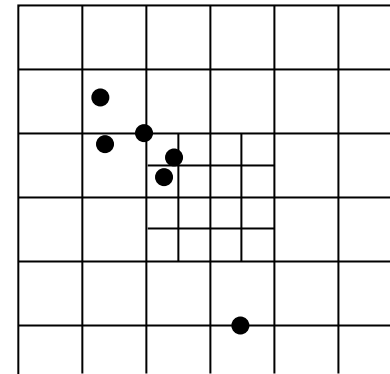
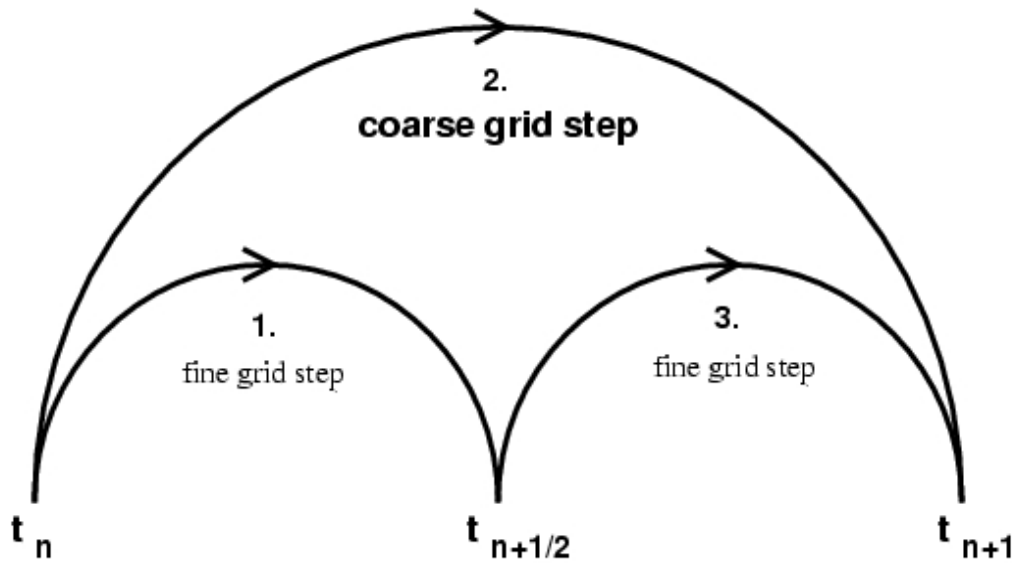
### Solving for Gravity

- moving particles on the AMR hierarchy
  - particles crossing grid boundaries



Solving for Gravity

- moving particles on the AMR hierarchy
  - particles crossing grid boundaries



1. Drift:  $\bar{x}^{n+1/4} = \bar{x}^n + \bar{p}^n \int_{t_n}^{t_n+\Delta t/4} dt$

2. Drift:  $\bar{x}^{n+1/2} = \bar{x}^{n+1/4} + \bar{p}^{n+1/2} \int_{t_n+\Delta t/4}^{t_n+\Delta t/2} dt$

← →

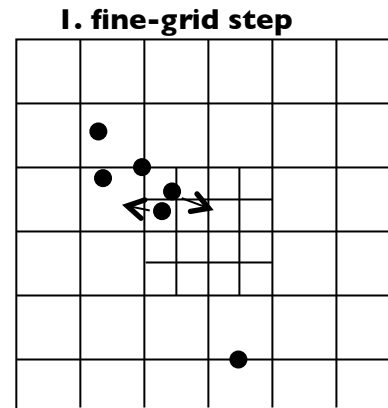
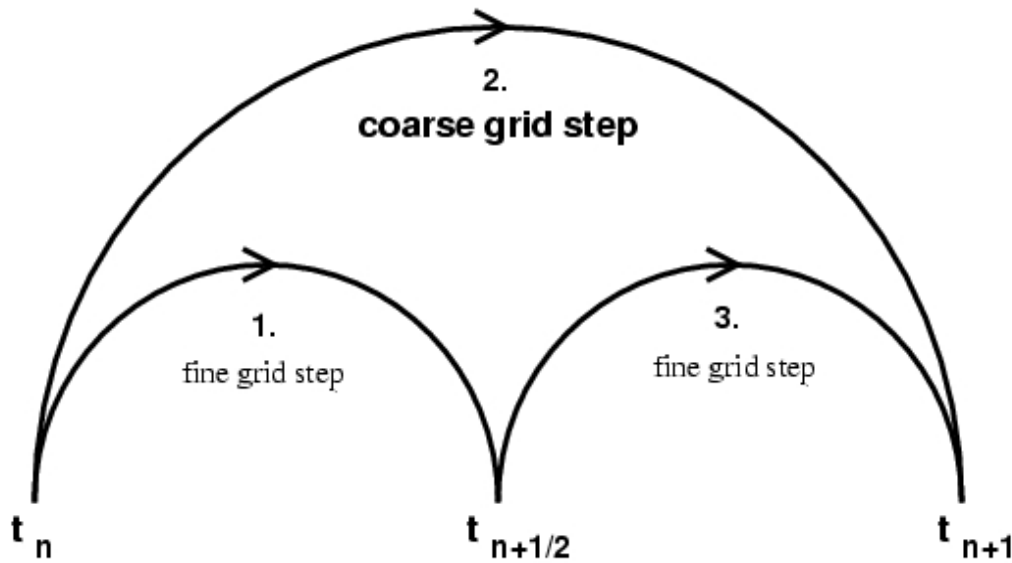
3. Drift:  $\bar{x}^{n+3/4} = \bar{x}^{n+1/2} + \bar{p}^n \int_{t_n+\Delta t/2}^{t_n+3\Delta t/4} dt$

4. Drift:  $\bar{x}^{n+1} = \bar{x}^{n+3/4} + \bar{p}^{n+1} \int_{t_n+3\Delta t/4}^{t_n+\Delta t} dt$  →

**un-drift and move with coarse grid time step to  $t_{n+1}$ ...**

Solving for Gravity

- moving particles on the AMR hierarchy
  - particles crossing grid boundaries



1. Drift:  $\vec{x}^{n+1/4} = \vec{x}^n + \vec{p}^n \int_{t_n}^{t_n+\Delta t/4} dt$

2. Drift:  $\vec{x}^{n+1/2} = \vec{x}^{n+1/4} + \vec{p}^{n+1/2} \int_{t_n+\Delta t/4}^{t_n+\Delta t/2} dt$

← →

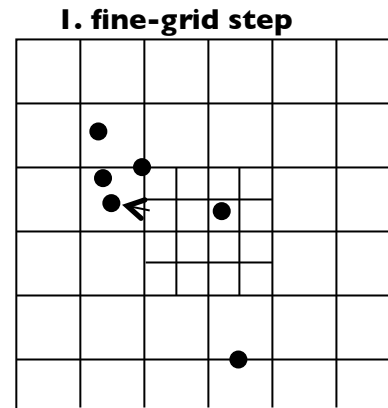
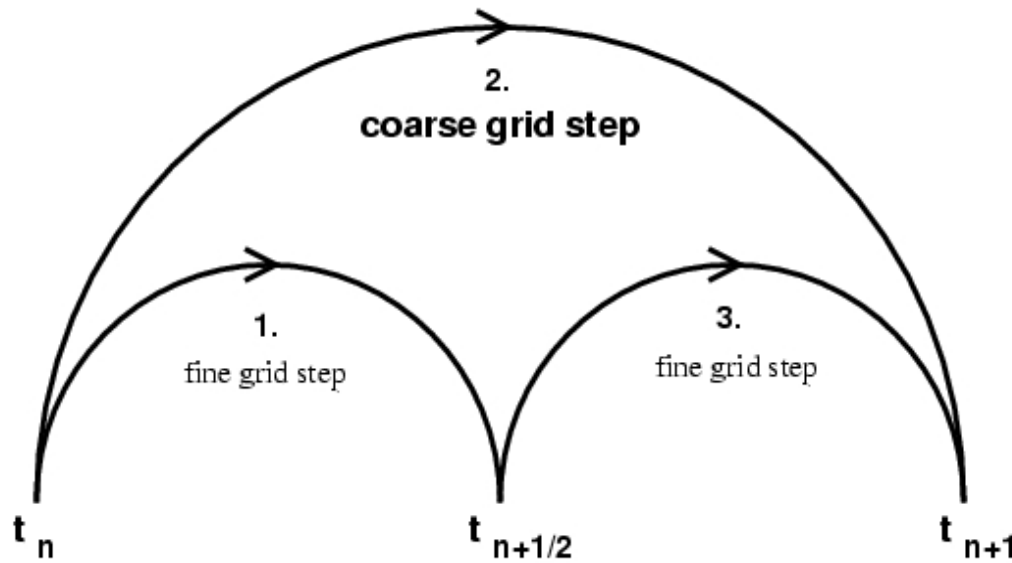
3. Drift:  $\vec{x}^{n+3/4} = \vec{x}^{n+1/2} + \vec{p}^n \int_{t_n+\Delta t/2}^{t_n+3\Delta t/4} dt$

4. Drift:  $\vec{x}^{n+1} = \vec{x}^{n+3/4} + \vec{p}^{n+1} \int_{t_n+3\Delta t/4}^{t_n+\Delta t} dt$  →

**un-drift and move with coarse grid time step to  $t_{n+1}$ ...**

Solving for Gravity

- moving particles on the AMR hierarchy
  - particles crossing grid boundaries



1. Drift:  $\bar{x}^{n+1/4} = \bar{x}^n + \bar{p}^n \frac{\Delta t}{4}$

2. Drift:  $\bar{x}^{n+1/2} = \bar{x}^{n+1/4} + \bar{p}^{n+1/2} \frac{\Delta t}{4}$

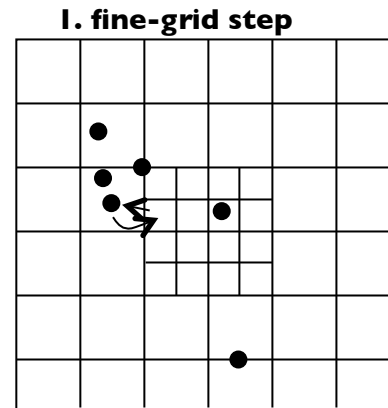
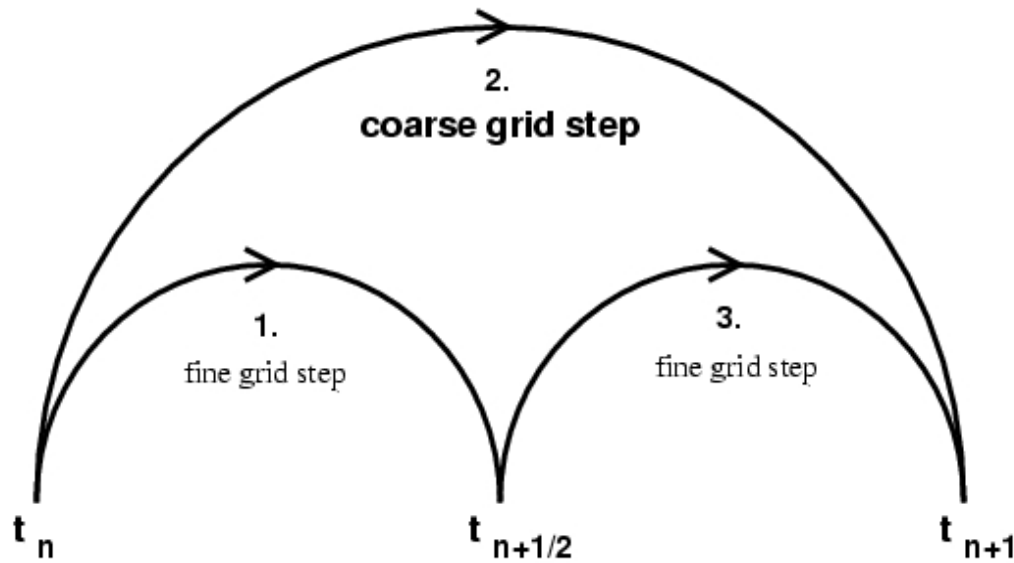
3. Drift:  $\bar{x}^{n+3/4} = \bar{x}^{n+1/2} + \bar{p}^n \frac{\Delta t}{4}$

4. Drift:  $\bar{x}^{n+1} = \bar{x}^{n+3/4} + \bar{p}^{n+1} \frac{\Delta t}{4}$

**un-drift and move with coarse grid time step to  $t_{n+1}$ ...**

Solving for Gravity

- moving particles on the AMR hierarchy
  - particles crossing grid boundaries



1. Drift:  $\bar{x}^{n+1/4} = \bar{x}^n + \bar{p}^n \frac{\Delta t}{4}$

2. Drift:  $\bar{x}^{n+1/2} = \bar{x}^{n+1/4} + \bar{p}^{n+1/2} \frac{\Delta t}{4}$

3. Drift:  $\bar{x}^{n+3/4} = \bar{x}^{n+1/2} + \bar{p}^n \frac{\Delta t}{4}$

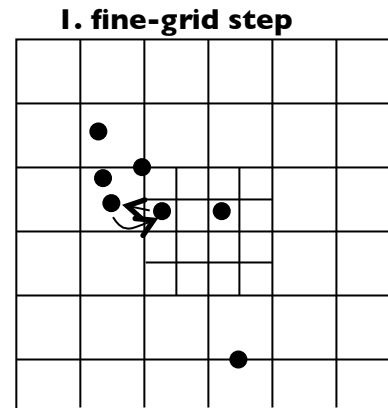
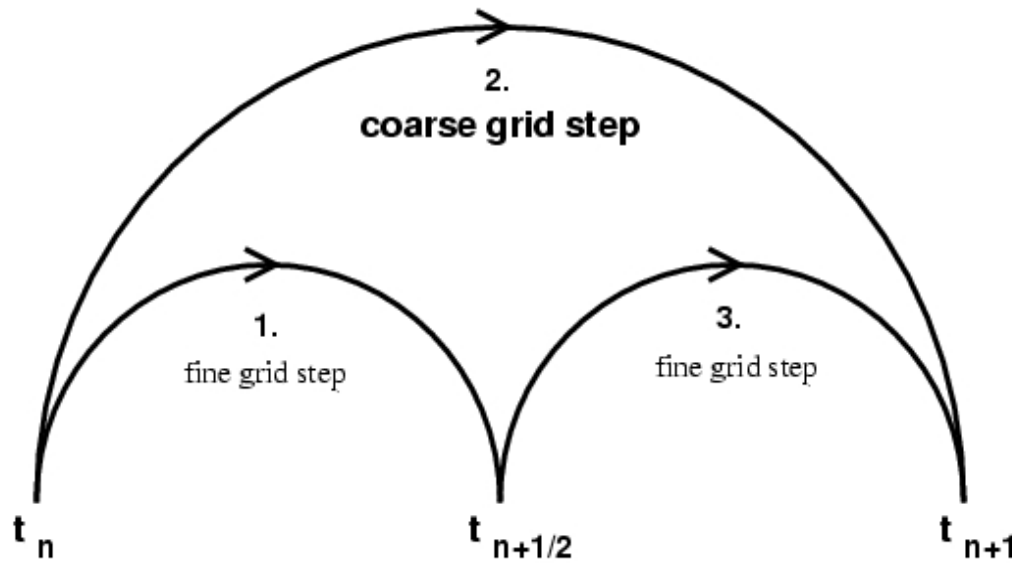
4. Drift:  $\bar{x}^{n+1} = \bar{x}^{n+3/4} + \bar{p}^{n+1} \frac{\Delta t}{4}$

**un-drift and move with coarse grid time step to  $t_{n+1}$ ...**



Solving for Gravity

- moving particles on the AMR hierarchy
  - particles crossing grid boundaries



1. Drift:  $\bar{x}^{n+1/4} = \bar{x}^n + \bar{p}^n \frac{\Delta t}{4}$

2. Drift:  $\bar{x}^{n+1/2} = \bar{x}^{n+1/4} + \bar{p}^{n+1/2} \frac{\Delta t}{4}$

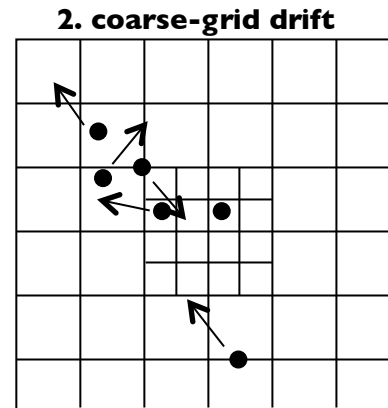
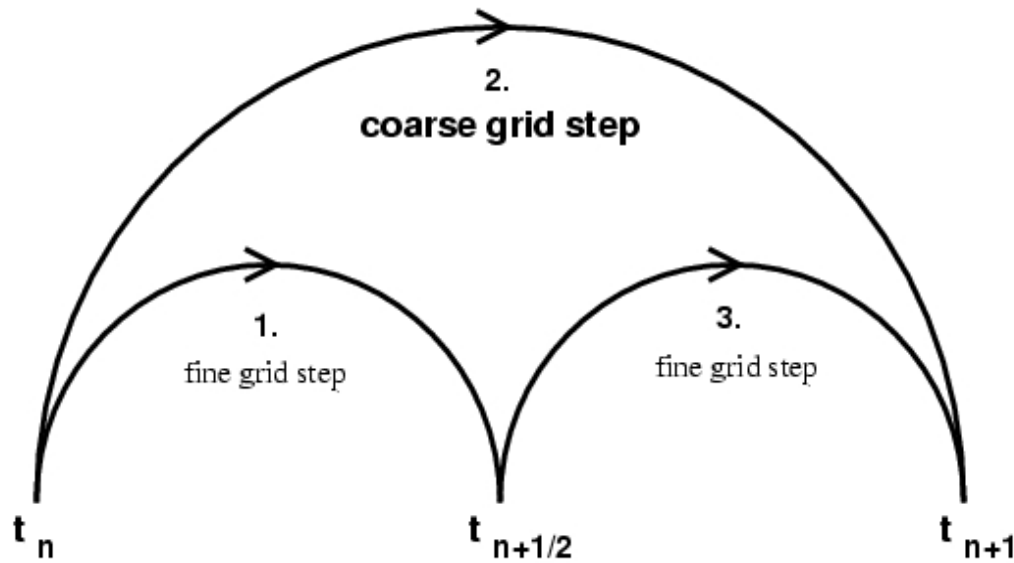
3. Drift:  $\bar{x}^{n+3/4} = \bar{x}^{n+1/2} + \bar{p}^n \frac{\Delta t}{4}$

4. Drift:  $\bar{x}^{n+1} = \bar{x}^{n+3/4} + \bar{p}^{n+1} \frac{\Delta t}{4}$

**un-drift and move with coarse grid time step to  $t_{n+1}$ ...**

Solving for Gravity

- moving particles on the AMR hierarchy
  - particles crossing grid boundaries



1. Drift:  $\bar{x}^{n+1/4} = \bar{x}^n + \bar{p}^n \frac{\Delta t}{4}$

2. Drift:  $\bar{x}^{n+1/2} = \bar{x}^{n+1/4} + \bar{p}^{n+1/2} \frac{\Delta t}{4}$

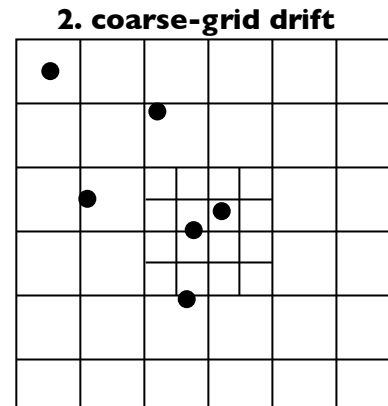
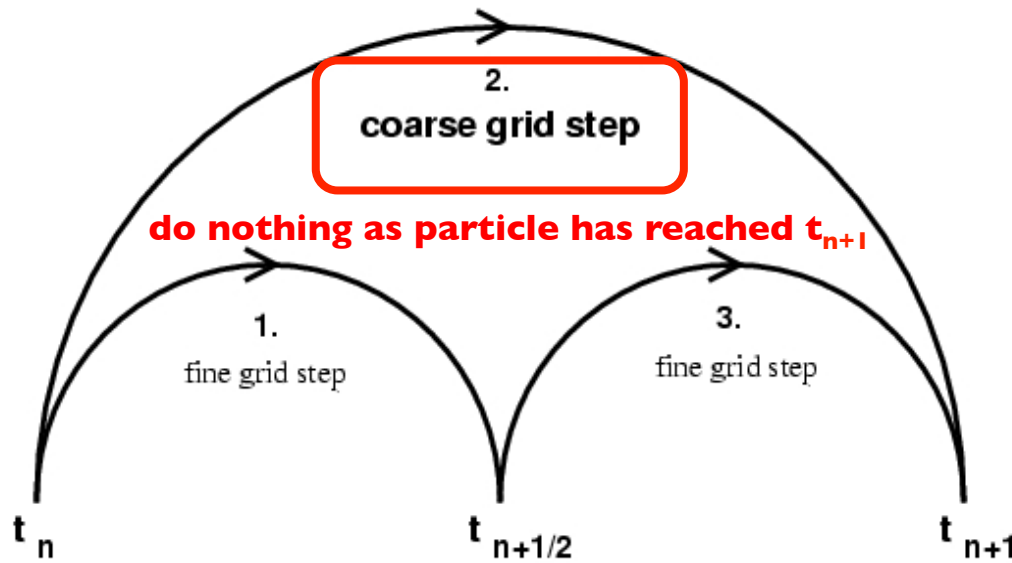
3. Drift:  $\bar{x}^{n+3/4} = \bar{x}^{n+1/2} + \bar{p}^n \frac{\Delta t}{4}$

4. Drift:  $\bar{x}^{n+1} = \bar{x}^{n+3/4} + \bar{p}^{n+1} \frac{\Delta t}{4}$

**un-drift and move with coarse grid time step to  $t_{n+1}$ ...**

Solving for Gravity

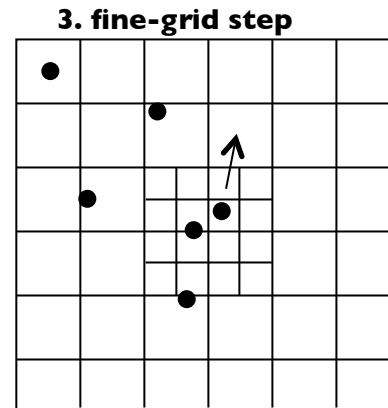
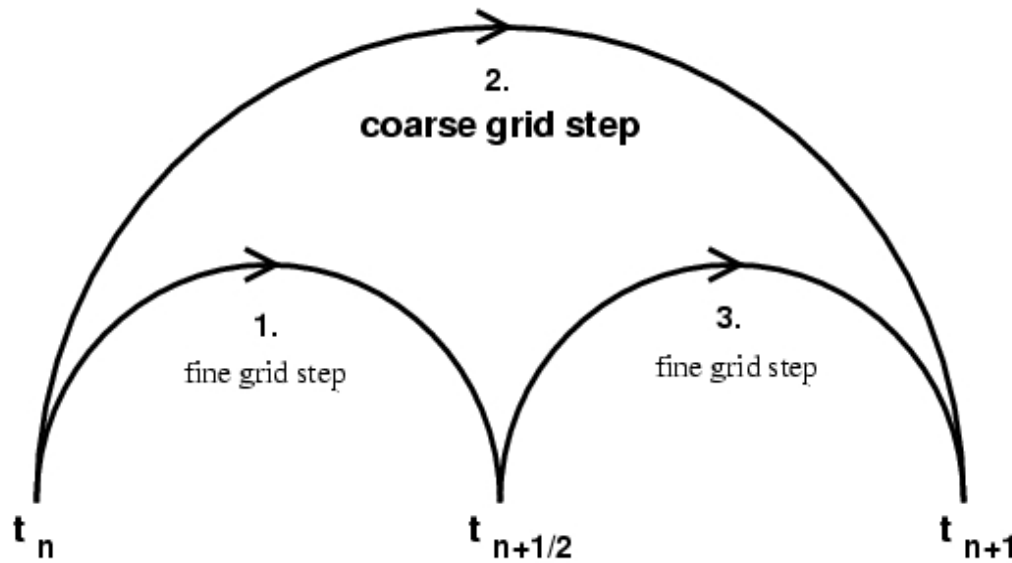
- moving particles on the AMR hierarchy
  - particles crossing grid boundaries



$$\begin{array}{l}
 \leftarrow 1. \text{ Drift: } \bar{x}^{n+1/4} = \bar{x}^n + \bar{p}^n \frac{\Delta t}{4} \\
 2. \text{ Drift: } \bar{x}^{n+1/2} = \bar{x}^{n+1/4} + \bar{p}^{n+1/2} \frac{\Delta t}{4} \\
 \rightarrow \leftarrow 3. \text{ Drift: } \bar{x}^{n+3/4} = \bar{x}^{n+1/2} + \bar{p}^n \frac{\Delta t}{4} \\
 4. \text{ Drift: } \bar{x}^{n+1} = \bar{x}^{n+3/4} + \bar{p}^{n+1} \frac{\Delta t}{4} \rightarrow
 \end{array}$$

Solving for Gravity

- moving particles on the AMR hierarchy
  - particles crossing grid boundaries



$$1. \text{ Drift: } \bar{x}^{n+1/4} = \bar{x}^n + \bar{p}^n \frac{\Delta t}{4}$$

$$2. \text{ Drift: } \bar{x}^{n+1/2} = \bar{x}^{n+1/4} + \bar{p}^{n+1/2} \frac{\Delta t}{4}$$

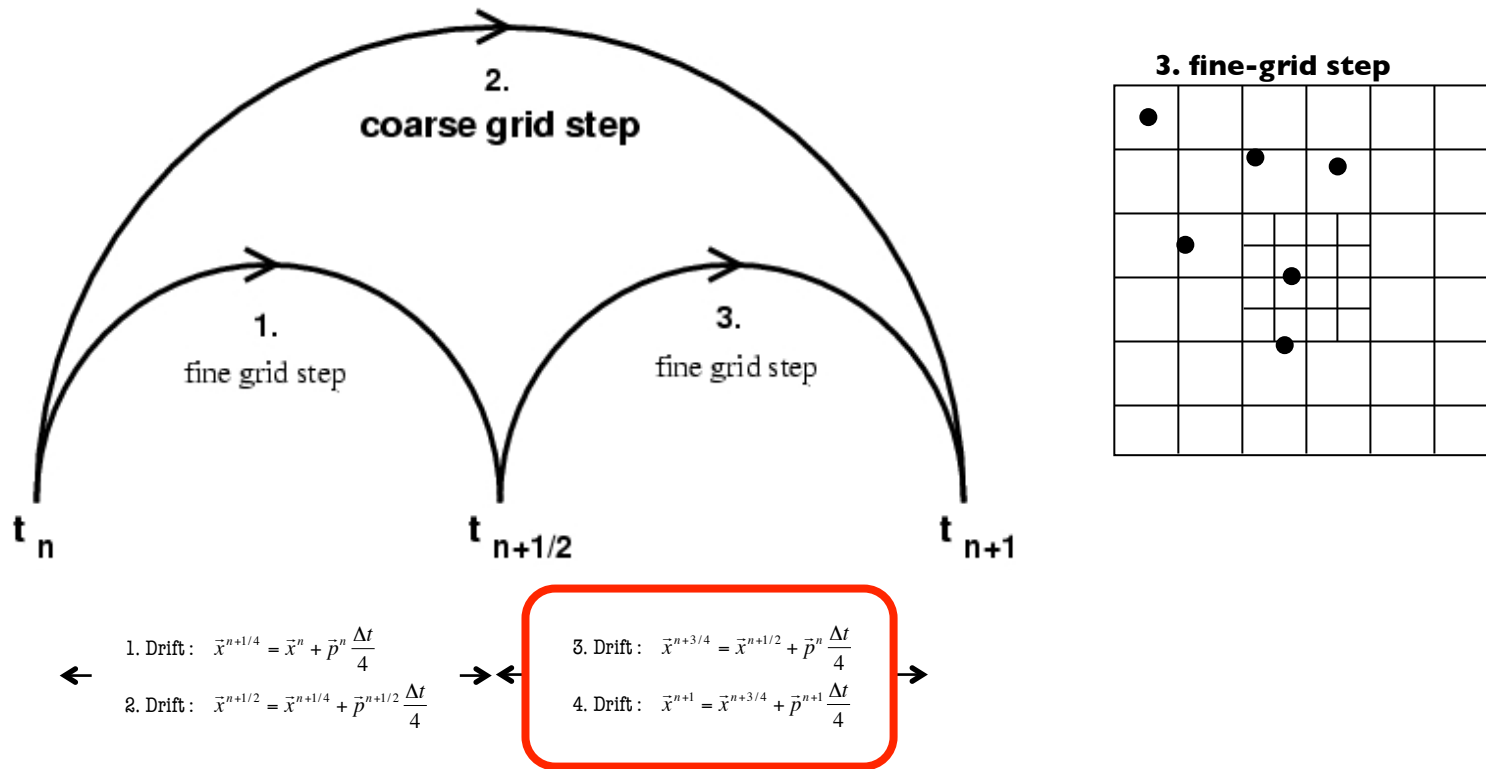
$$3. \text{ Drift: } \bar{x}^{n+3/4} = \bar{x}^{n+1/2} + \bar{p}^n \frac{\Delta t}{4}$$

$$4. \text{ Drift: } \bar{x}^{n+1} = \bar{x}^{n+3/4} + \bar{p}^{n+1} \frac{\Delta t}{4}$$

**keep on drift'ing as it will bring the particle to  $t_{n+1}$**

Solving for Gravity

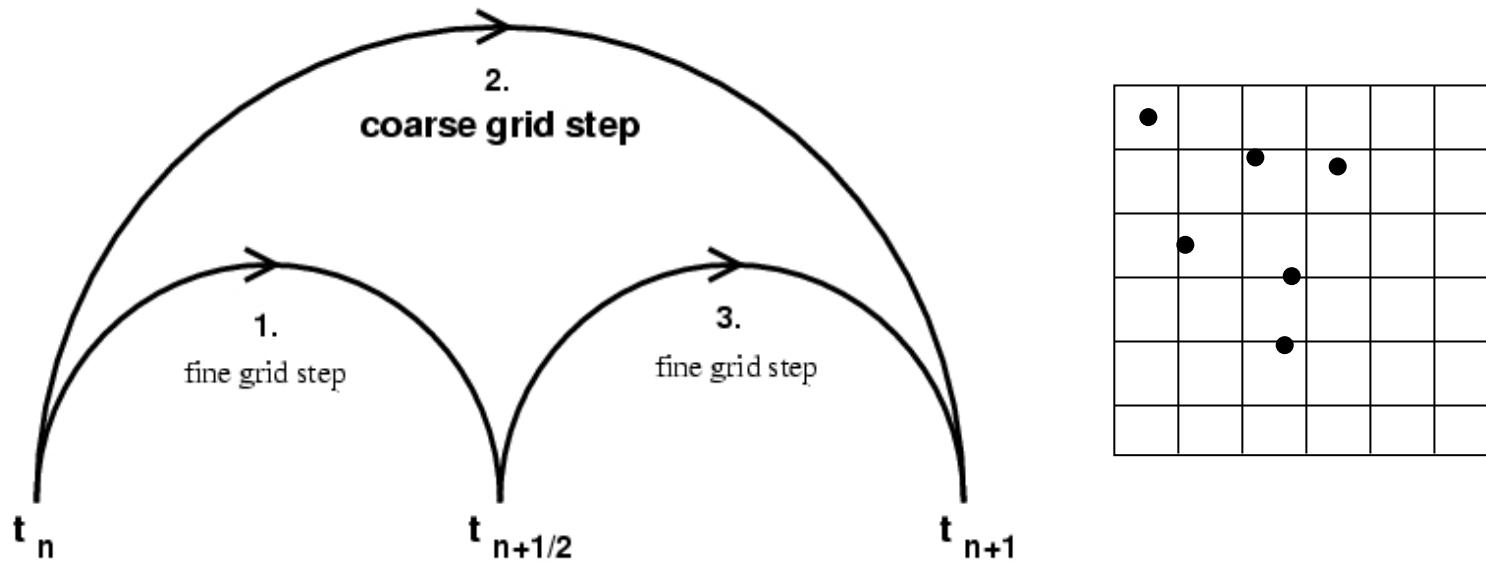
- moving particles on the AMR hierarchy
  - particles crossing grid boundaries



**keep on drift'ing as it will bring the particle to  $t_{n+1}$**

Solving for Gravity

- moving particles on the AMR hierarchy
  - particles crossing grid boundaries



$\leftarrow$  1. Drift:  $\bar{x}^{n+1/4} = \bar{x}^n + \bar{p}^n \frac{\Delta t}{4}$        $\rightarrow \leftarrow$  3. Drift:  $\bar{x}^{n+3/4} = \bar{x}^{n+1/2} + \bar{p}^n \frac{\Delta t}{4}$   
 2. Drift:  $\bar{x}^{n+1/2} = \bar{x}^{n+1/4} + \bar{p}^{n+1/2} \frac{\Delta t}{4}$       4. Drift:  $\bar{x}^{n+1} = \bar{x}^{n+3/4} + \bar{p}^{n+1} \frac{\Delta t}{4}$        $\rightarrow$

all particles have now moved from  $t_n$  to  $t_{n+1}$  and the refinements will be re-created...

## Solving for Gravity

---

```
Step(dt, CurrentGrid) {  
  
    NewGrid = Refine(CurrentGrid);  
  
    if(NewGrid) {  
        Step(dt/2, NewGrid); }  
  
    MoveParticles(dt, CurrentGrid);  
  
    if(NewGrid) {  
        Step(dt/2, NewGrid);  
        DestroyGrid(NewGrid);}  
}
```

## Solving for Gravity


AMIGA - AMIGA

Dict-EN Dict-ES Astro UAM MAD Banking Lifestyle Mac Mail Misc Movies Newspaper Music Shopping AK TV DM Week

AMIGA - AMIGA

**AMIGA** Documentation Feedback

**AMIGA**  
Adaptive Mesh Investigations of Galaxy Assembly



**AMIGA** will become the successor of [MLAPM](#)...one fine day...

For those brave enough to live with some bugs here and there and always feel the urge to play with the beta versions, respectively, are more than welcome to grab a copy of the source right here, right now.

Please note that the halo finder **AHF** is an integral part of the simulation code **AMIGA**. Check the [documentation](#) for more information.

[amiga-v0.0.tgz](#) always the latest beta version  
(please check the BUILT parameter `src/param.h` to verify if you are up-to-date...)

[Sample.tgz](#) some LCDM sample simulations  
(not needed, but very useful...)

If you are going to use **AMIGA** or **AHF**, please [register](#). This is the only way to inform you about bug fixes and other improvements, respectively.

**Last modified:** 03/05/2010 (BUILT 303: added `-DDVIR_200RHOCRT`; check [changelog.txt](#) for details)

[AMIGA](#) >